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Multistandard Sound Processor Family

Release Note: Revision bars indicate significant changes to the MSP 44x8G Data Sheet, Edition 16.06.03, 6251-516-1DS. The hardware and software description in this document is valid for the MSP 44x8G version C4 and following versions.

1. Introduction

The MSP 44x8G family of Multistandard Sound Processors covers the demodulation and stereo decoding of all analog TV-Standards worldwide, as well as the NICAM digital sound standards and FM stereo radio. The full demodulation and decoding, starting with analog sound IF signal in, down to processed analog or digital AF (baseband audio) out, is performed on a single chip. Fig. 1–1 on page 6 shows a simplified functional block diagram of the MSP 44x8G.

The MSP 44x8G built-in stereo A/D converters offer a S/N ratio of 95 dBA typ. The double stereo D/A converters with analog volume and 0.125 dB steps make use of the Micronas unique multibit Delta-Sigma technology, offering a dynamic range of 95 dBA typically. The DSP processing is performed at a 48 kHz sample rate, maintaining the full audio bandwidth of 20 kHz in all MSP 44x8G signal paths.

The MSP 44x8G has been designed for the usage in DVD/HDD-recorders, hybrid set-top boxes, and multimedia applications. It combines the function of a TV stereo decoder together with an Audio I²S Codec and DSP audio processing features. Its asynchronous I²S interfaces allows the reception and transmission of digital stereo signals with arbitrary sample rates from 6 to 49 kHz. In addition, a sample rate of 96 kHz is also supported at the asynchronous I²S input.

The MSP 44x8G offers the following automatic functions:

- ASD (Automatic Standard Detection) detects the actual broadcasted TV standard automatically.
- ASS (Automatic Sound Select) switches automatically (without any I²C action) between mono/stereo/ bilingual when the broadcast mode changes.

This generation of sound processing ICs includes versions for processing the multichannel television sound (MTS) signal conforming to the U.S. standard recommended by the Broadcast Television Systems Committee (BTSC). The DBX noise reduction, or alternatively, Micronas Noise Reduction (MNR) is performed alignment free. Apart from all 2-carrier standards, other processed standards are the Japanese FM-FM multiplex standard (EIA-J) and the FM Stereo Radio standard.

The MSP 44x8G versions are pin and software compatible to other MSP families. Standard selection requires only a single I²C transmission.

The ICs are produced in submicron CMOS technology and are available in the following packages:

PMQFP80-11, PMQFP64-2, and PSDIP64-1.

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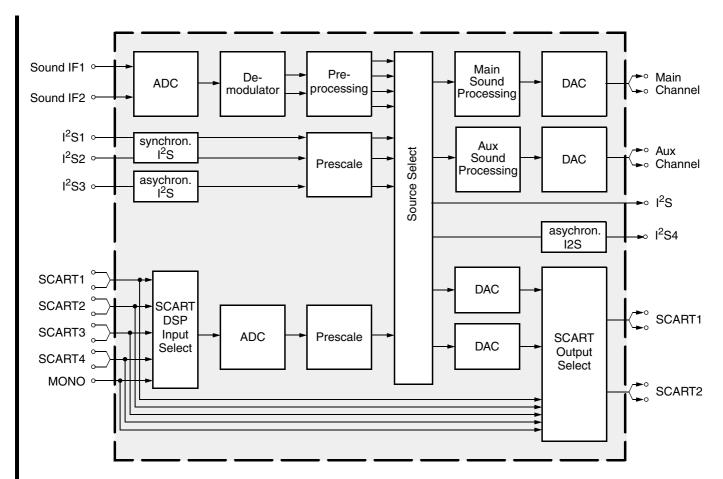


Fig. 1-1: Simplified functional block diagram of the MSP 44x8G

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1.1. Features of the MSP 44x8G Family

Feature	4408	4418	4428	4448	4458	4468
Standard Selection with single I ² C transmission	Х	Х	Х	Х	Х	Х
Automatic Standard Detection of terrestrial TV standards	Х	Х	Х	Х	Х	Х
Automatic Sound Selection (mono/stereo/bilingual), new registers MODUS, STATUS	Х	Х	Х	Х	Х	Х
Two selectable sound IF (SIF) inputs	Х	Х	Х	Х	Х	Х
Automatic Carrier Mute function	Х	Х	Х	Х	Х	Х
Interrupt output programmable (indicating status change)	Х	Х	Х	Х	Х	Х
Main/Aux channel with volume	Х	Х	Х	Х	Х	Х
AVC: Automatic Volume Correction	Х	Х	Х	Х	Х	Х
Two channel mixer	Х	Х	Х	Х	Х	Х
Selectable preemphasis for Aux channel	Х	Х	Х	Х	Х	Х
Four Stereo SCART (line) inputs, one Mono input; two Stereo SCART outputs	Х	Х	Х	Х	Х	Х
Complete SCART in/out switching matrix	Х	Х	Х	Х	Х	Х
Two synchronous 48 kHz I ² S inputs; one synchronous 48 kHz I ² S output	х	Х	Х	Х	Х	Х
Asynchronous 649, 96 kHz I ² S input, asynchronous 649 kHz I ² S output	Х	Х	Х	Х	Х	Х
Audio/Video synchronization	Х	Х	Х	Х	Х	Х
All analog Mono Sound carriers including AM-SECAM	Х	Х	Х	Х	Х	Х
Korean FM-Stereo A2 standard	Х	Х	Х	Х	Х	
All analog FM-Stereo A2 and satellite standards	Х	Х			Х	
Simultaneous demodulation of (very) high-deviation FM-Mono and NICAM		Х			Х	
Adaptive deemphasis for satellite (Wegener-Panda, acc. to ASTRA specification)	Х	Х			Х	Х
All NICAM standards		Х			Х	
Demodulation of the BTSC multiplex signal and the SAP channel			Х	Х	Х	
Alignment free digital DBX noise reduction for BTSC Stereo and SAP				Х	Х	
Alignment free digital Micronas Noise Reduction (MNR) for BTSC Stereo and SAP			Х			
BTSC stereo and EIA-J separation significantly better than spec.			Х	Х	Х	
SAP and stereo detection for BTSC system			Х	Х	Х	
Alignment-free Japanese standard EIA-J			Х	Х	Х	
Demodulation of the FM-Radio multiplex signal			Х	Х	Х	

1.2. MSP 44x8G Version List

Version	Status	Description
MSP 4408G	not confirmed	FM Stereo (A2) Version
MSP 4418G	available	NICAM and FM Stereo (A2) Version
MSP 4428G	available	NTSC Version (A2 Korea, BTSC with Micronas Noise Reduction (MNR), and Japanese EIA-J system)
MSP 4448G	available	NTSC Version (A2 Korea, BTSC with DBX noise reduction, and Japanese EIA-J system)
MSP 4458G	available	Global Version (all sound standards)
MSP 4468G	not confirmed	Global Mono Version (all sound standards)

1.3. MSP 44x8G Versions and their Application Fields

Table 1–1 provides an overview of TV sound standards that can be processed by the MSP 44x8G family. In addition, the MSP 44x8G is able to handle the FM-Radio standard. With the MSP 44x8G, a DVD/HDD-recorder or multimedia receiver covering all TV sound standards together with FM-Radio sound can be built.

Table 1-1: TV Stereo Sound Standards covered by the MSP 44x8G Family (details see Appendix A)

	MSP Version System		System	Position of Sound Carrier / MHz	Sound Modulation	Color System	Broadcast e.g. in:							
4408				B/G	5.5/5.7421875	FM-Stereo (A2)	PAL	Germany						
				Б/G	5.5/5.85	FM-Mono/NICAM	PAL	Scandinavia, Spain						
				L	6.5/5.85	AM-Mono/NICAM	SECAM-L	France						
				1	6.0/6.552	FM-Mono/NICAM	PAL	UK, Hong Kong						
					6.5/5.85	FM-Mono/NICAM	PAL	China, Hungary						
		4418		5 " 4	6.5/6.2578125	FM-Stereo (A2, D/K1)	SECAM-East	Slovak. Rep.						
		4	ω	8	-		8	œ	8	D/K	6.5/6.7421875	FM-Stereo (A2, D/K2)	PAL	currently no broadcast
80			4458		6.5/5.7421875	FM-Stereo (A2, D/K3)	SECAM-East	Poland						
4408				Satellite	6.5 7.02/7.2 7.38/7.56 etc.	FM-Mono FM-Stereo	PAL	Europe Sat.						
					4.5/4.724212	FM-Stereo (A2)	NTSC	Korea						
	3/48				М	4.5	FM-FM (EIA-J)	NTSC	Japan					
	4428/48				4.5	BTSC-Stereo + SAP	NTSC	USA						
				FM-Radio	10.7	FM-Stereo Radio		USA, Europe						
	4468 all Standards as above but Mono demodulation only													

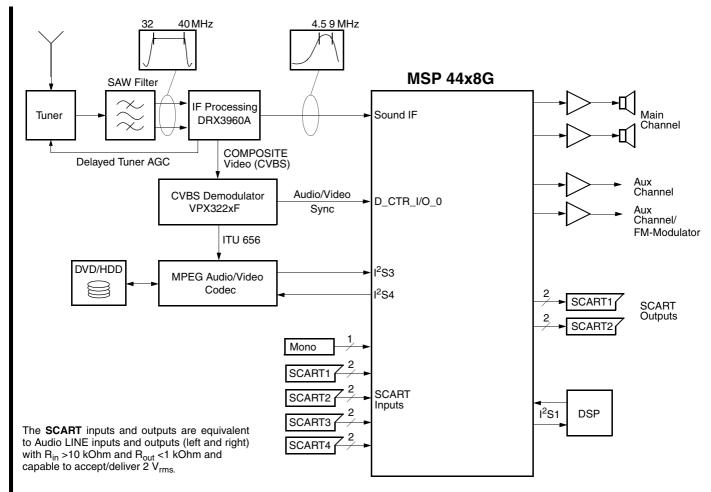
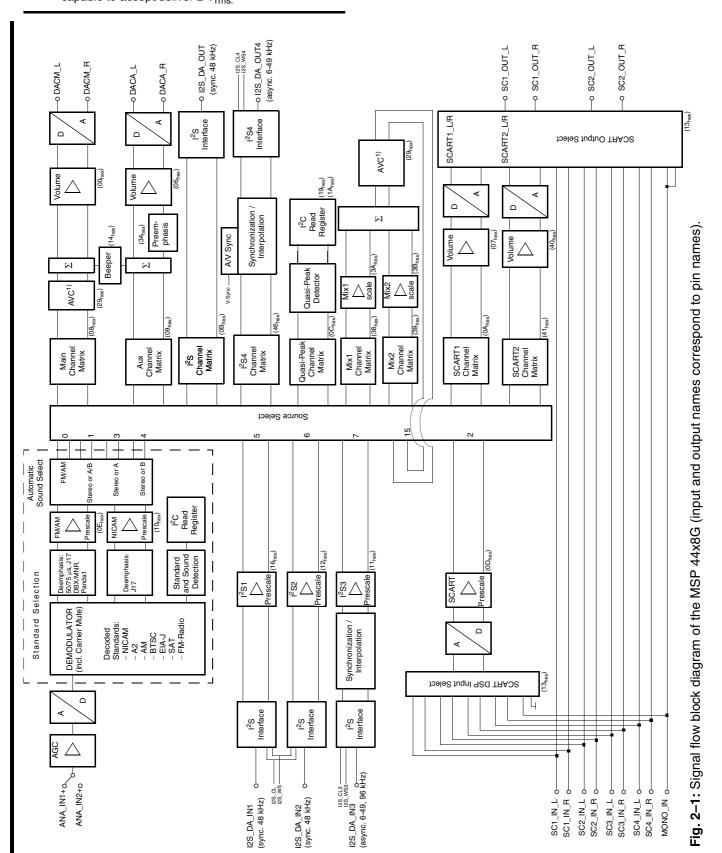


Fig. 1-2: Typical MSP 44x8G application

2. Functional Description

Note: The SCART inputs and outputs are equivalent to Audio LINE inputs and outputs (left and right) with $\rm R_{in}$ >10 kOhm and $\rm R_{out}$ <1 kOhm and capable to accept/deliver 2 $\rm V_{rms.}$

Note: 1) AVC location is programmable.



2.1. Architecture of the MSP 44x8G Family

Fig. 2–1 shows a simplified block diagram of the IC. The block diagram contains all features of the MSP 4458G. Other members of the MSP 44x8G family do not have the complete set of features: The demodulator handles only a subset of the standards presented in the demodulator block; NICAM processing is only possible in the MSP 4418G and MSP 4458G.

2.2. MSP 44x8G Sound IF Processing

2.2.1. Analog Sound IF Input

The input pins ANA_IN1+, ANA_IN2+, and ANA_IN-offer the possibility to connect two different sound IF (SIF) sources to the MSP 44x8G. The preselected sound IF signal is fed into an A/D-converter. An analog automatic gain circuit (AGC) allows a wide range of input levels. The highpass filters, formed by the coupling capacitors at pins ANA_IN1+ and ANA_IN2+ (see Section 7.3. "Application Circuit" on page 91), are sufficient in most cases to suppress video components. Some combinations of SAW filters and sound IF mixer ICs, however, show large picture components on their outputs. In this case, further filtering is recommended.

2.2.2. Demodulator: Standards and Features

The MSP 44x8G is able to demodulate all TV-sound standards worldwide including the digital NICAM system. Depending on the MSP 44x8G version, the following demodulation modes can be performed:

A2 Systems: Detection and demodulation of two separate FM carriers (FM1 and FM2), demodulation and evaluation of the identification signal of carrier FM2.

NICAM Systems: (Only possible in the MSP 4418G and MSP 4458G). Demodulation and decoding of the NICAM carrier, detection and demodulation of the analog FM or AM carrier. For D/K-NICAM, the FM carrier may have a maximum deviation of 384 kHz.

Very high deviation FM-Mono: Detection and robust demodulation of one FM carrier with a maximum deviation of 540 kHz.

BTSC-Stereo: Detection and FM demodulation of the aural carrier resulting in the MTS/MPX signal. Detection and evaluation of the pilot carrier, AM demodulation of the (L-R)-carrier and detection of the SAP subcarrier. Processing of DBX noise reduction or Micronas Noise Reduction (MNR).

BTSC-Mono + SAP: Detection and FM demodulation of the aural carrier resulting in the MTS/MPX signal. Detection and evaluation of the pilot carrier, detection and FM demodulation of the SAP subcarrier. Processing of DBX noise reduction or Micronas Noise Reduction (MNR).

Japan Stereo: Detection and FM demodulation of the aural carrier resulting in the MPX signal. Demodulation and evaluation of the identification signal and FM demodulation of the (L-R)-carrier.

FM-Satellite Sound: Demodulation of one or two FM carriers. Processing of high-deviation mono or narrow bandwidth mono, stereo, or bilingual satellite sound according to the ASTRA specification.

FM-Stereo-Radio: Detection and FM demodulation of the aural carrier resulting in the MPX signal. Detection and evaluation of the pilot carrier and AM demodulation of the (L-R)-carrier.

The demodulator blocks of all MSP 44x8G versions have identical user interfaces. Even completely different systems like the BTSC and NICAM systems are controlled the same way. Standards are selected by means of MSP Standard Codes. Automatic processes handle standard detection and identification without controller interaction. The key features of the MSP 44x8G demodulator blocks are

Standard Selection: The controlling of the demodulator is minimized: All parameters, such as tuning frequencies or filter bandwidth, are adjusted automatically by transmitting one single value to the STANDARD SELECT register. For all standards, specific MSP standard codes are defined.

Automatic Standard Detection: If the TV sound standard is unknown, the MSP 44x8G can automatically detect the actual standard, switch to that standard, and respond the actual MSP standard code.

Automatic Carrier Mute: To prevent noise effects or FM identification problems in the absence of an FM carrier, the MSP 44x8G offers a configurable carrier mute feature, which is activated automatically if the TV sound standard is selected by means of the STAN-DARD SELECT register. If no FM carrier is detected at one of the two MSP demodulator channels, the corresponding demodulator output is muted. This is indicated in the STATUS register.

2.2.3. Preprocessing of Demodulator Signals

The NICAM signals must be processed by a deemphasis filter and adjusted in level. The analog demodulated signals must be processed by a deemphasis filter, adjusted in level, and dematrixed. The correct deemphasis filters are already selected by setting the standard in the STANDARD SELECT register. The level adjustment has to be done by means of the FM/AM and NICAM prescale registers. The necessary dematrix function depends on the selected sound standard and the actual broadcasted sound mode (mono, stereo, or bilingual). It can be manually set by the FM Matrix Mode register or automatically by the Automatic Sound Selection.

2.2.4. Automatic Sound Select

In the Automatic Sound Select mode, the dematrix function is automatically selected based on the identification information in the STATUS register. No I²C interaction is necessary when the broadcasted sound mode changes (e.g. from mono to stereo).

The demodulator supports the identification check by switching between mono compatible standards (standards that have the same FM mono carrier) automatically and non-audible. If B/G-FM or B/G-NICAM is selected, the MSP will switch between these standards. The same action is performed for the standards: D/K1-FM, D/K2-FM, D/K3-FM, and D/K-NICAM. Switching is only done in the absence of any stereo or bilingual identification. If identification is found, the MSP keeps the detected standard.

In case of high bit-error rates, the MSP 44x8G automatically falls back from digital NICAM sound to analog FM or AM mono.

Table 2–1 summarizes all actions that take place when Automatic Sound Select is switched on

To provide more flexibility, the Automatic Sound Select block prepares four different source channels of demodulated sound (Fig. 2–2). By choosing one of the four demodulator channels, the preferred sound mode can be selected for each of the output channels (loud-speaker, headphone, etc.). This is done by means of the Source Select registers.

The following source channels of demodulated sound are defined:

- "FM/AM" channel: Analog mono sound, stereo if available. In case of NICAM, analog mono only (FM or AM mono).
- "Stereo or A/B" channel: Analog or digital mono sound, stereo if available. In case of bilingual broadcast, it contains both languages A (left) and B (right).

- "Stereo or A" channel: Analog or digital mono sound, stereo if available. In case of bilingual broadcast, it contains language A (on left and right).
- "Stereo or B" channel: Analog or digital mono sound, stereo if available. In case of bilingual broadcast, it contains language B (on left and right).

Fig. 2–2 and Table 2–2 show the source channel assignment of the demodulated signals in case of Automatic Sound Select mode for all sound standards.

Note: The analog primary input channel contains the signal of the mono FM/AM carrier or the L+R signal of the MPX carrier. The secondary input channel contains the signal of the second FM carrier, the L-R signal of the MPX carrier, or the SAP signal.

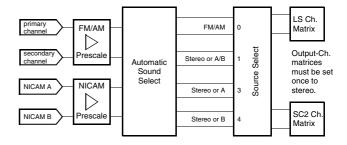


Fig. 2–2: Source channel assignment of demodulated signals in Automatic Sound Select Mode

2.2.5. Manual Mode

Fig. 2–3 shows the source channel assignment of demodulated signals in case of manual mode. If manual mode is required, more information can be found in Section 6.7. "Demodulator Source Channels in Manual Mode" on page 88.

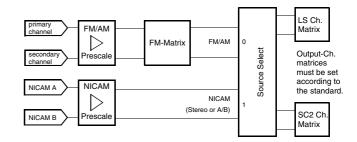


Fig. 2–3: Source channel assignment of demodulated signals in Manual Mode

Table 2-1: Performed actions of the Automatic Sound Selection

Selected TV Sound Standard	Performed Actions
B/G-FM, D/K-FM, M-Korea, and M-Japan	Evaluation of the identification signal and automatic switching to mono, stereo, or bilingual. Preparing four demodulator source channels according to Table 2–2.
B/G-NICAM, L-NICAM, I-NICAM, D/K-NICAM	Evaluation of NICAM-C-bits and automatic switching to mono, stereo, or bilingual. Preparing four demodulator source channels according to Table 2–2.
	In case of bad or no NICAM reception, the MSP switches automatically to FM/AM mono and switches back to NICAM if possible. A hysteresis prevents periodical switching.
B/G-FM, B/G-NICAM or D/K1-FM, D/K2-FM, D/K3-FM, and D/K-NICAM	Automatic searching for stereo/bilingual-identification in case of mono transmission. Automatic and non-audible changes between Dual-FM and FM-NICAM standards while listening to the basic FM-mono sound carrier. Example: If starting with B/G-FM-Stereo, there will be a periodical alternation to B/G-NICAM in the absence of FM-Stereo/Bilingual or NICAM-identification. Once an identification is detected, the MSP keeps the corresponding standard.
BTSC-STEREO, FM Radio	Evaluation of the pilot signal and automatic switching to mono or stereo. Preparing four demodulator source channels according to Table 2–2. Detection of the SAP carrier.
M-BTSC-SAP	In the absence of SAP, the MSP switches to BTSC-stereo if available. If SAP is detected, the MSP switches automatically to SAP (see Table 2–2).

