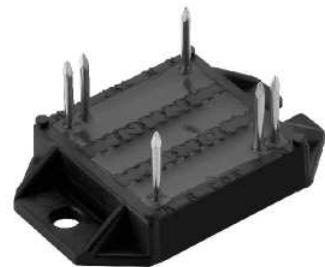
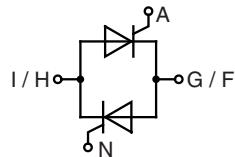


AC Controller Modules

Preliminary Data

I_{RMS} = 175 A
I_{TAVM} = 80 A
V_{RRM} = 1200/1600 V

V _{RSM}	V _{RRM}	
V _{DSM}	V _{DRM}	Typ
1300	1200	MMO 175-12i07
1700	1600	MMO 175-16i07



Symbol	Conditions	Maximum Ratings		
I _{RMS}	T _C = 85°C; 50-400 Hz (per single controller)	175	A	
I _{TRMS}		125	A	
I _{TAVM}	T _C = 85°C; 180° sine	80	A	
I _{TSM}	T _{VJ} = 45°C; t = 10 ms (50 Hz) V _R = 0 t = 8.3 ms (60 Hz)	1500	A	
	T _{VJ} = 125°C; t = 10 ms (50 Hz) V _R = 0 t = 8.3 ms (60 Hz)	1600	A	
		1350	A	
		1450	A	
I ² t	T _{VJ} = 45°C; t = 10 ms (50 Hz) V _R = 0 t = 8.3 ms (60 Hz)	11 200	A ² s	
	T _{VJ} = 125°C; t = 10 ms (50 Hz) V _R = 0 t = 8.3 ms (60 Hz)	10 750	A ² s	
		9 100	A ² s	
		8 830	A ² s	
(di/dt) _{cr}	T _{VJ} = 125°C; repetitive, I _T = 80 A f = 50 Hz; t _p = 200 µs;	150	A/µs	
	V _D = 2/3 V _{DRM} ; I _G = 0.45 A; di _G /dt = 0.45 A/µs	500	A/µs	
(dv/dt) _{cr}	T _{VJ} = 125°C; V _D = 2/3 V _{DRM} ; R _{GK} = ∞; method 1 (linear voltage rise)	1000	V/µs	
P _{GM}	T _{VJ} = 125°C; t _p = 30 ms I _T = I _{T(AV)M} ; t _p = 300 ms	10	W	
		5	W	
P _{GAVM}		0.5	W	
V _{RGM}		10	V	
T _{VJ}		-40...+150	°C	
T _{VJM}		150	°C	
T _{stg}		-40...+125	°C	
V _{ISOL}	50/60 Hz, RMS t = 1 min I _{ISOL} ≤ 1 mA t = 1 s	2500	V~	
		3000	V~	
M _d	Mounting torque (M4)	1.5 - 2.0	Nm	
		14 - 18	lb.in.	
Weight	Typical including screws	18	g	

Data according to IEC 60747 and refer to a single diode unless otherwise stated.

IXYS reserves the right to change limits, test conditions and dimensions.

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Symbol	Conditions	Characteristic Values	
		typ.	max.
I_D, I_R	$V_R / V_D = V_{RRM} / V_{DRM}$	$T_{VJ} = 125^\circ\text{C}$	5 mA
V_T	$I_T = 200 \text{ A}$	$T_{VJ} = 25^\circ\text{C}$	1.57 V
V_{TO}	For power-loss calculations only	0.85 V	
r_t		3.70 mΩ	
V_{GT}	$V_D = 6 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$	1.5 V
		$T_{VJ} = -40^\circ\text{C}$	1.6 V
I_{GT}	$V_D = 6 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$	100 mA
		$T_{VJ} = -40^\circ\text{C}$	200 mA
V_{GD}	$V_D = \frac{2}{3} V_{DRM};$	$T_{VJ} = 125^\circ\text{C}$	0.2 V
I_{GD}			10 mA
I_L	$t_p = 10 \mu\text{s};$ $I_G = 0.45 \text{ A}; dI_G/dt = 0.45 \text{ A}/\mu\text{s}$	$T_{VJ} = 25^\circ\text{C}$	450 mA
I_H	$V_D = 6 \text{ V}; R_{GK} = \infty;$	$T_{VJ} = 25^\circ\text{C}$	200 mA
t_{gd}	$V_D = \frac{1}{2} V_{DRM}$	$T_{VJ} = 25^\circ\text{C}$	2 μs
	$I_G = 0.45 \text{ A}; dI_G/dt = 0.45 \text{ A}/\mu\text{s}$		
R_{thJC}	per thyristor; DC current	0.50 K/W	
R_{thCH}		0.12 K/W	
R_{thJC}	per module	0.25 K/W	
R_{thCH}		0.06 K/W	
d_s	Creeping distance on surface	11.2 mm	
d_A	Creepage distance in air	5.0 mm	
a	Maximum allowable acceleration	50 m/s ²	