Table 2–2: Sound modes for the demodulator source channels with Automatic Sound Select

			Source Channels in Automatic Sound Select Mode				
Broadcasted Sound Standard	Selected MSP Standard Code ³⁾	Broadcasted Sound Mode	FM/AM (source select: 0)	Stereo or A/B (source select: 1)	Stereo or A (source select: 3)	Stereo or B (source select: 4)	
M-Korea B/G-FM	02 03. 08 ¹⁾	MONO	Mono	Mono	Mono	Mono	
D/K-FM	03, 08 ⁻⁷ 04, 05, 07, 0B ¹⁾ 30	STEREO	Stereo	Stereo	Stereo	Stereo	
M-Japan	30	BILINGUAL: Languages A and B	Left = A Right = B	Left = A Right = B	А	В	
B/G-NICAM L-NICAM I-NICAM	08, 03 ²⁾ 09 0A	NICAM not available or error rate too high	analog Mono	analog Mono	analog Mono	analog Mono	
D/K-NICAM D/K-NICAM	0B, 04 ²), 05 ²) 0C, 0D	MONO	analog Mono	NICAM Mono	NICAM Mono	NICAM Mono	
(with high		STEREO	analog Mono	NICAM Stereo	NICAM Stereo	NICAM Stereo	
deviation FM)		BILINGUAL: Languages A and B	analog Mono	Left = NICAM A Right = NICAM B	NICAM A	NICAM B	
	20, 21	MONO	Mono	Mono	Mono	Mono	
		STEREO	Stereo	Stereo	Stereo	Stereo	
	20	MONO + SAP	Mono	Mono	Mono	Mono	
BTSC		STEREO + SAP	Stereo	Stereo	Stereo	Stereo	
	21	MONO + SAP	Left = Mono Right = SAP	Left = Mono Right = SAP	Mono	SAP	
		STEREO + SAP	Left = Mono Right = SAP	Left = Mono Right = SAP	Mono	SAP	
FM Radio	40	MONO	Mono	Mono	Mono	Mono	
		STEREO	Stereo	Stereo	Stereo	Stereo	
1)	·						

¹⁾ The Automatic Sound Select process will automatically switch to the mono compatible analog standard.

²⁾ The Automatic Sound Select process will automatically switch to the mono compatible digital standard.

 $^{^{3)}}$ The MSP Standard Codes are defined in Table 3–7 on page 22.

2.3. Preprocessing for SCART and I²S Input Signals

The SCART and I²S inputs need only be adjusted in level by means of the SCART and I²S prescale registers.

2.4. Source Selection and Output Channel Matrix

The Source Selector makes it possible to distribute all source signals (one of the demodulator source channels, SCART, or I²S input) to the desired output channels (Main, Aux, etc.). All input and output signals can be processed simultaneously. Each source channel is identified by a unique source address.

For each output channel, the output channel matrix can be set to sound A, sound B, stereo, or mono.

If Automatic Sound Select is on, the output channel matrix can stay fixed to stereo (transparent) for demodulated signals.

2.4.1. Mixing Unit

Any source can be selected as the input for the two channels of the Mixing unit. The mixer channel matrices and the scaling factors can be programmed separately for each channel.

After adding up both channels, the signal is fed back and is available as source 15 (Mix output) of the Source Selector.

2.5. Audio Baseband Processing

2.5.1. Automatic Volume Correction (AVC)

Different sound sources (e.g. terrestrial channels, SAT channels, or SCART) fairly often do not have the same volume level. Advertisements during movies usually have a higher volume level than the movie itself. This results in annoying volume changes. The AVC solves this problem by equalizing the volume level.

To prevent clipping, the AVC's gain decreases quickly in dynamic boost conditions. To suppress oscillation effects, the gain increases rather slowly for low level inputs. The decay time is programmable by means of the AVC register (see page 31).

For input signals ranging from -24 dBr to 0 dBr, the AVC maintains a fixed output level of -18 dBr. Fig. 2-4 shows the AVC output level versus its input level. For prescale and volume registers set to 0 dB, a level of 0 dBr corresponds to full scale input/output. This is

- SCART input/output 0 dBr = 2.0 V_{rms}
- Loudspeaker output 0 dBr = 1.4 V_{rms}

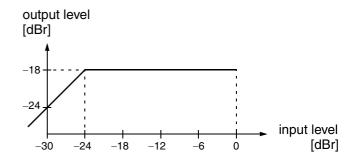


Fig. 2-4: Simplified AVC characteristics

2.5.2. Main and Aux Outputs

The Main and Aux output channels are adjustable in volume. A square wave beeper with adjustable frequency and volume can be added to them.

2.5.3. Quasi-Peak Detector

The Quasi-Peak Readout register can be used to read out the quasi-peak level of any input source. The feature is based on following filter time constants:

attack time: 1.3 msdecay time: 37 ms

2.6. SCART Signal Routing

2.6.1. SCART DSP In and SCART Out Select

The SCART DSP Input Select and SCART Output Select blocks include full matrix switching facilities. To design a TV set with four pairs of SCART-inputs and two pairs of SCART-outputs, no external switching hardware is required. The switches are controlled by the ACB user register (see page 33).

2.6.2. Stand-by Mode

If the MSP 44x8G is switched off by first pulling STANDBYQ low and then (after >1 μs delay) switching off DVSUP and AVSUP, but keeping AHVSUP ('Stand-by'-mode), the SCART switches maintain their position and function. This allows the copying from SCART-input to SCART-output in the TV set's stand-by mode.

In case of power on or starting from stand-by (switching on the DVSUP and AVSUP, RESETQ going high 2 ms later), all internal registers except the ACB register (see page 33) are reset to the default configuration (see Table 3–5 on page 20). The reset position of the ACB register becomes active after the first I²C transmission into the Baseband Processing part. By transmitting the ACB register first, the reset state can be redefined.

2.7. I²S Bus Interfaces

The MSP 44x8G has two kinds of interfaces: synchronous master/slave input/output interfaces running on 48 kHz and an asynchronous slave interface.

The interfaces accept a variety of formats with different sample width, bit-orientation, and wordstrobe timing. All I^2S options are set by means of the MODUS or I^2S CONFIG register.

2.7.1. Synchronous I²S-Interface(s)

The synchronous I²S bus interface consists of the pins:

- I2S_DA_IN1, I2S_DA_IN2/3 (I2S_DA_IN2 in PMQFP80-11 package):
 I²S serial data input, 16, 18...32 bits per sample.
- I2S_DA_OUT:
 I²S serial data output, 16, 18...32 bits per sample.
- I2S_CL:
 I²S serial clock.
- I2S_WS:
 I²S word strobe signal defines the left and right sample.

If the MSP 44x8G serves as the master on the I²S interface, the clock and word strobe lines are driven by the MSP. In this mode, only 16, 32 bits per sample can be selected. In slave mode, these lines are input to the MSP 44x8G and the MSP clock is synchronized to 384 times the I2S_WS rate (48 kHz). NICAM operation is not possible in slave mode.

An I^2S timing diagram is shown in Fig. 4–24 on page 65.

2.7.2. Asynchronous I²S Input Interface

The asynchronous I²S slave interface allows the reception of digital stereo signals with arbitrary sample rates from 6 to 49 kHz. In addition, a sample rate of 96 kHz is also supported at the asynchronous I²S input. The synchronization is performed by means of an adaptive sample rate converter. No oversampling clock is required.

The following pins are used for the asynchronous I²S input interface:

- I2S_WS3 (serves only as input)
- I2S_CL3 (serves only as input)
- I2S_DA_IN2/3 (I2S_DA_IN3 in PMQFP80-11 package).

The interface accepts I²S-input streams with MSB first and with sample widths of 16,18...32 bits. With left/right alignment and wordstrobe timing polarity, there are additional parameters available for the adaption to a variety of formats in the I²S-CONFIGURATION register (see page 26).

2.7.3. Asynchronous I²S Output Interface

The asynchronous I²S Master/Slave interface allows the transmission of digital stereo signals with arbitrary sample rates from 6 to 49 kHz. The synchronization is performed by means of an adaptive sample rate converter. In master mode, a programmable internal clock generator is used (see page 34). No oversampling clock is required.

The following pins are used for the asynchronous I²S output interface:

- I2S WS4
- I2S CL4
- I2S_DA_OUT4

The interface transmits I²S streams with MSB first and with sample widths of 16 or 32 bits. With left/right alignment and wordstrobe timing polarity, there are additional parameters available for the adaption to a variety of formats in the I²S CONFIGURATION2 register (see page 26).

2.8. Digital Control I/O Pins and Status Change Indication

The static level of the digital input/output pins D_CTR_I/O_0/1 is switchable between HIGH and LOW via the I²C-bus by means of the ACB register (see page 33). This enables the controlling of external hardware switches or other devices via I²C-bus.

The digital input/output pins can be set to high impedance by means of the MODUS register (see page 25). In this mode, the pins can be used as input. The current state can be read out of the STATUS register (see page 27).

Optionally, the pin D_CTR_I/O_1 can be used as an interrupt request signal to the controller, indicating any changes in the read register STATUS. This makes polling unnecessary, I²C bus interactions are reduced to a minimum (see "STATUS Register" on page 27 and "MODUS Register" on page 25).

If Audio/Video synchronization is used, D_CTR_I/O_0 has to be programmed as input in the MODUS register and the field synchronization signal of the video color decoder (e.g. VPX 322xF pin VREF_I) must be connected.

2.9. Preemphasis

When using the Aux output for feeding an external modulator, a preemphasis can be applied to the right channel.

The signal is scaled down by -3 dB. An overmodulation protection is included in the algorithm which limits the output signal to 0 dBFS. Due to the nature of a preemphasis, its gain at high frequencies exceeds 3 dB. Thus, even with 0 dB input signals and prescaler / volume set to 0 dB, clipping can occur.

There are three modes present: preemphasis off, 50 μ s, and 75 μ s. See Table 3–11 on page 28 for the register settings.

2.10. Clock PLL Oscillator and Crystal Specifications

The MSP 44x8G derives all internal system clocks from the 18.432 MHz oscillator. In NICAM or in I²S-Slave mode of the synchronous interface, the clock is phase-locked to the corresponding source. Therefore, it is not possible to use NICAM and I²S-Slave mode of the synchronous interface at the same time.

For proper performance, the MSP clock oscillator requires a 18.432-MHz crystal. Note that for the phase-locked modes (NICAM, I²S-Slave), crystals with tighter tolerance are required. Please note also, that the asynchronous I²S3 slave interface uses a different locking mechanism and does not require tighter crystal tolerances.

2.11. Audio/Video Synchronization

The I²S4 output interface can be used to synchronize audio and video data compliant to standard AES11-1997. If Audio/Video synchronization is active, D_CTR_I/O_0 has to be programmed as input in MODUS register and the field synchronization signal of the video color decoder (e.g. VPX 322xF pin VREF_I) must be connected.

3. Control Interface

3.1. Device and Subaddresses

The MSP 44x8G is controlled via the I²C bus slave interface.

The IC is selected by transmitting one of the MSP 44x8G device addresses. In order to allow up to three MSP ICs to be connected to a single bus, an address select pin (ADR_SEL) has been implemented. With ADR_SEL pulled to high, low, or left open, the MSP 44x8G responds to different device addresses. A device address pair is defined as a write address and a read address (see Table 3–1).

Writing is done by sending the write device address, followed by the subaddress byte, two address bytes, and two data bytes.

Reading is done by sending the write device address, followed by the subaddress byte and two address bytes. Without sending a stop condition, reading of the addressed data is completed by sending the device read address and reading two bytes of data.

Refer to Section 3.1.3. for the I²C bus protocol and to Section 3.4. "Programming Tips" on page 37 for proposals of MSP 44x8G I²C telegrams. See Table 3–2 for a list of available subaddresses.

Besides the possibility of hardware reset, the MSP can also be reset by means of the RESET bit in the CONTROL register by the controller via I²C bus.

Due to the architecture of the MSP 44x8G, the IC cannot react immediately to an I²C request. The typical

response time is about 0.3 ms. If the MSP cannot accept another byte of data (e.g. while servicing an internal interrupt), it holds the clock line I2C_CL low to force the transmitter into a wait state. The I²C Bus Master must read back the clock line to detect when the MSP is ready to receive the next I²C transmission. The positions within a transmission where this may happen are indicated by 'Wait' in section Section 3.1.3. The maximum wait period of the MSP during normal operation mode is less than 1 ms.

3.1.1. Internal Hardware Error Handling

In case of any hardware problems (e.g. interruption of the power supply of the MSP), the MSP's wait period is extended to 1.8 ms. After this time period elapses, the MSP releases data and clock lines.

Indication and solving the error status:

To indicate the error status, the remaining acknowledge bits of the actual I²C-protocol will be left high. Additionally, bit[14] of CONTROL is set to one. The MSP can then be reset via the I²C bus by transmitting the RESET condition to CONTROL.

Indication of reset:

Any reset, even caused by an unstable reset line etc., is indicated in bit[15] of CONTROL.

A general timing diagram of the I^2C bus is shown in Fig. 4–23 on page 63.

Table 3-1: I²C Bus Device Addresses

ADR_SEL	ADR_SEL Low (connected to DVSS)		High (connected to DVSUP)		Left Open	
Mode	Write	Read	Write	Read	Write	Read
MSP device address	80 _{hex}	81 _{hex}	84 _{hex}	85 _{hex}	88 _{hex}	89 _{hex}

Table 3-2: I²C Bus Subaddresses

Name	Binary Value	Hex Value	Mode	Function
CONTROL	0000 0000	00	Read/Write	Write: Software reset of MSP (see Table 3–3) Read: Hardware error status of MSP
WR_DEM	0001 0000	10	Write	write address demodulator
RD_DEM	0001 0001	11	Write	read address demodulator
WR_DSP	0001 0010	12	Write	write address DSP
RD_DSP	0001 0011	13	Write	read address DSP

3.1.2. Description of CONTROL Register

Table 3–3: CONTROL as a Write Register

Name	Subaddress	Bit[15] (MSB)	Bits[14:0]
CONTROL	00 _{hex}	1 : RESET 0 : normal	0

Table 3-4: CONTROL as a Read Register

Name	Subaddress	Bit[15] (MSB)	Bit[14]	Bits[13:0]			
CONTROL	00 _{hex}	RESET status after last reading of CONTROL: 0 : no reset occured 1 : reset occured	Internal hardware status: 0 : no error occured 1 : internal error occured	not of interest			
Reading of CONTROL will reset the bits[15,14] of CONTROL. After Power-on, bit[15] of CONTROL will be set; it must be read once to be reset.							

3.1.3. Protocol Description

Write to DSP or Demodulator

s	write	Wait	ACK	sub-addr	ACK	addr-byte	ACK	addr-byte	ACK	data-byte	ACK	data-byte	ACK	Р
	device					high		low		high		low		
	address													
	address													

Read from DSP or Demodulator

S	write	Wait	ACK	sub-addr	ACK	addr-byte	ACK	addr-byte	ACK	S	read	Wait	ACK	data-byte-	ACK	data-byte	NAK	Р
	device					high		low			device			high		low		
	address										address							

Write to Control Registers

Ī	S	write	Wait	ACK	sub-addr	ACK	data-byte	ACK	data-byte	ACK	Р
		device					high		low		
		address									

Read from Control Register

S	write device	Wait	ACK	00hex	ACK	S	device	Wait	ACK	data-byte- high	ACK	data-byte low	NAK	Р
	address						address							i

Note: $S = I^2C$ -Bus Start Condition from master

 $P = I^2C$ -Bus Stop Condition from master

ACK = Acknowledge-Bit: LOW on I2C_DA from slave (= MSP, light gray) or master (= controller, dark gray)

NAK = Not Acknowledge-Bit: HIGH on I2C_DA from master (dark gray) to indicate 'End of Read'

or from MSP indicating internal error state

Wait = I^2 C-Clock line is held low, while the MSP is processing the I^2 C command.

This waiting time is max. 1 ms

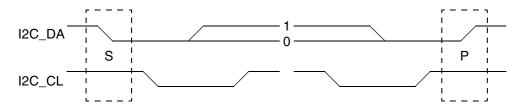


Fig. 3–1: I²C bus protocol (MSB first; data must be stable while clock is high)

3.1.4. Proposals for General MSP 44x8G I²C Telegrams

3.1.4.1. Symbols

daw write device address (80_{hex}, 84_{hex} or 88_{hex})
 read device address (81_{hex}, 85_{hex} or 89_{hex})
 Start Condition
 Stop Condition
 aa Address Byte
 dd Data Byte

3.1.4.2. Write Telegrams

<daw< th=""><th>00</th><th>d0</th><th>00></th><th>></th><th></th><th>write to CONTROL register</th></daw<>	00	d0	00>	>		write to CONTROL register
<daw< td=""><td>10</td><td>aa</td><td>aa</td><td>dd</td><td>dd></td><td>write data into demodulator</td></daw<>	10	aa	aa	dd	dd>	write data into demodulator
<daw< td=""><td>12</td><td>aa</td><td>aa</td><td>дд</td><td>44></td><td>write data into DSP</td></daw<>	12	aa	aa	дд	44>	write data into DSP

3.1.4.3. Read Telegrams

<daw< th=""><th>00</th><th><da< th=""><th>ar o</th><th>dd dd:</th><th>></th><th></th><th>read data from</th></da<></th></daw<>	00	<da< th=""><th>ar o</th><th>dd dd:</th><th>></th><th></th><th>read data from</th></da<>	ar o	dd dd:	>		read data from
							CONTROL register
<daw< td=""><td>11</td><td>aa</td><td>aa</td><td><dar< td=""><td>dd</td><td>dd></td><td>read data from demodulator</td></dar<></td></daw<>	11	aa	aa	<dar< td=""><td>dd</td><td>dd></td><td>read data from demodulator</td></dar<>	dd	dd>	read data from demodulator
<daw< td=""><td>13</td><td>aa</td><td>aa</td><td><dar< td=""><td>dd</td><td>dd></td><td>read data from DSP</td></dar<></td></daw<>	13	aa	aa	<dar< td=""><td>dd</td><td>dd></td><td>read data from DSP</td></dar<>	dd	dd>	read data from DSP

3.1.4.4. Examples

<80	00	80	00>	>			RESET MSP statically
<80	00	00	00>	>			Clear RESET
<80	10	00	30	00	01>		Automatic Sound Select = ON
<80	10	00	20	00	03>		Set demodulator to stand. 03 _{hex}
<80	11	02	00	<81	L dd	dd>	Read STATUS
<80	12	00	80	01	20>		Set MAIN channel
							source to Stereo or A/B and
							Matrix to Stereo
							(transparent mode)

More examples of typical application protocols are listed in Section 3.4. "Programming Tips" on page 37.

3.2. Start-Up Sequence: Power-Up and I²C-Controlling

After POWER-ON or RESET (see Fig. 4–22), the IC is in an inactive state. All registers are in the Reset position (see Table 3–5 and Table 3–6), the analog outputs are muted. The controller has to initialize all registers for which a non-default setting is necessary.

3.3. MSP 44x8G Programming Interface

3.3.1. User Registers Overview

The MSP 44x8G is controlled by means of user registers. The complete list of all user registers are given in Table 3–5 and Table 3–6. The registers are partitioned into the Demodulator section (Subaddress $10_{\rm hex}$ for writing, $11_{\rm hex}$ for reading) and the Baseband Processing sections (Subaddress $12_{\rm hex}$ for writing, $13_{\rm hex}$ for reading).

Write and read registers are 16 bit wide, whereby the MSB is denoted bit[15]. Transmissions via I²C bus have to take place in 16-bit words (two byte transfers, with the most significant byte transferred first). All write registers, except the demodulator write registers are readable.

Unused parts of the 16-bit write registers must be zero. Addresses not given in this table must not be accessed.

Table 3–5: List of MSP 44x8G Write Registers

Write Register	Address (hex)	Bits	Description and Adjustable Range	Reset	See Page
I ² C Subaddress = 10 _{hex} ; Registers at	re not readal	ole			
STANDARD SELECT	00 20	[15:0]	Initial Programming of complete Demodulator	00 00	24
MODUS	00 30	[15:0]	Demodulator, Automatic and I ² S options	00 00	25
I ² S CONFIGURATION	00 40	[15:0]	Configuration of I ² S options	00 00	26
I ² S ASYNC OUTPUT CONFIG	00 50	[15:0]	Configuration of I ² S4 options	00 00	26
I ² C Subaddress = 12 _{hex} ; Registers and	re <i>all</i> readabl	e by usin	g I ² C Subaddress = 13 _{hex}		
Volume main channel	00 00	[15:8]	[+12 dB –114 dB, MUTE]	MUTE	31
		[7:5] [4:0]	1/8 dB Steps must be set to 0	000 _{bin} 00000 _{bin}	
Volume Aux channel	00 06	[15:8]	[+12 dB –114 dB, MUTE]	MUTE	31
		[7:5] [4:0]	1/8 dB Steps must be set to 0	000 _{bin} 00000 _{bin}	
Volume SCART1 output channel	00 07	[15:8]	[+12 dB –114 dB, MUTE]	MUTE	32
Main source select	00 08	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM/AM	30
Main channel matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30
Aux source select	00 09	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM/AM	30
Aux channel matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30
SCART1 source select	00 0A	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM/AM	30
SCART1 channel matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30
I ² S source select	00 0B	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM/AM	30
I ² S channel matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30
Quasi-peak detector source select	00 0C	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM/AM	30
Quasi-peak detector matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30
Prescale SCART input	00 0D	[15:8]	[00 _{hex} 7F _{hex}]	00 _{hex}	29
Prescale FM/AM	00 0E	[15:8]	[00 _{hex} 7F _{hex}]	00 _{hex}	28
FM matrix		[7:0]	[NO_MAT, GSTEREO, KSTEREO]	NO_MAT	29
Prescale NICAM	00 10	[15:8]	[00 _{hex} 7F _{hex}]	00 _{hex}	29
Prescale I ² S3	00 11	[15:8]	[00 _{hex} 7F _{hex}]	10 _{hex}	29
Prescale I ² S2	00 12	[15:8]	[00 _{hex} 7F _{hex}]	10 _{hex}	29
SCART switches and D_CTR_I/O	00 13	[15:0]	Bits [15:0]	00 _{hex}	33
Beeper	00 14	[15:0]	[00 _{hex} 7F _{hex}]/[00 _{hex} 7F _{hex}]	00/00 _{hex}	34
Prescale I ² S1	00 16	[15:8]	[00 _{hex} 7F _{hex}]	10 _{hex}	29
AVC: Automatic Volume Correction	00 29	[15:8]	[off, on, decay time]	off	31
I2S4 Output Sample Frequency	00 2A	[15:0]	[48kHz 8kHz]	00 _{hex}	34
Audio/Video Synchronization	00 2B	[15:0]	[ON, Default Freq automatic mode, manual mode]	00 _{hex}	35
Aux Preemphasis on right channel	00 34	[15:8]	[OFF, 50 µs, 75 µs]	OFF	31
Mix1 source select	00 38	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM/AM	30
Mix1 channel matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30

Table 3-5: List of MSP 44x8G Write Registers, continued

Write Register	Address (hex)	Bits	Description and Adjustable Range	Reset	See Page
Mix2 source select	00 39	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM/AM	30
Mix2 channel matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30
Scale Mix1	00 3A	[15:8]	[00 _{hex} 7F _{hex}]	00 _{hex}	34
Scale Mix2	00 3B	[15:8]	[00 _{hex} 7F _{hex}]	00 _{hex}	34
Volume SCART2 output channel	00 40	[15:8]	[+12 dB114 dB, MUTE]	00 _{hex}	32
SCART2 source select	00 41	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM	30
SCART2 channel matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30
I2S4 source select	00 46	[15:8]	[FM/AM, NICAM, SCART, I ² S13, Mix output]	FM	30
I2S4 channel matrix		[7:0]	[SOUNDA, SOUNDB, STEREO, MONO]	SOUNDA	30

Table 3-6: List of MSP 44x8G Read Registers

Read Register	Address (hex)	Bits	Description and Adjustable Range	See Page					
I ² C Subaddress = 11 _{hex} ; Registers	I ² C Subaddress = 11 _{hex} ; Registers are <i>not</i> writable								
STANDARD RESULT	00 7E	[15:0]	Result of Automatic Standard Detection (see Table 3–8)	27					
STATUS	02 00	[15:0]	Monitoring of settings e.g. Stereo, Mono, Mute, D_CTR_I/O etc	27					
I ² C Subaddress = 13 _{hex} ; Registers are <i>not</i> writable									
Quasi peak readout left	00 19	[15:0]	[00 _{hex} 7FFF _{hex}]16 bit two's complement	36					
Quasi peak readout right	00 1A	[15:0]	[00 _{hex} 7FFF _{hex}]16 bit two's complement	36					
MSP hardware version code	00 1E	[15:8]	[00 _{hex} FF _{hex}]	36					
MSP major revision code		[7:0]	[00 _{hex} FF _{hex}]	36					
MSP product code	00 1F	[15:8]	[00 _{hex} FF _{hex}]	36					
MSP ROM version code		[7:0]	[00 _{hex} FF _{hex}]	36					

3.3.2. Description of User Registers

Table 3-7: Standard Codes for STANDARD SELECT register

MSP Standard Code (Data in hex)	TV Sound Standard	Sound Carrier Frequencies in MHz	MSP 44x8G Version
	Automatic Standard Detectio	n	
00 01	Starts Automatic Standard Detection and sets to detected standard		all
	Standard Selection	,	,
00 02	M-Dual FM-Stereo	4.5/4.724212	4408, -18, -48, -58
00 03	B/G-Dual FM-Stereo ¹⁾	5.5/5.7421875	4408, -18, -58
00 04	D/K1-Dual FM-Stereo ²⁾	6.5/6.2578125	
00 05	D/K2-Dual FM-Stereo ²⁾	6.5/6.7421875	
00 06	D/K-FM-Mono with HDEV3 ³⁾ , not detectable by Automatic Standard Detection, HDEV3 ³⁾ SAT-Mono (i.e. Eutelsat, see Table 6–12)	6.5	
00 07	D/K3-Dual FM-Stereo	6.5/5.7421875	4408, -18, -58
00 08	B/G-NICAM-FM ¹⁾	5.5/5.85	4418, -58
00 09	L-NICAM-AM	6.5/5.85	
00 0A	I-NICAM-FM	6.0/6.552	
00 0B	D/K-NICAM-FM ²⁾	6.5/5.85	
00 0C	D/K-NICAM-FM with HDEV2 ⁴⁾ , not detectable by Automatic Standard Detection, for China	6.5/5.85	
00 0D	D/K-NICAM-FM with HDEV3 ³⁾ , not detectable by Automatic Standard Detection, for China	6.5/5.85	4418, -58
00 20	BTSC-Stereo	4.5	4428, -48, -58
00 21	BTSC-Mono + SAP		
00 30	EIA-J Japan Stereo	4.5	4428, -48, -58
00 40	FM-Stereo Radio with 75 μs Deemphasis	10.7	4428, -48, -58
00 50	SAT-Mono (see Table 6–12)	6.5	4408, -18, -58
00 51	SAT-Stereo (see Table 6–12)	7.02/7.20	4408, -18, -58

 $^{^{1)}}$ In case of Automatic Sound Select, the B/G-codes 3_{hex} and 8_{hex} are equivalent. $^{2)}$ In case of Automatic Sound Select, the D/K-codes 4_{hex} , 5_{hex} , 7_{hex} and B_{hex} are equivalent. $^{3)}$ HDEV3: Max. FM deviation must not exceed 540 kHz $^{4)}$ HDEV2: Max. FM deviation must not exceed 360 kHz

3.3.2.1. STANDARD SELECT Register

The TV sound standard of the MSP 44x8G demodulator is determined by the STANDARD SELECT register. There are two ways to use the STANDARD SELECT register:

- Setting up the demodulator for a TV sound standard by sending the corresponding standard code with a single I²C bus transmission.
- Starting the Automatic Standard Detection for terrestrial TV standards. This is the most comfortable way to set up the demodulator. Within 0.5 s, the detection and setup of the actual TV sound standard is performed. The detected standard can be read out of the STANDARD RESULT register by the control processor. This feature is recommended for the primary setup of a TV set. Outputs should be muted during Automatic Standard Detection.

The Standard Codes are listed in Table 3-7.

Selecting a TV sound standard via the STANDARD SELECT register initializes the demodulator. This includes: AGC-settings and carrier mute, tuning frequencies, FIR-filter settings, demodulation mode (FM, AM, NICAM), deemphasis and identification mode.

TV stereo sound standards that are unavailable for a specific MSP version are processed in analog mono sound of the standard. In that case, stereo or bilingual processing will not be possible.

For a complete setup of the TV sound processing from analog IF input to the source selection, the transmissions as shown in Section 3.5. on page 37 are necessary.

There is a manual mode.

3.3.2.2. Refresh of STANDARD SELECT Register

A general refresh of the STANDARD SELECT register is not allowed. However, the following method enables watching the MSP 44x8G "alive" status and detection of accidental resets (only versions B6 and later):

- After Power-on, bit[15] of CONTROL will be set; it must be read once to enable the reset-detection feature.
- Reading of the CONTROL register and checking the reset indicator bit[15].
- If bit[15] is "0", any refresh of the STANDARD SELECT register is not allowed.
- If bit[15] is "1", indicating a reset, a refresh of the STANDARD SELECT register and all other MSPG registers is required.

3.3.2.3. STANDARD RESULT Register

If Automatic Standard Detection is selected in the STANDARD SELECT register, status and result of the Automatic Standard Detection process can be read out of the STANDARD RESULT register. The possible results are based on the mentioned Standard Code and are listed in Table 3–8.

In cases where no sound standard has been detected (no standard present, too much noise, strong interferers, etc.) the STANDARD RESULT register contains $00~00_{\rm hex}$. In that case, the controller has to start further actions (for example set the standard according to a preference list or by manual input).

As long as the STANDARD RESULT register contains a value greater than 07 FF $_{\rm hex}$, the Automatic Standard Detection is still active. During this period, the MODUS and STANDARD SELECT register must not be written. The STATUS register will be updated when the Automatic Standard Detection has finished.

If a present sound standard is unavailable for a specific MSP-version, it detects and switches to the analog mono sound of this standard.

Example:

The MSP 4448G will detect a B/G-NICAM signal as standard 3 and will switch to the analog FM-Mono sound.

Table 3–8: Results of the Automatic Standard Detection

Broadcasted Sound Standard	STANDARD RESULT Register Read 007E _{hex}
Automatic Standard Detection could not find a sound standard	0000 _{hex}
B/G-FM	0003 _{hex}
B/G-NICAM	0008 _{hex}
1	000A _{hex}
FM-Radio	0040 _{hex}
M-Korea	0002 _{hex} (if MODUS[14,13]=00)
M-Japan M-BTSC	0020 _{hex} (if MODUS[14,13]=01)
	0030 _{hex} (if MODUS[14,13]=10)
L-AM D/K1	0009 _{hex} (if MODUS[12]=0)
D/K1 D/K2 D/K3	0004 _{hex} (if MODUS[12]=1)
L-NICAM D/K-NICAM	0009 _{hex} (if MODUS[12]=0)
D/R-INICAIVI	000B _{hex} (if MODUS[12]=1)
Automatic Standard Detection still active	>07FF _{hex}

3.3.2.4. Write Registers on I^2C Subaddress 10_{hex}

Table 3–9: Write Registers on I²C Subaddress 10_{hex}

Register Address	Function	Name
STANDAR	D SELECTION	
00 20 _{hex}	STANDARD SELECTION Register	STANDARD_SEL
	Defines TV Sound or FM-Radio Standard	
	bit[15:0] 00 01 _{hex} start Automatic Standard Detection 00 02 _{hex} Standard Codes (see Table 3–7)	
	 00 60 _{hex}	

Table 3–9: Write Registers on I^2C Subaddress 10_{hex} , continued

Register Address	Function			Name
MODUS				
00 30 _{hex}	MODUS F	Register		MODUS
	Preferenc	e in Autom	atic Standard Detection:	
	bit[15]	0	reserved, must be 0	
	bit[14:13]	0 1 2 3	detected 4.5 MHz carrier is interpreted as: ¹⁾ standard M (Korea) standard M (BTSC) standard M (Japan) chroma carrier (M/N standards are ignored)	
	bit[12]	0 1	detected 6.5 MHz carrier is interpreted as: ¹⁾ standard L (SECAM) standard D/K1, D/K2, D/K3, or D/K NICAM	
	General M	ISP 44x8G	G Options	
	bit[11:9]	0	reserved, must be 0	
	bit[8]	0/1	ANA_IN1+/ANA_IN2+; select analog sound IF input pin	
	bit[7]	0/1	active/tristate state of audio clock output pin AUD_CL_OUT	
	bit[6]	0	word strobe alignment (synchronous I ² S) WS changes at data word boundary WS changes one clock cycle in advance	
	bit[5]	0/1	master/slave mode of I ² S interface (must be set to 0 (= Master) in case of NICAM mode)	
	bit[4]	0/1	active/tristate state of I ² S output pins	
	bit[3]	0	state of digital output pins D_CTR_I/O_0 and _1 active: D_CTR_I/O_0 and _1 are output pins (can be set by means of the ACB register. see also: MODUS[1])	
		1	tristate: D_CTR_I/O_0 and _1 are input pins (level can be read out of STATUS[4,3]) Tristate is needed for A/V synchronization mode.	
	bit[2]	0	reserved, must be 0	
	bit[1]	0/1	disable/enable STATUS change indication by means of the digital I/O pin D_CTR_I/O_1 Necessary condition: MODUS[3] = 0 (active)	
	bit[0]	0/1	off/on: Automatic Sound Select	
1) Valid at t	he next star	t of Automa	atic Standard Detection.	

Table 3–9: Write Registers on I^2C Subaddress 10_{hex} , continued

Register Address	Function			Name
0040 _{hex}			ON Register ombinations must not be used)	I2S_CONFIG
	bit[15:12]	0	undefined, must be set to 0	
	bit[11]	0 1	I ² S Data alignment (I ² S_3) left aligned right aligned	
	bit[10]	0 1	word strobe polarity (I ² S_3) 1 = right, 0 = left 0 = right, 1 = left	
	bit[9]	0 1	word strobe alignment (asynchronous I ² S_3) WS changes at data word boundary WS changes one clock cycle in advance	
	bit[8:2]	0	undefined, must be set to 0	
	bit[1:0]	00 01 1x	I2S_CL frequency and I ² S_DA_OUT sample length 2 * 16 Bit (1.536 MHz Clk) 2 * 32 Bit (3.072 MHz Clk) undefined, must not be used	
0050 _{hex}	I ² S CONFI	GURATIC	DN2 Register	I2S_CONFIG2
	bit[15:6]	0	undefined, must be set to 0	
	bit[5]	0 1	pad driver strength (I2S_4) weak strong	I2S4_STRENGTH
	bit[4]	0	enable/disable I2S Out (I2S_4) asyn-I2S-out off asyn-I2S-out on	I2S4_MODE
	bit[3]	0	master / slave mode of I2S Out (I2S_4) master slave	I2S4_SLAVE
	bit[2]	0 1	I2S Out word strobe polarity (I2S_4) 1 = right, 0 = left (L = Low, R = High) 0 = right, 1 = left (L = High, R = Low)	I2S4_WS_POL
	bit[1]	0 1	I2S Out word strobe alignment (I2S_4) wordstrobe changes at data word boundary wordstrobe changes one clock cycle in advance	I2S4_WS_MODE
	bit[0]	0	I2S_CL4 frequency and I ² S_DA_OUT4 sample length 32-bit/sample 16-bit/sample	I2S4_WLEN

3.3.2.5. Read Registers on I²C Subaddress 11_{hex}

Table 3–10: Read Registers on I²C Subaddress 11_{hex}

Register Address	Function	1		Name
00 7E _{hex}	STANDARD RESULT		T Register	STANDARD_RES
	Readbac	k of the det	ected TV Sound or FM-Radio Standard	
	bit[15:0]	00 00 _{hex}	Automatic Standard Detection could not find	
		00 02 _{hex}	a sound standard MSP Standard Codes (see Table on page 26)	
		00 40 _{hex} >07 FF _{hex}	Automatic Standard Detection still active	
02 00 _{hex}	STATUS	Register		STATUS
	Contains	all user rele	evant internal information about the status of the MSP	
	bit[15:10]	undefined	
	bit[8]	0/1	"1" indicates bilingual sound mode or SAP present (internally evaluated from received analog or digital identification signals)	
	bit[7]	0/1	"1" indicates independent mono sound (only for NICAM)	
	bit[6]	0/1	mono/stereo indication	
	bit[5,9]	00 01 10 11	analog sound standard (FM or AM) active this pattern will not occur digital sound (NICAM) available bad reception condition of digital sound (NICAM) due to: a. high error rate b. unimplemented sound code c. data transmission only	
	bit[4]	0/1	low/high level of digital I/O pin D_CTR_I/O_1	
	bit[3]	0/1	low/high level of digital I/O pin D_CTR_I/O_0 In A/V synchronization mode, this information is not available.	
	bit[2]	0 1	detected secondary carrier (2nd A2 or SAP carrier) no secondary carrier detected	
	bit[1]	0 1	detected primary carrier (Mono or MPX carrier) no primary carrier detected	
	bit[0]		undefined	
	change i	n the STATL	Idication is activated by means of MODUS[1]: Each JS register sets the digital I/O pin D_CTR_I/O_1 to high TATUS register resets D_CTR_I/O_1.	