Dimensions in mm (1 mm = 0.0394")

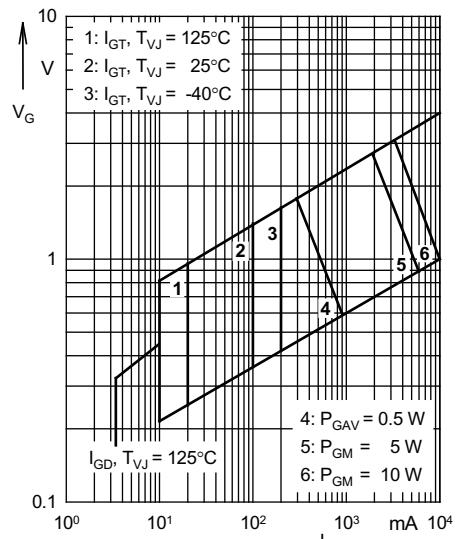
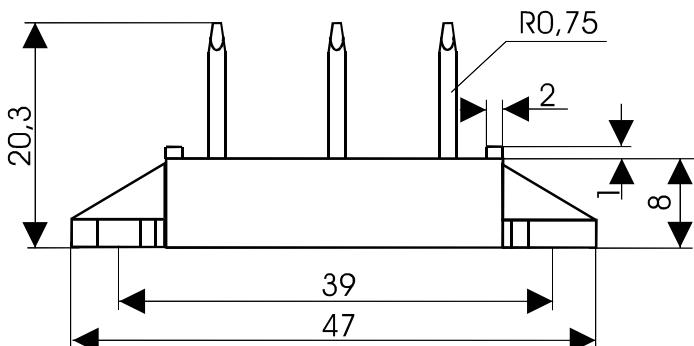
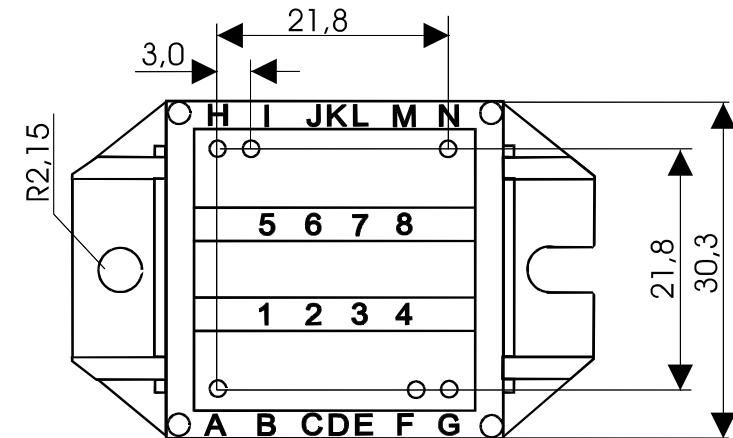


Fig. 1 Gate trigger characteristics

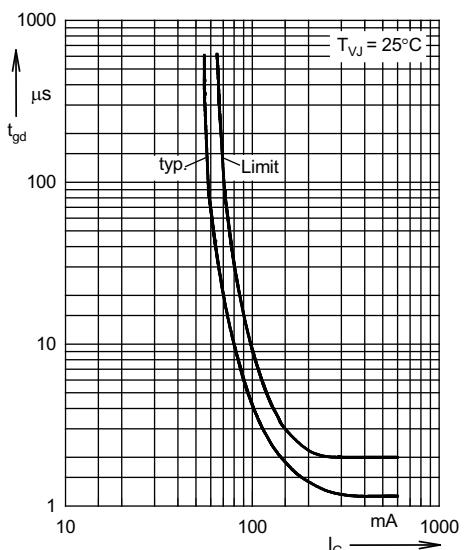


Fig. 2 Gate trigger delay time