3.3.2.6. Write Registers on I²C Subaddress 12_{hex}

Table 3–11: Write Registers on I²C Subaddress 12_{hex}

Register Address	Function	ı		Name
PREPROC	ESSING			
00 0E _{hex}	FM/AM P	rescale		PRE_FM
	bit[15:8]	00 _{hex}	Defines the input prescale gain for the demodulated FM or AM signal	
		7F _{hex} 00 _{hex}	off (RESET condition)	
	cale value		xcept satellite FM and AM-mode, the combinations of preseviation listed below lead to internal full scale with 1 kHz test phasis.	
	FM mode	•		
	bit[15:8]	7F _{hex} 48 _{hex} 30 _{hex} 24 _{hex} 18 _{hex}	28 kHz FM deviation 50 kHz FM deviation 75 kHz FM deviation 100 kHz FM deviation 150 kHz FM deviation 180 kHz FM deviation (limit)	
	FM high o	deviation m	node (HDEV2, MSP Standard Code = C _{hex})	
	bit[15:8]	30 _{hex} 14 _{hex}	150 kHz FM deviation 360 kHz FM deviation (limit)	
	FM very h	nigh deviati	on mode (HDEV3, MSP Standard Code = 6)	
	bit[15:8]	20 _{hex} 1A _{hex}	450 kHz FM deviation 540 kHz FM deviation (limit)	
	Satellite F	-M with ada	aptive deemphasis	
	bit[15:8]	10 _{hex}	recommendation	
	AM mode	(MSP Sta	ndard Code = 9)	
	bit[15:8]	7C _{hex}	recommendation for SIF input levels from 0.1 V_{pp} to 0.8 V_{pp}	
			(Due to the AGC switched on, the AM-output level remains stable and independent of the actual SIF-level in the mentioned input range)	

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Table 3–11: Write Registers on I²C Subaddress 12_{hex}, continued

Register Address	Function		Name
(continued)	FM Matrix Modes		FM_MATRIX
00 0E _{hex}	Defines the dematrix fur	nction for the demodulated FM signal	
	01 _{hex} Go 02 _{hex} Ko 03 _{hex} so	o matrix (used for bilingual and unmatrixed stereo sound) erman stereo (Standard B/G) orean stereo (also used for BTSC, EIA-J, and FM Radio) bund A mono (left and right channel contain the mono bund of the FM/AM mono carrier) bund B mono (i.e. SAP)	
	cally. Writing to the FM/A In order not to disturb the	ound Select = on , the FM Matrix Mode is set automati-AM prescale register (00 0E _{hex} high part) is still allowed. ne automatic process, the low part of any I ² C transmisnored. Therefore, any FM-Matrix readback values may previously.	
	In case of Automatic So shown in Table 6–11 of A	ound Select = off, the FM Matrix Mode must be set as Appendix B.	
	To enable a Forced Mor Section 6.3.2. on page 8	no Mode set A2 THRESHOLD as described in 34	
00 10 _{hex}	NICAM Prescale		PRE_NICAM
	Defines the input presca	ale value for the digital NICAM signal	
	bit[15:8] 00 _{hex} 7F _{he}	_{ex} prescale gain	
	examples:		
	5A _{hex} 9	ff dB gain dB gain (recommendation) 12 dB gain (maximum gain)	
00 16 _{hex} 00 12 _{hex} 00 11 _{hex}	I2S1 Prescale I2S2 Prescale I2S3 Prescale		PRE_I2S1 PRE_I2S2 PRE_I2S3
	Defines the input presca	ale value for digital I ² S input signals	
	bit[15:8] 00 _{hex} 7F _{he}	_{ex} prescale gain	
		if dB gain (recommendation) 18 dB gain (maximum gain)	
00 0D _{hex}	SCART Input Prescale		PRE_SCART
	Defines the input presca	ale value for the analog SCART input signal	
	bit[15:8] 00 _{hex} 7F _{he}	_{ex} prescale gain	
		if dB gain (2 V _{RMS} input leads to digital full scale) 14 dB gain (400 mV _{RMS} input leads to digital full scale)	

Table 3–11: Write Registers on I²C Subaddress 12_{hex}, continued

	Register Address	Function			Name	
	SOURCE S	SELECT AN				
I	00 08 _{hex} 00 09 _{hex} 00 0A _{hex} 00 41 _{hex} 00 0B _{hex} 00 0C _{hex} 00 38 _{hex} 00 39 _{hex} 00 46 _{hex}	Source fo	urce for: Main Output Aux Output SCART1 DA Output SCART2 DA Output I ² S Output Quasi-Peak Detector Mix1 Input Mix2 Input I2S4 Async Output			
		bit[15:8]	00 _{hex}	"FM/AM": demodulated FM or AM mono signal		
			01 _{hex}	"Stereo or A/B": demodulator Stereo or A/B signal		
			03 _{hex}	"Stereo or A": demodulator Stereo Sound or Language A (only defined for Automatic Sound Select)		
			04 _{hex}	"Stereo or B": demodulator Stereo Sound or Language B (only defined for Automatic Sound Select)		
			02 _{hex}	SCART input		
			05 _{hex}	I ² S1 input		
			06 _{hex}	I ² S2 input		
			07 _{hex}	I ² S3 input		
			0F _{hex}	Mix output		
		For demo	dulator sou	urces, see Table 2–2.		
1	00 08 _{hex} 00 09 _{hex} 00 0A _{hex} 00 41 _{hex} 00 0B _{hex} 00 0C _{hex} 00 38 _{hex} 00 39 _{hex} 00 46 _{hex}	Matrix Me	Main Out Aux Out SCART1 SCART2 I ² S Outp Quasi-Pe Mix1 Inp Mix2 Inp	put DA Output DA Output ut eak Detector ut	MAT_MAIN MAT_AUX MAT_SCART1 MAT_SCART2 MAT_I2S MAT_QPEAK MAT_MIX1 MAT_MIX2 MAT_I2S4	
		bit[7:0]	00 _{hex} 10 _{hex} 20 _{hex} 30 _{hex}	Sound A Mono (or Left Mono) Sound B Mono (or Right Mono) Stereo (transparent mode) Mono (sum of left and right inputs divided by 2) More modes are listed in Section 6.5.1.		
		according	to Table 2	d Select mode, the demodulator source channels are set 1-2. Therefore, the matrix modes of the corresponding output set to "Stereo" (transparent).		

Table 3–11: Write Registers on I²C Subaddress 12_{hex}, continued

Register Address	Function			Name
MAIN AND	AUX PRO	CESSING		
00 00 _{hex} 00 06 _{hex}	Volume N Volume A	VOL_MAIN VOL_AUX		
	bit[15:8]	7F _{hex} 7E _{hex}	uble with 1 dB step size +12 dB (maximum volume) +11 dB	
		74 _{hex} 73 _{hex} 72 _{hex}	+1 dB 0 dB -1 dB	
		02 _{hex} 01 _{hex} 00 _{hex} FF _{hex}	-113 dB -114 dB Mute (reset condition) Fast Mute (needs about 75 ms until the signal is completely ramped down)	
	bit[7:5]	higher res 0 1	solution volume table +0 dB +0.125 dB increase in addition to the volume table	
		 7	+0.875 dB increase in addition to the volume table	
	bit[4:0]	not used must be s	set to 0	
	With large	scale input	t signals, positive volume settings may lead to signal clipping.	
	analog se ume only. turn volur	ection. With Analog vo	ain and Aux volume function is divided into a digital and an Fast Mute, volume is reduced to mute position by digital volume is not changed. This reduces any audible DC plops. To n, the volume step that has been used before Fast Mute was ansmitted.	
00 29 _{hex}	Automati	ic Volume	Correction (AVC) Loudspeaker Channel	AVC
	bit[15]	00 _{hex} 01 _{hex}	AVC off (and reset internal variables) AVC on	
	bit[14]	00 _{hex} 01 _{hex}	AVC is located in main path AVC is located in mixer path	
	bit[11:8]	08 _{hex} 04 _{hex} 02 _{hex} 01 _{hex}	8 sec decay time 4 sec decay time 2 sec decay time 20 ms decay time (should be used for approx. 100 ms after channel change)	
00 34 _{hex}	Preemph	asis Aux (Channel	PREEMP_AUX
	bit[15:8]	00 _{hex} 7F _{hex} FF _{hex}	Preemphasis OFF Preemphasis 50 μs (–3 dB scaling) Preemphasis 75 μs (–3 dB scaling)	

Table 3–11: Write Registers on I²C Subaddress 12_{hex}, continued

Register Address	Function	1		Name
SCART O	UTPUT CH	ANNEL		
00 07 _{hex} 00 40 _{hex}			utput Channel utput Channel	VOL_SCART1 VOL_SCART2
	bit[15:8]	volume to 7Fhex 7Ehex 74hex 73hex 72hex 02hex 01hex 00hex	+11 dB +1 dB 0 dB -1 dB	
	bit[7:5]		solution volume table +0 dB +0.125 dB increase in addition to the volume table +0.875 dB increase in addition to the volume table	
	bit[4:0]	01 _{hex}	this must be 01 _{hex}	

Table 3–11: Write Registers on I²C Subaddress 12_{hex}, continued

Register Address	Function			Name			
SCART SV	SCART SWITCHES AND DIGITAL I/O PINS						
00 13 _{hex}	ACB Reg	jister		ACB_REG			
	Defines th	ne level of the	e digital output pins and the position of the SCART switches				
	bit[15]	0/1	low/high of digital output pin D_CTR_I/O_1 (MODUS[3]=0)				
	bit[14]	0/1	low/high of digital output pin D_CTR_I/O_0 (MODUS[3]=0)				
	bit[13:5]	xxxx00 xx0 xxxx01 xx0 xxxx10 xx0 xxxx11 xx0	matrix mode for the corresponding output channels) SCART2 to DSP input SCART3 to DSP input				
	bit[13:5]	xxxx11 xx1	SCART4 to DSP input mute DSP input utput Select				
	ЫЦ 1 3. 3]	xx00xx x0x xx01xx x0x xx10xx x0x xx11xx x0x xx00xx x1x xx01xx x1x xx10xx x1x	SCART3 input to SCART1 output (RESET position) SCART2 input to SCART1 output MONO input to SCART1 output SCART1 DA to SCART1 output SCART2 DA to SCART1 output SCART1 input to SCART1 output SCART4 input to SCART1 output mute SCART1 output				
	bit[13:5]	00xxxx 0xx 01xxxx 0xx 10xxxx 0xx 00xxxx 1xx 01xxxx 1xx 10xxxx 1xx 11xxxx 1xx	utput Select SCART1 DA to SCART2 output (RESET position) SCART1 input to SCART2 output MONO input to SCART2 output SCART2 DA to SCART2 output SCART2 input to SCART2 output SCART3 input to SCART2 output SCART4 input to SCART2 output SCART4 input to SCART2 output mute SCART2 output				
	bit[4:0]	must be ze	·				
	the contro	ol bus to the	becomes active at the time of the first write transmission on audio processing part. By writing to the ACB register first, be redefined.				

Table 3–11: Write Registers on I²C Subaddress 12_{hex}, continued

Register Address	Function	Function					
MIXING UI							
00 3A _{hex} 00 3B _{hex}		MIX1 Scale MIX2 Scale					
	Defines th	ne input scale v	value for the digital	mixing unit			
	bit[15:8]	40 _{hex} 10	: % (-6 dB gain) 0% (0 dB gain) 0% (+6 dB gain = r	naximum gain)			
		ne sum of both ccessive proces		eds 100%, clipping may occur in th	ne		
BEEPER							
00 14 _{hex}	Beeper V	olume and Fr	equency		BEEPER		
	bit[15:8]	Beeper Volum 00 _{hex} off 7F _{hex} ma					
	bit[7:0]	40 _{hex} 1 I	iency Hz (lowest) kHz kHz				
I2S ASYN	СОПТР	INTERFACE					
00 2A _{hex}	I2S4 Out	put Sample Fr	equency		I2S4_OUT_FS		
		the I2S4 outp		y in master mode. In slave mode,			
	bit[15:0]	fs out [kHz]	32 bit/sample	16 bit/sample			
		48 44.1 32 24 22.05 16 12 11.025 8	18 00 _{hex} 1A 1F _{hex} 24 00 _{hex} 30 00 _{hex} 34 3F _{hex} 48 00 _{hex} 60 00 _{hex} 68 7D _{hex} 90 00 _{hex}	30 00 _{hex} 34 3F _{hex} 48 00 _{hex} 60 00 _{hex} 68 7D _{hex} 90 00 _{hex} C0 00 _{hex} D0 FB _{hex}			

Table 3–11: Write Registers on I²C Subaddress 12_{hex}, continued

Register Address	Function	ı		Name		
AUDIO/VID	EO SYNCI	HRONIZAT	ION			
00 2B _{hex}	Audio/Vi	AV_SYNC				
	frequency To use the	Controls the I ² S4 output sample frequency according to the field synchronization frequency input at pin D_CTR_I/O_0 (e.g. of VPX 322xF, pin VREF_I). To use the Audio/Video Synchronization, D_CTR_I/O_0 must be set to tristate (MODUS[3]=1).				
	frequenci I2S4_OU per samp and supp	es 48 kHz, T_FS regis le. Audio/Vi	onization is only supported for the nominal I2S4 sample 44.1 kHz, or 32 kHz which has to be defined in the ter. I ² S4 sample length I2S4_WLEN must be set to 32 bit ideo Synchronization is compliant to standard AES11-1997 d frequencies PAL/SECAM (50 Hz), NTSC (59.94 Hz), and).			
			o disable Audio/Video Synchronization during a channel when the v-sync signal is stable.			
	bit[15]	Enable Au 0 1	udio/Video Synchronization Off On	AV_ON		
	bit[14]	Default fie (bit[2:0] = 0 1	eld frequency for Automatic Video Standard Detection 0) Monochrome (field frequency = 60 Hz) NTSC (field frequency = 59.94 Hz)	AV_AUTOFREC		
	bit[13:3]	reserved,	set to 0			
	bit[2:0]	Video Sta 0 _{hex} 1 _{hex} 2 _{hex} 4 _{hex}	Indard Selection Automatic Video Standard Detection PAL / SECAM (field frequency = 50 Hz) NTSC (field frequency = 59.94 Hz) Monochrome (field frequency = 60 Hz)	AV_STD_SEL		
		Standard sured and SECAM (o standard is selected (bit[2:0] = 0), the Automatic Video Detection is active. In this mode, field frequency is meating the video standard is automatically switched to PAL / field frequency = 50 Hz) or to the frequency defined with onochrome or NTSC).			
		n: Mode ch I off and or	anges only have effect if A/V synchronization is again.			
STATUS2						
00 7B _{hex}	STATUS2	2 Register		STATUS2		
	bit[14]	Status of 0	Audio/Video Synchronization No A/V synchronization. Possible reasons:	AV_ACTIVE		
			Check if frequency I2S4_OUT_FS is set to 48 kHz, 44.1 kHz, or 32 kHz Check if A/V synchronization is switched on. Check v-sync signal at pin D_CTR_I/O_0: Is the v-sync signal stable? Is the v-sync frequency in range of ±5%?			
		1	A/V synchronization is active.			

3.3.2.7. Read Registers on I^2C Subaddress 13_{hex}

Table 3–12: Read Registers on I²C Subaddress 13_{hex}

	Register Address				Name
Ī	QUASI-PE	PEAK DETECTOR READOUT			
	00 19 _{hex} 00 1A _{hex}				QPEAK_L QPEAK_R
		bit[15:0] 0 _{hex} 7FFF _{hex}			
		Values are 16 bit two's complement (only positive). A value of $4000_{\rm hex}$ corresponds to internal full scale.			
	MSP 44x80	x8G VERSION READOUT Registers			
	001E _{hex}	1E _{hex} MSP Hardware Version Code			MSP_HARD
		bit[15:8]	03 _{hex}	MSP 44x8G- <u>C</u> 4	
		A change in the hardware version code defines hardware optimizations that may have influence on the chip's behavior. The readout of this register is identical to the hardware version code in the chip's imprint.			
		MSP Family Code			MSP_FAMILY
		bit[7:4]	1 _{hex}	MSP 44x8G-C4	
		MSP Major Revision Code			MSP_REVISION
		bit[3:0]	7 _{hex}	MSP 44x8 G -C4	
	001F _{hex}	MSP Product Code			MSP_PRODUCT
		bit[15:8]	08 _{hex} 12 _{hex} 1C _{hex} 30 _{hex} 3A _{hex}	MSP 44 <u>08</u> G-C4 MSP 44 <u>18</u> G-C4 MSP 44 <u>28</u> G-C4 MSP 44 <u>48</u> G-C4 MSP 44 <u>58</u> G-C4	
		By means which TV			
		MSP ROM Version Code			MSP_ROM
		bit[7:0]	44 _{hex}	MSP 44x8G-C <u>4</u>	
		may have included. \ lems, cust	influence of While a soft comers that	If version code defines internal software optimizations, that on the chip's behavior, e.g. new features may have been fitware change is intended to create no compatibility probt want to use the new functions can identify new according to this number.	

3.4. Programming Tips

This section describes the preferred method for initializing the MSP 44x8G. The initialization is grouped into four sections:

- SCART Signal Path (analog signal path)
- Demodulator
- SCART and I2S Inputs
- Output Channels

See Fig. 2-1 on page 10 for a complete signal flow.

SCART Signal Path

- Select analog input for the SCART baseband processing (SCART DSP Input Select) by means of the ACB register.
- Select the source for each analog SCART output (SCART Output Select) by means of the ACB register.

Demodulator

For a complete setup of the sound processing from analog IF input to the source selection, the following steps must be performed:

- Set MODUS register to the preferred mode and Sound IF input.
- 2. Write STANDARD SELECT register.
- 3. Choose preferred prescale (FM and NICAM) values.
- If Automatic Sound Select is not active: Choose FM matrix repeatedly according to the sound mode indicated in the STATUS register.

SCART and I²S Inputs

- 1. Select preferred prescale for SCART.
- 2. Select preferred prescale for I²S inputs (set to 0 dB after RESET).

Output Channels

- 1. Select the source channel and matrix for each output channel.
- 2. Set audio baseband features (i.e. AVC, 75 μs preemphasis)
- 3. Select volume for each output channel.

3.5. Examples of Minimum Initialization Codes

Initialization of the MSP 44x8G according to these listings reproduces sound of the selected standard on the main output. All numbers are hexadecimal. The examples have the following structure:

- 1. Perform an I²C controlled reset of the IC.
- 2. Write MODUS register (with Automatic Sound Select).
- 3. Set Source Selection for main channel (with matrix set to STEREO).
- 4. Set Prescale (FM and/or NICAM and dummy FM matrix).
- 5. Write STANDARD SELECT register.
- 6. Set Volume main channel to 0 dB.

3.5.1. B/G-FM (A2 or NICAM)

```
<80 00 80 00>  // Softreset
<80 00 00 00>  // MODUS-Register: Automatic = on
<80 10 00 30 20 03>  // MODUS-Register: Automatic = on
<80 12 00 08 03 20>  // Source Sel. = (St or A) & Ch. Matr. = St
<80 12 00 0E 24 03>  // FM/AM-Prescale = 24<sub>hex</sub>, FM-Matrix = MONO/SOUNDA
<80 12 00 10 5A 00>  // NICAM-Prescale = 5A<sub>hex</sub>
<80 10 00 20 00 03>  // Standard Select: A2 B/G or NICAM B/G or
<80 10 00 20 00 08>
<80 12 00 00 73 00>  // Main Volume 0 dB
```

3.5.2. BTSC-Stereo

```
<80 00 80 00> // Softreset
<80 00 00 00> // MODUS-Register: Automatic = on
<80 10 00 30 20 03> // MODUS-Register: Automatic = on
<80 12 00 08 03 20> // Source Sel. = (St or A) & Ch. Matr. = St
<80 12 00 0E 24 03> // FM/AM-Prescale = 24<sub>hex</sub>, FM-Matrix = Sound A Mono
<80 10 00 20 00 20> // Standard Select: BTSC-STEREO
<80 12 00 00 73 00> // Main Volume 0 dB
```

3.5.3. BTSC-SAP with SAP at Main Channel

```
<80 00 80 00>  // Softreset
<80 00 00 00>  // MODUS-Register: Automatic = on
<80 10 00 30 20 03>  // MODUS-Register: Automatic = on
<80 12 00 08 04 20>  // Source Sel. = (St or B) & Ch. Matr. = St
<80 12 00 0E 24 03>  // FM/AM-Prescale = 24<sub>hex</sub>, FM-Matrix = Sound A Mono
<80 10 00 20 00 21>  // Standard Select: BTSC-SAP
<80 12 00 00 73 00>  // Main Volume 0 dB
```

3.5.4. FM-Stereo Radio

```
<80 00 80 00> // Softreset
<80 00 00 00>
<80 10 00 30 20 03> // MODUS-Register: Automatic = on
<80 12 00 08 03 20> // Source Sel. = (St or A) & Ch. Matr. = St
<80 12 00 0E 24 03> // FM/AM-Prescale = 24<sub>hex</sub>, FM-Matrix = Sound A Mono
<80 10 00 20 00 40> // Standard Select: FM-STEREO-RADIO
<80 12 00 00 73 00> // Main Volume 0 dB
```

3.5.5. Automatic Standard Detection

A detailed software flow diagram is shown in Fig. 3–2 on page 39.

```
<80 00 80 00>  // Softreset
<80 00 00 00>  // MODUS-Register: Automatic = on
<80 10 00 30 20 03>  // MODUS-Register: Automatic = on
<80 12 00 08 03 20>  // Source Sel. = (St or A) & Ch. Matr. = St
<80 12 00 0E 24 03>  // FM/AM-Prescale = 24hex, FM-Matrix = Sound A Mono
<80 12 00 10 5A 00>  // NICAM-Prescale = 5Ahex
<80 10 00 20 00 01>  // Standard Select: Automatic Standard Detection
// Wait till STANDARD RESULT contains a value ≤ 07FF
// IF STANDARD RESULT contains 0000
// do some error handling
// ELSE
<80 12 00 00 73 00>  // Main Volume 0 dB
```

3.5.6. Software Flow for Interrupt driven STATUS Check

A detailed software flow diagram is shown in Fig. 3–2 on page 39.

If the D_CTR_I/O_1 pin of the MSP 44x8G is connected to an interrupt input pin of the controller, the following interrupt handler can be applied to be automatically called with each status change of the MSP 44x8G. The interrupt handler may adjust the display according to the new status information.

```
Interrupt Handler:
```

```
<80 11 02 00 <81 dd dd> // Read STATUS
// adjust display with given status information
// Return from Interrupt
```

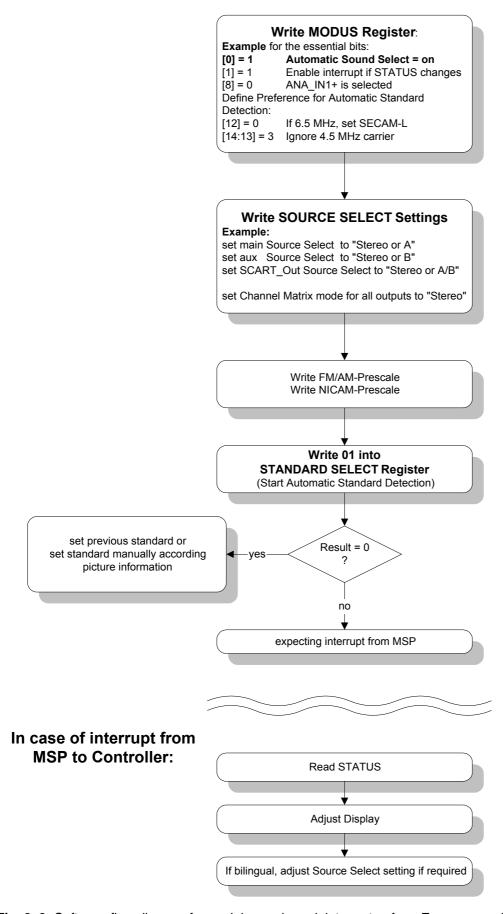


Fig. 3–2: Software flow diagram for a minimum demodulator setup for a European multistandard set applying the Automatic Sound Select feature

4. Specifications

4.1. Outline Dimensions

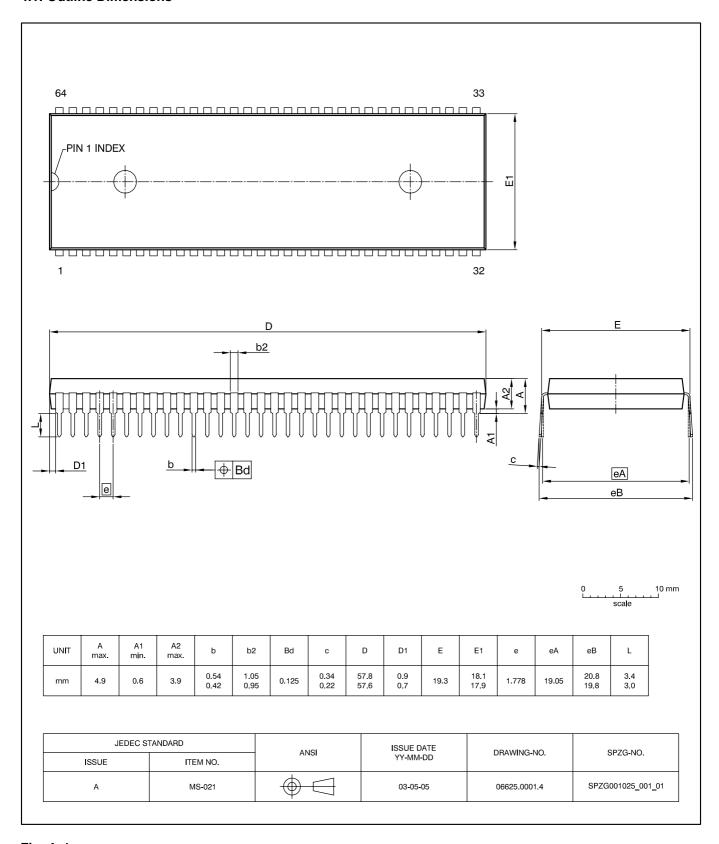


Fig. 4–1:

PSDIP64-1: Plastic Shrink Dual In-line Package, 64 leads, 750 mil

Ordering code: PP

Weight approximately 8.77 g

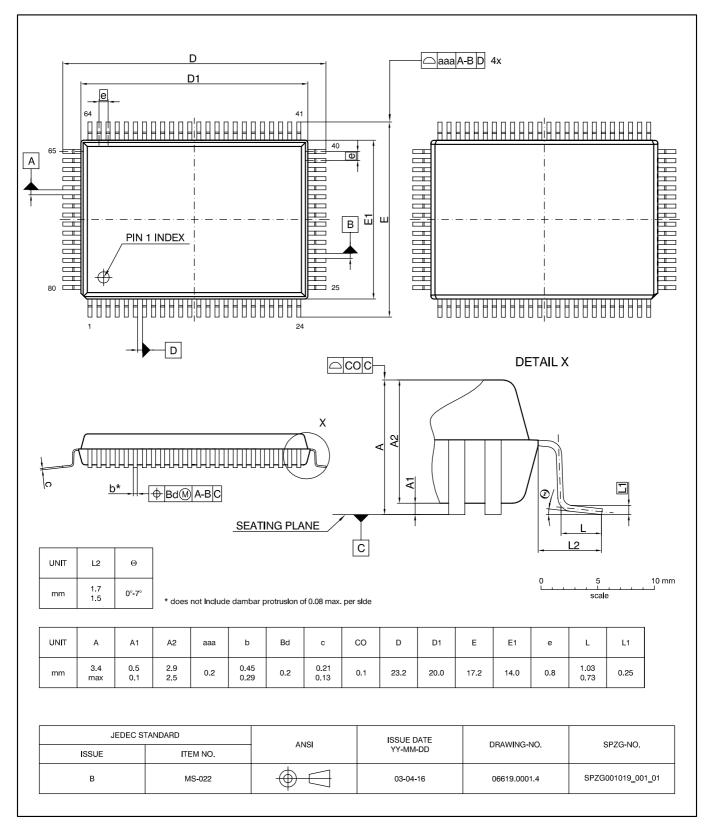


Fig. 4–2: PMQFP80-11: Plastic Metric Quad Flat Package, 80 leads, $14 \times 20 \times 2.7 \text{ mm}^3$, high standoff Ordering code: QA

Weight approximately 1.68 g

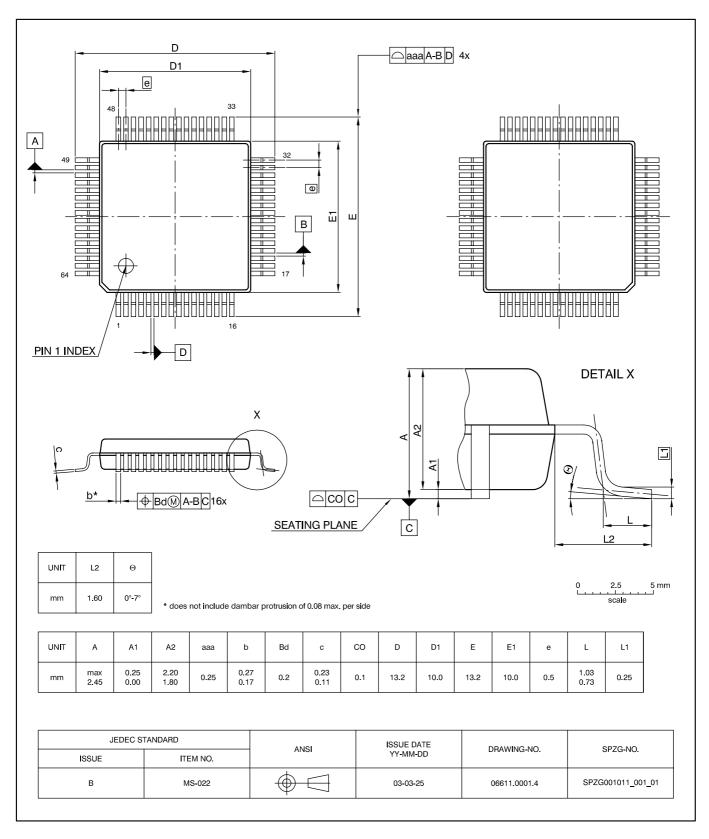


Fig. 4–3: PMQFP64-2: Plastic Metric Quad Flat Package, 64 leads, $10 \times 10 \times 2 \text{ mm}^3$ Ordering code: QI Weight approximately 0.5 g

4.2. Pin Connections and Short Descriptions

NC = not connected; leave vacant LV = if not used, leave vacant

OBL = obligatory; connect as described in circuit diagram DVSS: if not used, connect to DVSS AHVSS: connect to AHVSS

	Pin No.		Pin Name	Туре	Connection	Short Description
PMQFP 80-11	PMQFP 64-2	PSDIP 64-1			(if not used)	·
1	64	8	NC		LV	Not connected
2	1	9	I2C_CL	IN/OUT	OBL	I ² C clock
3	2	10	I2C_DA	IN/OUT	OBL	I ² C data
4	3	11	I2S_CL	IN/OUT	LV	I ² S clock
5	4	12	I2S_WS	IN/OUT	LV	I ² S word strobe
6	5	13	I2S_DA_OUT	OUT	LV	I ² S data output
7	6	14	I2S_DA_IN1	IN	LV	I ² S1 data input
8	7	15	I2S_DA_OUT4	OUT	LV	Asynchronous I ² S4 data output
9	8	16	I2S_WS4	IN/OUT	LV	Asynchronous I ² S4 word strobe input/output
10	9	17	I2S_CL4	IN/OUT	LV	Asynchronous I ² S4 clock input/output
11	_	_	DVSUP		OBL	Digital power supply +5 V
12	-	_	DVSUP		OBL	Digital power supply +5 V
13	10	18	DVSUP		OBL	Digital power supply +5 V
14	1	-	DVSS		OBL	Digital ground
15	1	_	DVSS		OBL	Digital ground
16	11	19	DVSS		OBL	Digital ground
_	12	20	I2S_DA_IN2/3	IN	LV	I ² S2/3-data input
17	1	-	I2S_DA_IN2	IN	LV	PMQFP80-11: pin 22 separate I2S_DA_IN3
18	13	21	NC		LV	Not connected
19	14	22	12S_CL3	IN	LV	l ² S3 clock
20	15	23	12S_WS3	IN	LV	I ² S3 word strobe
21	16	24	RESETQ	IN	OBL	Power-on-reset
22	-	-	I2S_DA_IN3	IN	LV	I ² S3 data input
23	_	_	NC		LV	Not connected
24	17	25	DACA_R	OUT	LV	Aux out, right

PMQFP 80-11	Pin No. PMQFP 64-2	PSDIP 64-1	Pin Name	Туре	Connection (if not used)	Short Description
25	18	26	DACA_L	OUT	LV	Aux out, left
26	19	27	VREF2		OBL	Reference ground 2
27	20	28	DACM_R	OUT	LV	Main out, right
28	21	29	DACM_L	OUT	LV	Main out, left
29	22	30	NC		LV	Not connected
30	23	31	NC		LV	Not connected
31	24	32	NC		LV	Not connected
32	-	-	NC		LV	Not connected
33	25	33	SC2_OUT_R	OUT	LV	SCART output 2, right
34	26	34	SC2_OUT_L	OUT	LV	SCART output 2, left
35	27	35	VREF1		OBL	Reference ground 1
36	28	36	SC1_OUT_R	OUT	LV	SCART output 1, right
37	29	37	SC1_OUT_L	OUT	LV	SCART output 1, left
38	30	38	CAPL_A		OBL	Volume capacitor Aux
39	31	39	AHVSUP		OBL	Analog power supply 8.0 V
40	32	40	CAPL_M		OBL	Volume capacitor Main
41	-	_	NC		LV	Not connected
42	-	_	NC		LV	Not connected
43	-	-	AHVSS		OBL	Analog ground
44	33	41	AHVSS		OBL	Analog ground
45	34	42	AGNDC		OBL	Analog reference voltage
46	-	-	NC		LV	Not connected
47	35	43	SC4_IN_L	IN	LV	SCART 4 input, left
48	36	44	SC4_IN_R	IN	LV	SCART 4 input, right
49	37	45	ASG		AHVSS	Analog Shield Ground
50	38	46	SC3_IN_L	IN	LV	SCART 3 input, left
51	39	47	SC3_IN_R	IN	LV	SCART 3 input, right
52	40	48	ASG		AHVSS	Analog Shield Ground
53	41	49	SC2_IN_L	IN	LV	SCART 2 input, left
54	42	50	SC2_IN_R	IN	LV	SCART 2 input, right
55	43	51	ASG		AHVSS	Analog Shield Ground

PMQFP	Pin No.	PSDIP	Pin Name	Туре	Connection (if not used)	Short Description
80-11	64-2	64-1				
56	44	52	SC1_IN_L	IN	LV	SCART 1 input, left
57	45	53	SC1_IN_R	IN	LV	SCART 1 input, right
58	46	54	VREFTOP		OBL	Reference voltage IF A/D converter
59	_	_	NC		LV	Not connected
60	47	55	MONO_IN	IN	LV	Mono input
61	_	_	AVSS		OBL	Analog ground
62	48	56	AVSS		OBL	Analog ground
63	-	_	NC		LV	Not connected
64	-	_	NC		LV	Not connected
65	_	_	AVSUP		OBL	Analog power supply +5 V
66	49	57	AVSUP		OBL	Analog power supply +5 V
67	50	58	ANA_IN1+	IN	LV	IF input 1
68	51	59	ANA_IN-	IN	AVSS via 56 pF / LV	IF common (Can be left vacant, only if IF input 1 is also not in use)
69	52	60	ANA_IN2+	IN	AVSS via 56 pF / LV	IF input 2 (Can be left vacant, only if IF input 1 is also not in use)
70	53	61	TESTEN	IN	AVSS	Test pin
71	54	62	XTAL_IN	IN	OBL	Crystal oscillator
72	55	63	XTAL_OUT	OUT	OBL / LV	Crystal oscillator (See also Section 4.3. "Pin Descriptions" on page 46)
73	56	64	TP		LV	Test pin
74	57	1	AUD_CL_OUT	OUT	LV	Audio clock output (18.432 MHz)
75	58	2	NC		LV	Not connected
76	59	3	NC		LV	Not connected
77	60	4	D_CTR_I/O_1	IN/OUT	LV	D_CTR_I/O_1
78	61	5	D_CTR_I/O_0	IN/OUT	LV	D_CTR_I/O_0; A/V Sync In
79	62	6	ADR_SEL	IN	OBL	I ² C Bus address select
80	63	7	STANDBYQ	IN	OBL	Stand-by (low-active)

4.3. Pin Descriptions

Pin numbers refer to the PMQFP80-11 package.

Pin 1, NC - Pin not connected.

Pin 2, $I2C_CL - I^2C$ Clock Input/Output (Fig. 4–14) Via this pin, the I^2C -bus clock signal has to be supplied. The signal can be pulled down by the MSP in case of wait conditions.

Pin 3, **I2C_DA** – I²C Data Input/Output (Fig. 4–14) Via this pin, the I²C-bus data is written to or read from the MSP.

Pin 4, **I2S_CL** – I²S Clock Input/Output (Fig. 4–15) Clock line for the synchronous I²S bus. In master mode, this line is driven by the MSP; in slave mode, an external I²S clock has to be supplied.

Pin 5, **I2S_WS** – I²S Word Strobe Input/Output (Fig. 4–15)

Word strobe line for the synchronous I²S bus. In master mode, this line is driven by the MSP; in slave mode, an external I²S word strobe has to be supplied.

Pin 6, **I2S_DA_OUT1** – I²S Data Output (Fig. 4–19) Output of digital serial sound data of the MSP on the synchronous I²S bus.

Pin 7, $I2S_DA_IN1 - I^2S$ Data Input 1 (Fig. 4–11) First input of digital serial sound data to the MSP via the synchronous I^2S bus.

Pin 8, **I2S_DA_OUT4** – Async I2S Data Output (Fig. 4–19)

Output of digital serial sound data from the MSP via the asynchronous I²S4 bus.

Pin 9, **I2S_WS4** – Async I2S Bus Word Strobe Input / Output

(Fig. 4-19)

Word strobe line for the asynchronous I²S4 bus. In master mode, this line is driven by the MSP; in slave mode, an external I²S word strobe has to be supplied.

Pin 10, **I2S_CL4** – Async I2S Bus Clock Input / Output (Fig. 4–19)

Clock line for the asynchronous I²S4 bus. In master mode, this line is driven by the MSP; in slave mode, an external I²S clock has to be supplied.

Pins 11, 12, 13, **DVSUP*** – Digital Supply Voltage Power supply for the digital circuitry of the MSP. Must be connected to a +5 V (or +3.3 V only available on request) power supply.

Pins 14, 15, 16, **DVSS*** – Digital Ground Ground connection for the digital circuitry of the MSP.

Pin 17, $I2S_DA_IN2 - I^2S$ Data Input 2 (Fig. 4–11) Second input of digital serial sound data to the MSP via the synchronous I^2S bus. In all packages except PMQFP80-11, this pin is also connected to the asynchronous I^2S interface 3.

Pins 18, NC - Pin not connected.

Pins 19, $I2S_CL3 - I^2S$ Clock Input (Fig. 4–11) Clock line for the asynchronous I^2S bus. Since only a slave mode is available an external I^2S clock has to be supplied.

Pins 20, **I2S_WS3** – I²S Word Strobe Input (Fig. 4–11) Word strobe line for the asynchronous I²S bus. Since only a slave mode is available an external I²S word strobe has to be supplied.

Pin 21, **RESETQ** – Reset Input (Fig. 4–7) In the steady state, high level is required. A low level resets the MSP 44x8G.

Pin 22, **I2S_DA_IN3** – I²S Data Input 3 (Fig. 4–11) Input of digital serial sound data to the MSP via the asynchronous I²S bus. In all packages except PMQFP80-11, this pin is also connected to synchronous I²S interface 2.

Pins 23, **NC** – Pin not connected.

Pins 24, 25, **DACA_R/L** – Aux Outputs (Fig. 4–17) Output of the Aux signal. A 1 nF capacitor to AHVSS must be connected to these pins. The DC offset on these pins depends on the selected Aux volume.

Pin 26. VREF2 - Reference Ground 2

Reference analog ground. This pin must be connected separately to the ground (AHVSS). VREF2 serves as a clean ground and should be used as the reference for analog connections to the Main and Aux outputs.

Pins 27, 28, **DACM_R/L** – Main Outputs (Fig. 4–17)

Output of the Main signal. A 1 nF capacitor to AHVSS must be connected to these pins. The DC offset on these pins depends on the selected Main volume.

Pin 29, 30, 31, 32 **NC** – Pin not connected.

Pins 33, 34, **SC2_OUT_R/L** – SCART2 Outputs (Fig. 4–18)

Output of the SCART2 signal. Connections to these pins must use a 100- Ω series resistor and are intended to be AC-coupled.

Pin 35, VREF1 - Reference Ground 1

Reference analog ground. This pin must be connected separately to the ground (AHVSS). VREF1 serves as a clean ground and should be used as the reference for analog connections to the SCART outputs.

Pins 36, 37, **SC1_OUT_R/L** – SCART1 Outputs (Fig. 4–18)

Output of the SCART1 signal. Connections to these pins must use a 100- Ω series resistor and are intended to be AC-coupled.

Pin 38, **CAPLA** – Volume Capacitor Aux (Fig. 4–20) A 10- μ F capacitor to AHVSUP must be connected to this pin. It serves as a smoothing filter for Aux volume changes in order to suppress audible plops. The value of the capacitor can be lowered to 1- μ F if faster response is required. The area encircled by the trace lines should be minimized; keep traces as short as possible. This input is sensitive for magnetic induction.

Pin 39, **AHVSUP*** – Analog Power Supply High Voltage

Power is supplied via this pin for the analog circuitry of the MSP (except IF input). This pin must be connected to the +8 V supply. (+5 V-operation is possible with restrictions in performance)

Pin 40, **CAPLM** – Volume Capacitor Main (Fig. 4–20) A 10- μ F capacitor to AHVSUP must be connected to this pin. It serves as a smoothing filter for Main volume changes in order to suppress audible plops. The value of the capacitor can be lowered to 1 μ F if faster response is required. The area encircled by the trace lines should be minimized; keep traces as short as possible. This input is sensitive for magnetic induction.

Pins 41, 42, NC - Pins not connected.

Pins 43, 44, **AHVSS*** – Analog Power Supply High Voltage

Ground connection for the analog circuitry of the MSP (except IF input).

Pin 45, **AGNDC** – Internal Analog Reference Voltage This pin serves as the internal ground connection for the analog circuitry (except IF input). It must be connected to the VREF pins with a 3.3- μ F and a 100-nF capacitor in parallel. This pins shows a DC level of typically 3.73 V (with AHVSUP = 8 V).

Pin 46, NC - Pin not connected.

Pins 47, 48, **SC4_IN_L/R** – SCART4 Inputs (Fig. 4–10)

The analog input signal for SCART4 is fed to this pin. Analog input connection must be AC-coupled.

Pins 49, 52, and 55, **ASG*** – Analog Shield Ground Analog ground (AHVSS) should be connected to this pin to reduce cross-coupling between SCART inputs.

Pins 50, 51, **SC3_IN_L/R** – SCART3 Inputs (Fig. 4–10)

The analog input signal for SCART3 is fed to this pin. Analog input connection must be AC-coupled.

Pins 53, 54 **SC2_IN_L/R** – SCART2 Inputs (Fig. 4–10) The analog input signal for SCART2 is fed to this pin. Analog input connection must be AC-coupled.

Pins 56, 57 **SC1_IN_L/R** – SCART1 Inputs (Fig. 4–10) The analog input signal for SCART1 is fed to this pin. Analog input connection must be AC-coupled.

Pin 58, **VREFTOP** – Reference Voltage IF A/D Converter (Fig. 4–12)

Via this pin, the reference voltage for the IF A/D converter is decoupled. It must be connected to AVSS pins with a 10- μ F and a 100-nF capacitor in parallel. Traces must be kept short.

Pin 59, NC - Pin not connected.

Pin 60 MONO_IN – Mono Input (Fig. 4–10)

The analog mono input signal is fed to this pin. Analog input connection must be AC-coupled.

Pins 61, 62, **AVSS*** – Analog Power Supply Voltage Ground connection for the analog IF input circuitry of the MSP.

Pins 63, 64, **NC** – Pins not connected.

Pins 65, 66, **AVSUP*** – Analog Power Supply Voltage Power is supplied via this pin for the analog IF input circuitry of the MSP. This pin must be connected to the +5 V supply.

Pin 67, **ANA IN1**+ – IF Input 1 (Fig. 4–12)

The analog sound IF signal is supplied to this pin. Inputs must be AC-coupled. This pin is designed as symmetrical input: ANA_IN1+ is internally connected to one input of a symmetrical op amp, ANA_IN- to the other.

Pin 68, **ANA_IN**- – IF Common (Fig. 4–12)

This pins serves as a common reference for ANA_IN1/2+ inputs and must be AC-coupled.

Pin 69, **ANA_IN2**+ – IF Input 2 (Fig. 4–12)

The analog sound if signal is supplied to this pin. Inputs must be AC-coupled. This pin is designed as symmetrical input: ANA_IN2+ is internally connected to one input of a symmetrical op amp, ANA_IN- to the other.

Pin 70, **TESTEN** – Test Enable Pin (Fig. 4–8)

This pin enables factory test modes. For normal operation, it must be connected to ground.

Pins 71, 72 **XTAL_IN, XTAL_OUT** – Crystal Input and Output Pins (Fig. 4–16)

These pins are connected to an 18.432 MHz crystal oscillator which is digitally tuned by integrated capacitances. An external clock can be fed into XTAL_IN (leave XTAL_OUT vacant in this case). The audio clock output signal AUD_CL_OUT is derived from the oscillator. External capacitors at each crystal pin to ground (AVSS) are required. It should be verified by layout, that no supply current for the digital circuitry is flowing through the ground connection point.

Pin 73, **TP** – This pin enables factory test modes. For normal operation, it must be left vacant.

Pin 74, **AUD_CL_OUT** – Audio Clock Output (Fig. 4–16)

This is the 18.432 MHz main clock output.

Pins 75, 76, NC - Pins not connected.

Pins 77, 78, **D_CTR_I/O_1/0** – Digital Control Input/ Output Pins (Fig. 4–15)

These pins serve as general purpose input/output pins. Pin D_CTR_I/O_1 can be used as an interrupt request pin to the controller. D_CTR_I/O_0 can be used as input pin for Audio/Video synchronization.

Pin 79, **ADR_SEL** – I²C Bus Address Select (Fig. 4–13)

By means of this pin, one of three device addresses for the MSP can be selected. The pin can be connected to ground (12 C device addresses $80/81_{hex}$), to +5 V supply ($84/85_{hex}$), or left open ($88/89_{hex}$).

Pin 80, STANDBYQ - Stand-by

In normal operation, this pin must be High. If the MSP is switched off by first pulling STANDBYQ low and then (after >1 μs delay) switching off the 5 V, but keeping the 8-V power supply ('Stand-by'-mode), the SCART switches maintain their position and function.

Pin -, I2S_DA_IN2/3 -I²S data input (see Fig. 4-11). This pin is connected to I2S_DA_IN2 and I2S_DA_IN3. Not available for PMQFP80-11 package.

* Application Note:

All ground pins should be connected to one low-resistive ground plane.

All supply pins should be connected separately with short and low-resistive lines to the power supply.

Decoupling capacitors from DVSUP to DVSS, AVSUP to AVSS, and AHVSUP to AHVSS are recommended as closely as possible to these pins. Decoupling of DVSUP and DVSS is most important. We recommend using more than one capacitor. By choosing different values, the frequency range of active decoupling can be extended. In our application boards we use: 220 pF, 470 pF, 1.5 nF, and 10 μF . The capacitor with the lowest value should be placed nearest to the pins.

The ASG pins should be connected as closely as possible to the MSP ground. They are intended for leading with the SCART signals as shield lines and should <u>not</u> be connected to ground at the SCART-connector.

4.4. Pin Configurations

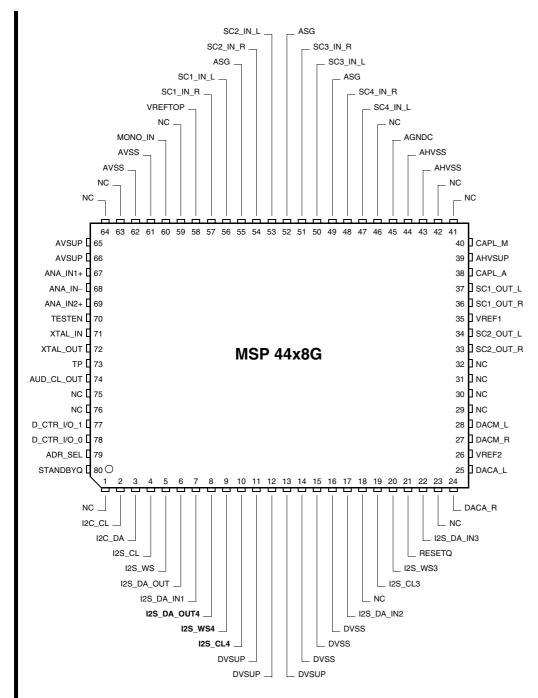


Fig. 4-4: PMQFP80-11 package

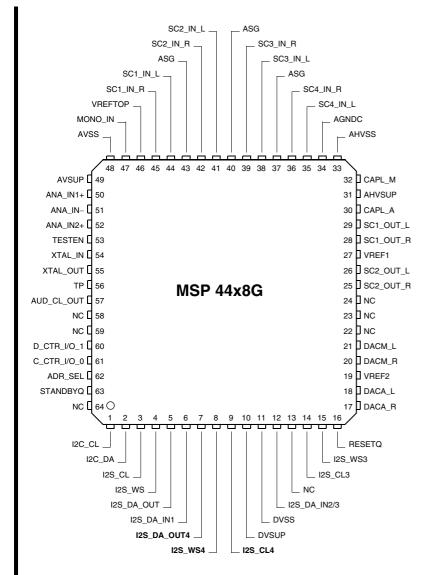


Fig. 4-5: PMQFP64-2 package

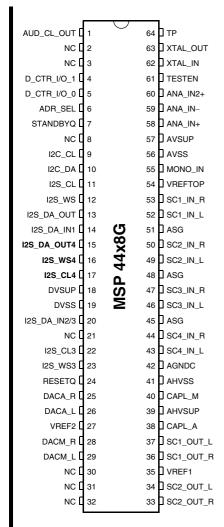


Fig. 4-6: PSDIP64-1 package

4.5. Pin Circuits

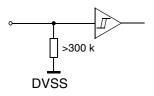


Fig. 4-7: Input Pin: RESETQ

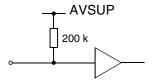


Fig. 4-8: Input Pin: TESTEN

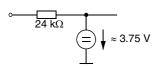


Fig. 4-9: Input Pin: MONO_IN

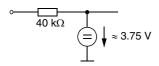


Fig. 4-10: Input Pins: SC4-1_IN_L/R

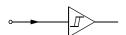


Fig. 4-11: Input Pins:

I2S_DA_IN1..3, I2S_CL3, I2S_WS3, STANDBYQ

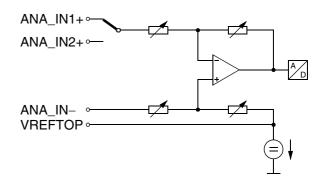


Fig. 4–12: Input Pins: VREFTOP, ANA_IN1+, ANA_IN-, ANA_IN2+

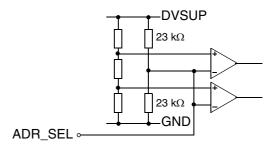


Fig. 4-13: Input Pin: ADR_SEL

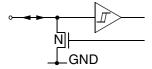


Fig. 4-14: Input/Output Pins: I2C_CL, I2C_DA

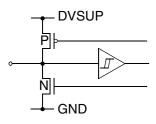


Fig. 4–15: Input/Output Pins: I2S_CL, I2S_WS, D_CTR_I/O_1, D_CTR_I/O_0, I2S_CL4, I2S_WS4

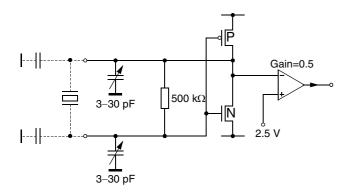


Fig. 4–16: Input/Output Pins: XTAL_IN, XTAL_OUT, AUD_CL_OUT

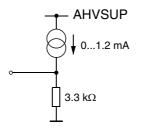


Fig. 4-17: Output Pins: DACA_R/L, DACM_R/L

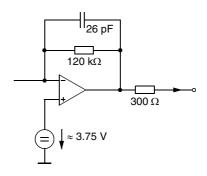


Fig. 4–18: Output Pins: SC_2_OUT_R/L, SC_1_OUT_R/L

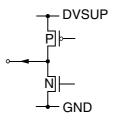


Fig. 4-19: Output Pins: I2S_DA_OUT, I2S_DA_OUT4

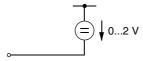


Fig. 4-20: Capacitor Pins: CAPL_A, CAPL_M

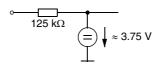


Fig. 4-21: Pin: AGNDC

4.6. Electrical Characteristics

Abbreviations:

tbd = to be defined vacant = not applicable positive current values mean current flowing into the chip

4.6.1. Absolute Maximum Ratings

Stresses beyond those listed in the "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only. Functional operation of the device at these conditions is not implied. Exposure to absolute maximum rating conditions for extended periods will affect device reliability.

This device contains circuitry to protect the inputs and outputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than absolute maximum-rated voltages to this high-impedance circuit.

All voltages listed are referenced to ground (0 V, V_{SS}) except where noted.

All GND pins must be connected to a low-resistive ground plane close to the IC.

Table 4-1: Absolute Maximum Ratings

Symbol	Parameter	Pin Name	Limit \	Values	Unit
			Min.	Max.	
T _A ¹⁾	Ambient Operating Temperature PSDIP64-1 PMQFP80-11 PMQFP64-2	_	0	70 70 65	°C
T _C	Case Operating Temperature PSDIP64-1 PMQFP80-11 PMQFP64-2	-	0	85 95 100	°C
T _S	Storage Temperature	_	-40	125	°C
P _{MAX}	Maximum Power Dissipation PSDIP64-1 PMQFP80-11 PMQFP64-2			1540 980 1000	mW mW mW
V _{SUP1}	Supply Voltage 1	AHVSUP	-0.3	9.0	V
V _{SUP2}	Supply Voltage 2	DVSUP	-0.3	6.0	٧
V _{SUP3}	Supply Voltage 3	AVSUP	-0.3	6.0	V
V _{Idig}	Input Voltage, all Digital Inputs		-0.3	V _{SUP2} +0.3	V
I _{Idig}	Input Current, all Digital Pins	_	-20	+20	mA

Measured on standard board according to JESD 51 Standard with maximum power consumption allowed for this package.

Table 4-1: Absolute Maximum Ratings, continued

Symbol	Parameter	Pin Name	Limit Values		Unit
			Min.	Max.	
V _{lana}	Input Voltage, all Analog Inputs	SCn_IN_s, ¹⁾ MONO_IN	-0.3	V _{SUP1} +0.3	V
I _{lana}	Input Current, all Analog Inputs	SCn_IN_s, ¹⁾ MONO_IN	- 5	+5	mA
I _{Oana}	Output Current, all SCART Outputs	SCn_OUT_s ¹⁾	2)	2)	
I _{Oana}	Output Current, all Analog Outputs except SCART Outputs	DACp_s ¹⁾	2)	2)	
I _{Cana}	Output Current, other pins connected to capacitors	CAPL_p, ¹⁾ AGNDC	2)	2)	

^{1) &}quot;n" means "1", "2", "3", or "4", "s" means "L" or "R", "p" means "M" or "A"
2) The analog outputs are short-circuit proof with respect to Supply Voltage 1 and ground.

4.6.2. Recommended Operating Conditions

Functional operation of the device beyond those indicated in the "Recommended Operating Conditions/Characteristics" is not implied and may result in unpredictable behavior, reduce reliability and lifetime of the device.

All voltages listed are referenced to ground ($V_{SS} = 0 \text{ V}$) except where noted.

All GND pins must be connected to a low-resistive ground plane close to the IC.

Do not insert the device into a live socket. Instead, apply power by switching on the external power supply. For power-up/-down sequences, see the instructions in Section 4.6.3.3. of this document.

4.6.2.1. General Recommended Operating Conditions

Symbol	Parameter	Pin Name	Li	imit Value	es	Unit
			Min.	Тур.	Max.	
T _A	Ambient Operating Temperature PSDIP64-1 PMQFP80-11 PMQFP64-2	_			1) 70 70 65	°C
T _C	Case Operating Temperature PSDIP64-1 PMQFP80-11 PMQFP64-2	_			85 95 100	Ô
V _{SUP1}	Supply Voltage 1 (AHVSUP = 8 V)	AHVSUP	7.6	8.0	8.7	V
	Supply Voltage 1 (AHVSUP = 5 V)		4.75	5.0	5.25	V
V _{SUP2}	Supply Voltage 2 (DVSUP = 5 V)	DVSUP	4.75	5.0	5.25	V
	Supply Voltage 2 (DVSUP = 3.3 V) ²⁾		3.15 ²⁾	3.3 ²⁾	3.45 ²⁾	V
V _{SUP3}	Supply Voltage 3	AVSUP	4.75	5.0	5.25	V
t _{STBYQ1}	STANDBYQ Setup Time before Turn-off of Second Supply Voltage	STANDBYQ, DVSUP	1			μS

¹⁾ A power-optimized board layout is recommended. The Case Operating Temperatures mentioned in the Recommended Operating Conditions must not be exceeded at worst case conditions of the application.

²⁾ only available on request

4.6.2.2. Analog Input and Output Recommendations

Symbol	Parameter	Pin Name	Limit Values		es	Unit
			Min.	Тур.	Max.	
C _{AGNDC}	AGNDC-Filter-Capacitor	AGNDC	-20%	3.3		μF
	Ceramic Capacitor in Parallel		-20%	100		nF
C _{inSC}	DC-Decoupling Capacitor in front of SCART Inputs	SCn_IN_s ¹⁾	-20%	330		nF
V _{inSC}	SCART Input Level				2.0	V _{RMS}
V_{inMONO}	Input Level, Mono Input	MONO_IN			2.0	V_{RMS}
R _{LSC}	SCART Load Resistance	SCn_OUT_s ¹⁾	10			kΩ
C _{LSC}	SCART Load Capacitance				6.0	nF
C _{VMA}	Main/Aux Volume Capacitor	CAPL_p		10		μF
C _{FMA}	Main/Aux Filter Capacitor	DACp_s ¹⁾	-10%	1	+10%	nF
1) "n" means "	f1", "2", "3", or "4", "s" means "L" or "R",	"p" means "M" or "A	,,			

4.6.2.3. Recommendations for Analog Sound IF Input Signal

Symbol	Parameter	Pin Name	Li	imit Value	es	Unit
			Min.	Тур.	Max.	
C _{VREFTOP}	VREFTOP-Filter-Capacitor	VREFTOP	-20%	10		μF
	Ceramic Capacitor in Parallel		-20%	100		nF
F _{IF_FMTV}	Analog Input Frequency Range for TV Applications	ANA_IN1+, ANA_IN2+,	0		9	MHz
F _{IF_FMRADIO}	Analog Input Frequency for FM-Radio Applications	ANA_IN-		10.7		MHz
V _{IF_FM}	Analog Input Range FM/NICAM		0.1	0.8	3	V _{pp}
V _{IF_AM}	Analog Input Range AM/NICAM		0.1	0.45	0.8	V _{pp}
R _{FMNI}	Ratio: NICAM Carrier/FM Carrier (unmodulated carriers) BG: I:		-20 -23	-7 -10	0 0	dB dB
R _{AMNI}	Ratio: NICAM Carrier/AM Carrier (unmodulated carriers)		-25	-11	0	dB
R _{FM}	Ratio: FM-Main/FM-Sub Satellite			7		dB
R _{FM1/FM2}	Ratio: FM1/FM2 German FM-System			7		dB
R _{FC}	Ratio: Main FM Carrier/ Color Carrier		15	-	_	dB
R _{FV}	Ratio: Main FM Carrier/ Luma Components		15	-	_	dB
PR _{IF}	Passband Ripple		-	_	±2	dB
SUP _{HF}	Suppression of Spectrum above 9.0 MHz (not for FM Radio)		15			dB
FM _{MAX}	Maximum FM-Deviation (approx.) normal mode HDEV2: high deviation mode HDEV3: very high deviation mode				±180 ±360 ±540	kHz kHz kHz

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4.6.2.4. Crystal Recommendations

Symbol	Parameter	Pin Name	L	imit Value	es	Unit
			Min.	Тур.	Max.	
General Cr	ystal Recommendations					
f _P	Crystal Parallel Resonance Frequency at 12 pF Load Capacitance			18.432		MHz
R _R	Crystal Series Resistance			8	25	Ω
C ₀	Crystal Shunt (Parallel) Capacitance			6.2	7.0	pF
C _L	External Load Capacitance ¹⁾	XTAL_IN, XTAL_OUT	PSDIP PMQFP	approx.		pF pF
Crystal Rec	commendations for Master-Slave Appli	cations (MSP-clock n	nust perfor	m synchroi	nization to	² S clock)
f _{TOL}	Accuracy of Adjustment		-20		+20	ppm
D _{TEM}	Frequency Variation versus Temperature		-20		+20	ppm
C ₁	Motional (Dynamic) Capacitance		19	24		fF
f _{CL}	Required Open Loop Clock Frequency (T _{amb} = 25 °C)	AUD_CL_OUT	18.431		18.433	MHz
Crystal Rec	commendations for FM / NICAM Applic	ations (No MSP-clock	synchroni	zation to I ²	S clock po	ssible)
f _{TOL}	Accuracy of Adjustment		-30		+30	ppm
D _{TEM}	Frequency Variation versus Temperature		-30		+30	ppm
C ₁	Motional (Dynamic) Capacitance		15			fF
f_{CL}	Required Open Loop Clock Frequency (T _{amb} = 25 °C)	AUD_CL_OUT	18.4305		18.4335	MHz
Crystal Rec	commendations for all analog FM/AM A	Applications (No MSF	P-clock syn	chronizatio	n to I ² S clo	ck possible)
f _{TOL}	Accuracy of Adjustment		-100		+100	ppm
D _{TEM}	Frequency Variation versus Temperature		-50		+50	ppm
f _{CL}	Required Open Loop Clock Frequency (T _{amb} = 25 °C)	AUD_CL_OUT	18.429		18.435	MHz
Amplitude	Recommendation for Operation with E	xternal Clock Input	(C _{load} afte	er reset ty	p. 22 pF)	
V _{XCA}	External Clock Amplitude	XTAL_IN	0.7			V _{pp}

¹⁾ External capacitors at each crystal pin to ground are required. They are necessary to tune the open-loop frequency of the internal PLL and to stabilize the frequency in closed-loop operation. Due to different layouts, the accurate capacitor value should be determined with the customer PCB. The suggested values (1.5...3.3 pF) are figures based on experience and should serve as "start value".

To adjust the capacitor value, reset the MSP. After the reset, no I^2C telegrams should be transmitted. Measure the frequency at AUD_CL_OUT-pin. Change the capacitor value until the free running frequency matches 18.432 MHz as closely as possible. The higher the capacity, the lower the resulting clock frequency.

Note: To minimize adjustment tolerances for all MSP-generations, it is strongly recommended to use the so-called MSP-XTAL-REF ICs (available in all packages) for the capacitor adjustment.

4.6.3. Characteristics

For Min./Max. values:

at T_A = 0 to 70 °C, f_{CLOCK} = 18.432 MHz $V_{SUP1} = 7.6 \text{ to } 8.7 \text{ V } (4.75 \text{ to } 5.25 \text{ V if } V_{SUP1} = 5 \text{ V}) \\ V_{SUP2} = 4.75 \text{ to } 5.25 \text{ V } (3.15 \text{ to } 3.45 \text{ V if } V_{SUP2} = 3.3 \text{ V , only available on request)} \\ V_{SUP3} = 4.75 \text{ to } 5.2 \text{ V}$

For typical values:

at T_A = 60 °C, f_{CLOCK} = 18.432 MHz V_{SUP1} = 8 V (5 V if noted) V_{SUP2} = 5 V (3.3 V if noted, only available on request) V_{SUP3} = 5 V

 $T_J = Junction Temperature$

MAIN (M) = Main Channel, AUX (A) = Aux Channel

4.6.3.1. General Characteristics

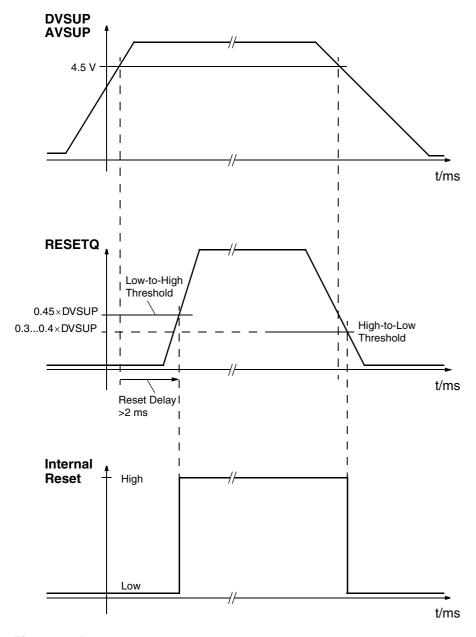
Symbol	Parameter	Pin Name		Limit Valu	s	Unit	Test Conditions
			Min.	Тур.	Max.		
Supply							
I _{SUP1A}	First Supply Current (active) (AHVSUP = 8 V)	AHVSUP		17 11	25 16	mA mA	Vol. Main and Aux = 0 dB Vol. Main and Aux = -30dB
	First Supply Current (active) (AHVSUP = 5 V)			11 8	17 11	mA mA	Vol. Main and Aux = 0 dB Vol. Main and Aux = -30 dB
I _{SUP2A}	Second Supply Current (active) (DVSUP = 5 V)	DVSUP		75	100	mA	
	Second Supply Current (active) (DVSUP = 3.3 V) ¹⁾			75 ¹⁾	100 ¹⁾	mA	
I _{SUP3A}	Third Supply Current (active)	AVSUP		35	45	mA	
I _{SUP1S}	First Supply Current (AHVSUP = 8 V)	AHVSUP		5.6	7.7	mA	STANDBYQ = low
	First Supply Current (AHVSUP = 5 V)			3.7	5.1	mA	
Clock							
f _{CLOCK}	Clock Input Frequency	XTAL_IN		18.432		MHz	
D _{CLOCK}	Clock High to Low Ratio		45		55	%	
t _{JITTER}	Clock Jitter (Verification not provided in Production Test)				50	ps	
V _{xtalDC}	DC-Voltage Oscillator			2.5		V	
t _{Startup}	Oscillator Startup Time at VDD Slew-rate of 1 V/μs	XTAL_IN, XTAL_OUT		0.4	2	ms	
V _{ACLKAC}	Audio Clock Output AC Voltage	AUD_CL_OUT	1.2	1.8		V _{pp}	load = 40 pF
V _{ACLKDC}	Audio Clock Output DC Voltage		0.4		0.6	V _{SUP3}	I _{max} = 0.2 mA
r _{outHF_ACL}	HF Output Resistance			140		Ω	
1) only availa	ble on request	•		-		•	•

4.6.3.2. Digital Inputs, Digital Outputs

Symbol	Parameter	Pin Name	ı	Limit Valus		Unit	Test Conditions
			Min.	Тур.	Max.		
Digital Inpu	ts Levels						
V _{DIGIL}	Digital Input Low Voltage	STANDBYQ			0.2	V _{SUP2}	
V _{DIGIH}	Digital Input High Voltage	D_CTR_I/O_0/1	0.5			V _{SUP2}	
Z _{DIGI}	Input Impedance				5	pF	
I _{DLEAK}	Digital Input Leakage Current		-1		1	μА	0 V < U _{INPUT} < DVSUP D_CTR_I/O_0/1: tri-state
V _{DIGIL}	ADR_SEL Input Low Voltage	ADR_SEL			0.2	V _{SUP2}	
V _{DIGIH}	ADR_SEL Input High Voltage		0.8			V _{SUP2}	
I _{ADRSEL}	Input Current		-500	-220		μА	U _{ADR_SEL} = DVSS
				220	500	μА	U _{ADR_SEL} = DVSUP
Digital Outp	out Levels					·	
V _{DCTROL}	Digital Output Low Voltage	D_CTR_I/O_0			0.4	V	IDDCTR = 1 mA
V _{DCTROH}	Digital Output High Voltage	D_CTR_I/O_1	V _{SUP2} – 0.3			V	IDDCTR = -1 mA

4.6.3.3. Reset Input and Power-Up

Symbol	Parameter	Pin Name	Limit Valus			Unit	Test Conditions	
			Min.	Тур.	Max.			
RESETQ Input Levels								
V _{RHL}	Reset High-Low Transition Voltage	RESETQ	0.3		0.4	V _{SUP2}		
V _{RLH}	Reset Low-High Transition Voltage			0.45		V _{SUP2}		
Z _{RES}	Input Capacitance				5	pF		
I _{RES}	Input High Current				20	μА	U _{RESETQ} = DVSUP	



Note: The reset should not reach high level before the oscillator has started. This requires a reset delay of >2 ms

0.45 x DVSUP means 2.25 Volt with DVSUP = 5.0 V

Fig. 4-22: Power-up sequence

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4.6.3.4. I²C-Bus Characteristics

Symbol	Parameter	Pin Name	ı	Limit Valu	ıs	Unit	Test Conditions
			Min.	Тур.	Max.		
V _{I2CIL}	I ² C-BUS Input Low Voltage	I2C_CL, I2C_DA			0.3	V _{SUP2}	
V _{I2CIH}	I ² C-BUS Input High Voltage	- IZC_DA	0.6			V _{SUP2}	
t _{l2C1}	I ² C START Condition Setup Time		120			ns	
t _{I2C2}	I ² C STOP Condition Setup Time		120			ns	
t _{I2C5}	I ² C-Data Setup Time before Rising Edge of Clock		55			ns	
t _{I2C6}	I ² C-Data Hold Time after Falling Edge of Clock		55			ns	
t _{I2C3}	I ² C-Clock Low Pulse Time	I2C_CL	500			ns	
t _{I2C4}	I ² C-Clock High Pulse Time		500			ns	
f _{I2C}	I ² C-BUS Frequency				1.0	MHz	
V _{I2COL}	I ² C-Data Output Low Voltage	I2C_CL,			0.4	V	I _{I2COL} = 3 mA
I _{I2COH}	I ² C-Data Output High Leakage Current	12C_DA			1.0	μА	V _{I2COH} = 5 V
t _{I2COL1}	I ² C-Data Output Hold Time after Falling Edge of Clock		15			ns	
t _{I2COL2}	I ² C-Data Output Setup Time before Rising Edge of Clock		100			ns	f _{I2C} = 1 MHz

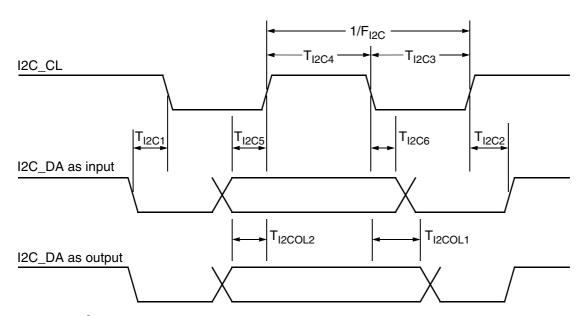
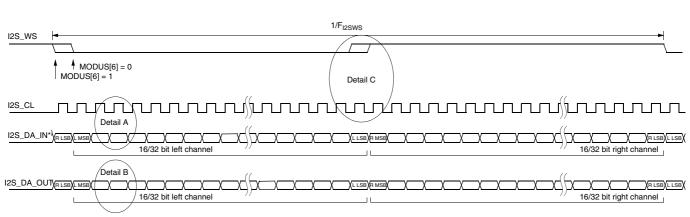


Fig. 4–23: I²C bus timing diagram

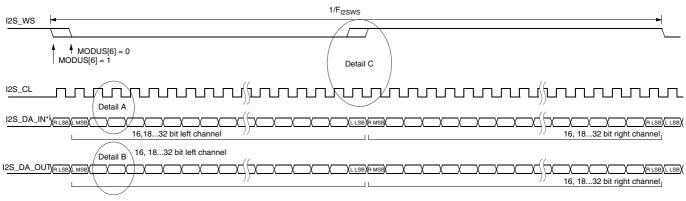
4.6.3.5. I²S-Bus Characteristics

Symbol	Parameter	Pin Name		_imit Valu	ıs	Unit	Test Conditions
			Min.	Тур.	Max.		
V _{I2SIL}	Input Low Voltage	I2S_CL			0.2	V _{SUP2}	
V _{I2SIH}	Input High Voltage	I2S_WS I2S_CL3	0.5			V _{SUP2}	
Z _{I2SI}	Input Impedance	I2S_WS3 I2S_DA_IN13			5	pF	
I _{LEAKI2S}	Input Leakage Current		-1		1	μА	0 V < U _{INPUT} < DVSUP
V _{I2SOL}	I ² S Output Low Voltage	I2S_CL			0.4	V	I _{I2SOL} = 1 mA
V _{I2SOH}	I ² S Output High Voltage	I2S_WS I2S_DA_OUT	V _{SUP2} – 0.3			V	I _{I2SOH} = -1 mA
f _{I2SOWS}	I ² S-Word Strobe Output Frequency	I2S_WS		48.0		kHz	
f _{I2SOCL}	I ² S-Clock Output Frequency	I2S_CL		1.536	3.072	MHz	
R _{I2S10/I2S20}	I ² S-Clock Output High/Low-Ratio		0.9	1.0	1.1		
Synchronou	s I ² S Interface		<u> </u>		<u> </u>	1	
t _{s_I2S}	I ² S Input Setup Time before Rising Edge of Clock	I2S_DA_IN1/2 I2S_CL	12			ns	for details see Fig. 4–24 "I2S timing diagram (syn- chronous interface)"
t _{h_I2S}	I ² S Input Hold Time after Rising Edge of Clock		40			ns	
t _{d_I2S}	I ² S Output Delay Time after Falling Edge of Clock	I2S_CL I2S_WS I2S_DA_OUT			28	ns	C _L =30 pF
f _{I2SWS}	I ² S-Word Strobe Input Frequency	I2S_WS		48.0		kHz	
f _{I2SCL}	I ² S-Clock Input Frequency	I2S_CL		1.536	3.072	MHz	
R _{I2SCL}	I ² S-Clock Input Ratio		0.9		1.1		
Asynchrono	us I ² S Input Interface						
t _{s_l2S3}	I ² S3 Input Setup Time before Rising Edge of Clock	I2S_CL3 I2S_WS3	4			ns	for details see Fig. 4–25 "I2S3 timing diagram
t _{h_I2S3}	I ² S3 Input Hold Time after Rising Edge of Clock	I2S_DA_IN3	40			ns	(asynchronous input interface)"
f _{I2S3WS}	I ² S3-Word Strobe Input Frequency	I2S_WS3	6		49	kHz	
f _{I2S3CL}	I ² S3-Clock Input Frequency	I2S_CL3			3.136	MHz	
R _{I2S3CL}	I ² S3-Clock Input Ratio		0.9		1.1		
Asynchrono	us I ² S Output Interface						
t _{s_I2S4}	I ² S Wordstrobe Setup Time before Rising Edge of Clock	I2S_WS4 I2S_CL4	4			ns	for details see Fig. 4–26 "I2S4 timing diagram (asynchronous output interface)"
t _{h_I2S4}	I ² S Wordstrobe Hold Time after Rising Edge of Clock		40			ns	
t _{d_I2S4}	I ² S Output Delay Time after Falling Edge of Clock	I2S_CL4 I2S_WS4 I2S_DA_OUT4			28	ns	C _L =30 pF
f _{I2SWS4}	I ² S-Word Strobe Slave Frequency	I2S_WS4	6		49	kHz	
f _{I2SCL4}	I ² S-Clock Input Frequency	I2S_CL4	0.129		3.136	MHz	
R _{I2SCL4}	I ² S-Clock Input Ratio		0.9		1.1		

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Data: MSB first, I²S synchronous master



Data: MSB first, I²S synchronous slave

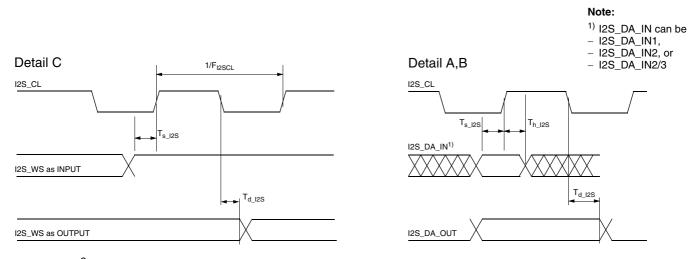
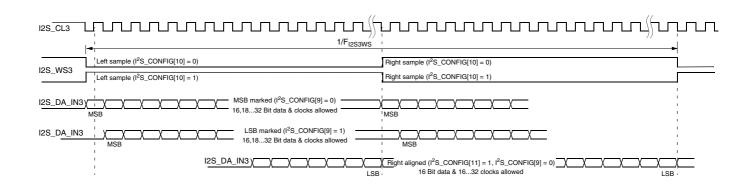


Fig. 4-24: I²S timing diagram (synchronous interface)



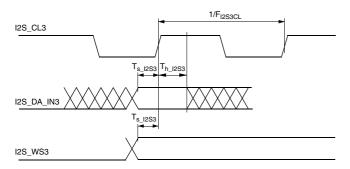


Fig. 4–25: I²S3 timing diagram (asynchronous input interface)

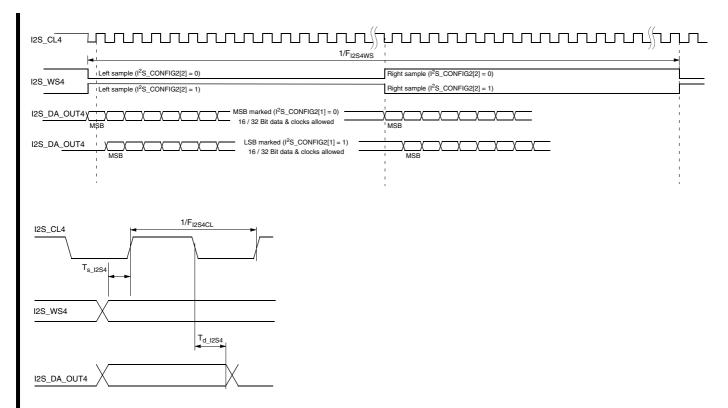


Fig. 4–26: I²S4 timing diagram (asynchronous output interface)

▮ 4.6.3.6. Analog Baseband Inputs and Outputs, AGNDC

Symbol	Parameter	Pin Name		Limit Valus		Unit	Test Conditions
			Min.	Тур.	Max.		
Analog Gro	und						
V _{AGNDC0}	AGNDC Open Circuit Voltage (AHVSUP =8 V)	AGNDC		3.77		V	R _{load} ≥10 MΩ
	AGNDC Open Circuit Voltage (AHVSUP = 5 V)			2.51		V	
R _{outAGN}	AGNDC Output Resistance (AHVSUP = 8 V)		70	125	180	kΩ	3 V ≤ V _{AGNDC} ≤ 4 V
	AGNDC Output Resistance (AHVSUP = 5 V)		47	83	120	kΩ	
Analog Inpu	ut Resistance						
R _{inSC}	SCART Input Resistance from T _A = 0 to 70 °C	SCn_IN_s ¹⁾	25	40	58	kΩ	f _{signal} = 1 kHz, I = 0.05 mA
R _{inMONO}	MONO Input Resistance from T _A = 0 to 70 °C	MONO_IN	15	24	35	kΩ	f _{signal} = 1 kHz, I = 0.1 mA
1) "n" means	s "1", "2", "3", or "4"; "s" means "L"	or "R"					

Symbol	Parameter	Pin Name		Limit Val	us	Unit	Test Conditions
			Min.	Тур.	Max.		
Audio Analo	og-to-Digital-Converter	<u> </u>			•		•
V _{AICL}	Analog Input Clipping Level for Analog-to-Digital- Conversion (AHVSUP = 8 V)	SCn_IN_s, ¹⁾ MONO_IN	2.00		2.25	V _{RMS}	f _{signal} = 1 kHz
	Analog Input Clipping Level for Analog-to-Digital- Conversion (AHVSUP = 5 V)		1.13		1.51	V _{RMS}	
SCART Out	puts						
R _{outSC}	SCART Output Resistance	SCn_OUT_s ¹⁾	200 200	330	460 500	ΩΩ	$ f_{signal} = 1 \text{ kHz, I} = 0.1 \text{ mA} $ $ T_{j} = 27 \text{ °C} $ $ T_{A} = 0 \text{ to } 70 \text{ °C} $
dV _{OUTSC}	Deviation of DC-Level at SCART Output from AGNDC Voltage		-70		+70	mV	
A _{SCtoSC}	Gain from Analog Input to SCART Output	SCn_IN_s, ¹⁾ MONO_IN	-1.0		+0.5	dB	f _{signal} = 1 kHz
f _{rSCtoSC}	Frequency Response from Analog Input to SCART Output	→ SCn_OUT_s ¹⁾	-0.5		+0.5	dB	with resp. to 1 kHz Bandwidth: 0 to 20000 Hz
V _{outSC}	Signal Level at SCART Output (AHVSUP = 8 V)	SCn_OUT_s ¹⁾	1.8	1.9	2.0	V _{RMS}	f _{signal} = 1 kHz Volume 0 dB
	Signal Level at SCART Output (AHVSUP = 5V)		1.17	1.27	1.37	V _{RMS}	Full Scale input from I ² S
Main and A	ux Outputs						
R _{outMA}	Main/AUX Output Resistance	DACp_s ¹⁾	2.1 2.1	3.3	4.6 5.0	kΩ kΩ	$ f_{signal} = 1 \text{ kHz, I} = 0.1 \text{ mA} $ $ T_{j} = 27 \text{ °C} $ $ T_{A} = 0 \text{ to } 70 \text{ °C} $
V _{outDCMA}	DC-Level at Main/AUX-Output (AHVSUP = 8 V)		1.80	2.04 61	2.28	V mV	Volume 0 dB Volume –30 dB
	DC-Level at Main/AUX-Output (AHVSUP = 5 V)		1.12	1.36 40	1.60	V mV	Volume 0 dB Volume –30 dB
V _{outMA}	Signal Level at Main/AUX-Output (AHVSUP = 8 V)		1.23	1.37	1.51	V _{RMS}	f _{signal} = 1 kHz Volume 0 dB
	Signal Level at Main/AUX-Output (AHVSUP = 5 V)	0.76 0.90 1	1.04	V _{RMS}	Full scale input from I ² S		

4.6.3.7. Sound IF Inputs

Symbol	Parameter	Pin Name	Limit Valus			Unit	Test Conditions
			Min.	Тур.	Max.		
R _{IFIN}	Input Impedance	ANA_IN1+, ANA_IN2+, ANA_IN-	1.5 6.8	2 9.1	2.5 11.4	kΩ kΩ	Gain AGC = 20 dB Gain AGC = 3 dB
DC _{VREFTOP}	DC Voltage at VREFTOP	VREFTOP	2.45	2.65	2.75	V	
DC _{ANA_IN}	DC Voltage on IF Inputs	ANA_IN1+, ANA_IN2+, ANA_IN-	1.3	1.5	1.7	V	
XTALK _{IF}	Crosstalk Attenuation	ANA_IN1+, ANA_IN2+, ANA_IN-	40			dB	f _{signal} = 1 MHz Input Level = -2 dBr
BW _{IF}	3 dB Bandwidth		10			MHz	
AGC	AGC Step Width			0.85		dB	

4.6.3.8. Power Supply Rejection

Symbol	Parameter	Pin Name	Limit Valus		Unit	Test Conditions					
			Min.	Тур.	Max.						
PSRR: Reje	PSRR: Rejection of Noise on AHVSUP at 1 kHz										
PSRR	AGNDC	AGNDC		80		dB					
	From Analog Input to I ² S Output	MONO_IN, SCn_IN_s ¹⁾		70		dB					
	From Analog Input to SCART Output	MONO_IN, SCn_IN_s ¹⁾ SCn_OUT_s ¹⁾		70		dB					
	From I ² S Input to SCART Output	SCn_OUT_s ¹⁾		60		dB					
	From I ² S Input to Main/Aux Output	DACp_s ¹⁾		80		dB					
1) "n" mean	s "1", "2", "3", or "4"; "s" means "L" or	"R"; "p" means "N	∕/" or "A"			•	•				

4.6.3.9. Analog Performance

Symbol	Parameter	Pin Name		Limit Valu	ıs	Unit	Test Conditions
			Min.	Тур.	Max.		
Specificatio	ons for AHVSUP = 8 V						
SNR	Dynamic Range and Signal-to-Noise Ratio						
	from Analog Input to I ² S Output	MONO_IN, SCn_IN_s ¹)	90	95		dB	Input Level = -20 dB with resp. to V_{AICL} , $f_{sig} = 1$ kHz, A-weighted 20 Hz20 kHz
	from Analog Input to SCART Output	MONO_IN, SCn_IN_s ¹⁾ → SCn_OUT_s ¹⁾	93	96		dB	Input Level = -20 dB, f _{sig} = 1 kHz, A-weighted 20 Hz20 kHz Volume = 0 dB
	from I ² S Input to SCART Output	SCn_OUT_s ¹⁾	90	95		dB	Volume = 0 db
	from I ² S Input to Main/Aux-Output for Analog Volume at 0 dB for Analog Volume at –30 dB	DACp_s ¹⁾	90 83	95 88		dB dB	
THD	Total Harmonic Distortion						
	from Analog Input to I ² S Output	MONO_IN, SCn_IN_s ¹⁾		0.008	0.03	%	Input Level = -3 dBr with resp. to V _{AICL} , f _{sig} = 1 kHz, unweighted 20 Hz20 kHz
	from Analog Input to SCART Output	MONO_IN, SCn_IN_s → SCn_OUT_s ¹⁾		0.008	0.03	%	Input Level = -3 dBr, f _{sig} = 1 kHz, unweighted 20 Hz20 kHz
	from I ² S Input to SCART Output	SCn_OUT_s ¹⁾		0.008	0.03	%	
	from I ² S Input to Main or Aux Output	DACp_s ¹⁾		0.008	0.03	%	
1) "n" means	s "1", "2", "3", or "4"; "s" means "L" or	"R"; "p" means "	M" or "A"				

Symbol	Parameter	Pin Name		Limit Val	us	Unit	Test Conditions
			Min.	Тур.	Max.		
Specification	ons for AHVSUP = 5 V						
SNR	Dynamic Range and Signal-to-Noise Ratio						
	from Analog Input to I ² S Output	MONO_IN, SCn_IN_s ¹⁾	87	92		dB	Input Level = -20 dB with resp. to V_{AICL} , $f_{sig} = 1$ kHz A-weighted 20 Hz 20 kHz
	from Analog Input to SCART Output	MONO_IN, SCn_IN_s ¹⁾ → SCn_OUT_s ¹⁾	90	93		dB	Input Level = -20 dB, f _{sig} = 1 kHz, A-weighted 20 Hz20 kHz Volume = 0 dB
	from I ² S Input to SCART Output	SCn_OUT_s ¹⁾	87	92		dB	- Volume = 0 dB
	from I ² S Input to Main/Aux-Output for Analog Volume at 0 dB for Analog Volume at –30 dB	DACp_s ¹⁾	87 75	92 80		dB dB	
THD	Total Harmonic Distortion						
	from Analog Input to I ² S Output	MONO_IN, SCn_IN_s ¹)		0.03	0.1	%	Input Level = -3 dBr with resp. to V_{AICL} , $f_{sig} = 1$ kHz unweighted 20 Hz20 kHz
	from Analog Input to SCART Output	MONO_IN, SCn_IN_s → SCn_OUT_s ¹⁾			0.1	%	Input Level = -3 dBr, $f_{sig} = 1$ kHz, unweighted 20 Hz20 kHz
	from I ² S Input to SCART Output	SCn_OUT_s ¹⁾			0.1	%	
	from I ² S Input to Main or Aux Output	DACp_s ¹⁾			0.1	%	

Symbol	Parameter Pir	n Name		Limit Valu	ıs	Unit	Test Conditions
			Min.	Тур.	Max.		
CROSSTALI	K Specifications						·
XTALK	Crosstalk Attenuation		Input Level = -3 dB, f_{sig} = 1 kHz, unused analog inputs connected to ground by Z < 1 k Ω				
	between left and right channel within SCART Input/Output pair (L→R, R→L)						unweighted 20 Hz20 kHz
	$SCn_IN \rightarrow SCn_OUT^{1)}$		80			dB	
	SC1_IN or SC2_IN \rightarrow I ² S Output		80			dB	
	$SC3_IN \rightarrow I^2S$ Output		80			dB	
	$I^2S Input \rightarrow SCn_OUT^{1)}$		80			dB	
	between left and right channel within Main or Aux Output pair						unweighted 20 Hz20 kHz
	$I^2S Input \rightarrow DACp^{1)}$		75			dB	
	between SCART Input/Output pairs1)						(unweighted
	D = disturbing program O = observed program						20 Hz20 kHz) same signal source on left and right disturbing chan-
	D: MONO/SCn_IN \rightarrow SCn_OUT O: MONO/SCn_IN \rightarrow SCn_OUT ¹⁾		100			dB	nel, effect on each observed output channel
	D: MONO/SCn_IN \rightarrow SCn_OUT or unsel. O: MONO/SCn_IN \rightarrow I ² S Output		95			dB	
	D: MONO/SCn_IN \rightarrow SCn_OUT O: I ² S Input \rightarrow SCn_OUT ¹⁾		100			dB	
	D: MONO/SCn_IN \rightarrow unselected O: I ² S Input \rightarrow SC1_OUT ¹⁾		100			dB	
	Crosstalk between Main and Aux Output pairs $I^2S \text{ Input DSP} \rightarrow DACp^{1)}$		90			dB	(unweighted 20 Hz20 kHz) same signal source on left and right disturbing chan- nel, effect on each observed output channel
XTALK	Crosstalk from Main or Aux Output to SC and vice versa	CART Output					(unweighted 20 Hz20 kHz) same signal source on left
	D = disturbing program O = observed program						and right disturbing chan- nel, effect on each observed output channel
	D: MONO/SCn_IN/DSP \rightarrow SCn_OUT O: I ² S Input \rightarrow DACp ¹⁾	D: MONO/SCn_IN/DSP \rightarrow SCn_OUT O: I^2S Input \rightarrow DACp ¹⁾				dB	SCART output load resistance 10 $k\Omega$
	D: MONO/SCn_IN/DSP \rightarrow SCn_OUT O: 1^2 S Input \rightarrow DACp ¹⁾		85			dB	SCART output load resistance 30 $k\Omega$
	D: I^2S Input \rightarrow DACp O: MONO/SCn_IN \rightarrow SCn_OUT ¹⁾		95			dB	
	D: I^2S Input \rightarrow DACM O: I^2S Input \rightarrow SCn_OUT ¹⁾		95			dB	
1) "n" means	s "1", "2", "3", or "4"; "s" means "L" or "R";	"p" means "	M" or "A"				

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4.6.3.10. Sound Standard Dependent Characteristics

Symbol	Parameter	Pin Name		Limit Valu	ıs	Unit	Test Conditions
			Min.	Тур.	Max.		
NICAM Chara	cteristics (MSP Standard Code = 8)		· ·		<u>'</u>	1	
dV _{NICAMOUT}	Tolerance of Output Voltage of NICAM Baseband Signal	DACp_s SCn_OUT_s ¹⁾	-1.5		+1.5	dB	2.12 kHz, Modulator input level = 0 dBref
S/N _{NICAM}	S/N of NICAM Baseband Signal		72			dB	NICAM: -6 dB, 1 kHz, RMS unweighted 0 to 15 kHz, Vol = 9 dB NIC_Presc = 7Fh Output level 1 V _{RMS} at DACp_s
THD _{NICAM}	Total Harmonic Distortion + Noise of NICAM Baseband Signal				0.1	%	2.12 kHz, Modulator input level = 0 dBref
BER _{NICAM}	NICAM: Bit Error Rate				1	10 ⁻⁷	FM+NICAM, norm conditions
fR _{NICAM}	NICAM Frequency Response, 2015000 Hz		-1.0		+1.0	dB	Modulator input level = -12 dB dBref; RMS
XTALK _{NICAM}	NICAM Crosstalk Attenuation (Dual)		80			dB	
SEP _{NICAM}	NICAM Channel Separation (Stereo)		80			dB	
FM Character	ristics (MSP Standard Code = 3)						
dV _{FMOUT}	Tolerance of Output Voltage of FM Demodulated Signal	DACp_s, SCn_OUT_s ¹⁾	-1.5		+1.5	dB	1 FM-carrier, 50 μs, 1 kHz, 40 kHz deviation; RMS
S/N _{FM}	S/N of FM Demodulated Signal		73			dB	1 FM-carrier 5.5 MHz,
THD _{FM}	Total Harmonic Distortion + Noise of FM Demodulated Signal				0.1	%	 50 μs, 1 kHz, 40 kHz deviation; RMS, unweighted 0 to 15 kHz (for S/N); full input range, FM-Prescale = 46 h, Vol = 0 dB → Output Level 1 V_{RMS} at DACp_s
fR _{FM}	FM Frequency Responses, 2015000 Hz		-1.0		+1.0	dB	1 FM-carrier 5.5 MHz, 50 μs, Modulator input level = -14.6 dBref; RMS
XTALK _{FM}	FM Crosstalk Attenuation (Dual)		80			dB	2 FM-carriers 5.5/5.74 MHz, 50 μs, 1 kHz, 40 kHz deviation; Bandpass 1 kHz
SEP _{FM}	FM Channel Separation (Stereo)		50			dB	2 FM-carriers 5.5/5.74 MHz, 50 μs, 1 kHz, 40 kHz deviation; RMS

 [&]quot;n" means "1", "2", "3", or "4"; "s" means "L" or "R"; "p" means "M" or "A"
 EIM refers to 75-μs Equivalent Input Modulation. It is defined as the audio-signal level which results in a stated percentage modulation, when the DBX encoding process is replaced by a 75-μs preemphasis network.

Symbol	Parameter	Pin Name	L	imit Valu	ıs	Unit	Test Conditions
			Min.	Тур.	Max.		
AM Characte	ristics (MSP Standard Code = 9)						
S/N _{AM(1)}	S/N of AM Demodulated Signal measurement condition: RMS/Flat	DACp_s, SCn_OUT_s ¹⁾	55			dB	SIF level: 0.1–0.8 V _{pp} AM-carrier 54% at 6.5 MHz
S/N _{AM(2)}	S/N of AM Demodulated Signal measurement condition: QP/CCIR		45			dB	Vol = 0 dB, FM/AM prescaler set for output = 0.5 V _{RMS} at
THD _{AM}	Total Harmonic Distortion + Noise of AM Demodulated Signal				0.6	%	Main out; Standard Code = 09 _{hex} no video/chrominance
fR _{AM}	AM Frequency Response 50 Hz 12 kHz		-2.5		+1.0	dB	components
BTSC Charac	cteristics (MSP Standard Code = 20 _h	_{ex} , 21 _{hex})					
S/N _{BTSC}	S/N of BTSC Stereo Signal S/N of BTSC-SAP Signal	DACp_s, SCn_OUT_s ¹⁾	68 57			dB dB	1 kHz L or R or SAP, 100% modulation, 75 μs deem- phasis, RMS unweighted 0 to 15 kHz
THD _{BTSC}	THD+N of BTSC Stereo Signal THD+N of BTSC SAP Signal				0.1 0.5	%	1 kHz L or R or SAP, 100% 75 µs EIM ²⁾ , DBX NR or MNR, RMS unweighted 0 to 15 kHz
fR _{DBX}	Frequency Response of BTSC Stereo, 50 Hz12 kHz		-1.0		1.0	dB	L or R or SAP, 1%66% EIM ²⁾ , DBX NR
	Frequency Response of BTSC- SAP, 50 Hz9 kHz		-1.0		1.0	dB	
fR _{MNR}	Frequency Response of BTSC Stereo, 50 Hz12 kHz		-2.0		2.0	dB	L or R 5%66% EIM ²⁾ , MNR
	Frequency Response of BTSC- SAP, 50 Hz9 kHz		-2.0		2.0	dB	SAP, white noise, 10% Modulation, MNR
XTALK _{BTSC}	Stereo → SAP SAP → Stereo		76 80			dB dB	1 kHz L or R or SAP, 100% modulation, 75 μs deemphasis, Bandpass 1 kHz
SEP _{DBX}	Stereo Separation DBX NR 50 Hz10 kHz 50 Hz12 kHz		35 30			dB dB	L or R 1%66% EIM ²⁾ , DBX NR
SEP _{MNR}	Stereo Separation MNR		30			dB	L = 300 Hz, R = 3.1 kHz 14% Modulation, MNR
FM _{pil}	Pilot deviation threshold	ANA_IN1+, ANA_IN2+	3.2 1.2		3.5 1.5	kHz kHz	4.5 MHz carrier modulated with f_h = 15.734 kHz SIF level = 100 mV _{pp} indication: STATUS Bit[6]
f _{Pilot}	Pilot Frequency Range		15.563		15.843	kHz	standard BTSC stereo sig- nal, sound carrier only

^{1) &}quot;n" means "1", "2", "3", or "4"; "s" means "L" or "R"; "p" means "M" or "A"

²⁾ EIM refers to 75-μs Equivalent Input Modulation. It is defined as the audio-signal level which results in a stated percentage modulation, when the DBX encoding process is replaced by a 75-μs preemphasis network.

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Symbol	Parameter	Pin Name	ı	Limit Valu	ıs	Unit	Test Conditions
			Min.	Тур.	Max.		
BTSC Charac with a minim	cteristics (MSP Standard Code = 20 _h um IF input signal level of 70 mVpp	_{ex} , 21 _{hex}) (measured without	t any vide	eo/chroma	a signal c	components	s)
S/N _{BTSC}	S/N of BTSC Stereo Signal S/N of BTSC-SAP Signal	DACp_s, SCn_OUT_s ¹⁾	64 55			dB dB	1 kHz L or R or SAP, 100% modulation, 75 μs deem- phasis, RMS unweighted 0 to 15 kHz
THD _{BTSC}	THD+N of BTSC Stereo Signal THD+N of BTSC SAP Signal				0.15 0.8	%	1 kHz L or R or SAP, 100% 75 µs EIM ²⁾ , DBX NR or MNR, RMS unweighted 0 to 15 kHz
fR _{DBX}	Frequency Response of BTSC Stereo, 50 Hz12 kHz		-1.0		1.0	dB	L or R or SAP, 1%66% EIM ²⁾ , DBX NR
	Frequency Response of BTSC- SAP, 50 Hz9 kHz		-1.0		1.0	dB	
fR _{MNR}	Frequency Response of BTSC Stereo, 50 Hz12 kHz		-2.0		2.0	dB	L or R 5%66% EIM ²⁾ , MNR
	Frequency Response of BTSC- SAP, 50 Hz9 kHz		-2.0		2.0	dB	SAP, white noise, 10% Modulation, MNR
XTALK _{BTSC}	Stereo → SAP SAP → Stereo		75 75			dB dB	1 kHz L or R or SAP, 100% modulation, 75 μs deem- phasis, Bandpass 1 kHz
SEP _{DBX}	Stereo Separation DBX NR 50 Hz10 kHz 50 Hz12 kHz		35 30			dB dB	L or R 1%66% EIM ²⁾ , DBX NR
SEP _{MNR}	Stereo Separation MNR		30			dB	L = 300 Hz, R = 3.1 kHz 14% Modulation, MNR
EIA-J Charac	teristics (MSP Standard Code = 30 _h	_{ex})					
S/N _{EIAJ}	S/N of EIA-J Stereo Signal S/N of EIAJ Sub-Channel	DACp_s, SCn_OUT_s ¹⁾	60 60			dB dB	1 kHz L or R, 100% modulation, 75 µs deemphasis,
THD _{EIAJ}	THD+N of EIA-J Stereo Signal THD+N of EIA-J Sub-Channel				0.2 0.3	%	RMS unweighted 0 to 15 kHz
fR _{EIAJ}	Frequency Response of EIA-J Stereo, 50 Hz12 kHz		-1.0		1.0	dB	100% modulation, 75 μs deemphasis
	Frequency Response of EIA-J Sub- Channel, 50 Hz12 kHz		-1.0		1.0	dB	
XTALK _{EIAJ}	Main → SUB Sub → Main		66 80			dB dB	1 kHz L or R, 100% modu- lation, 75 μs deemphasis, Bandpass 1 kHz
SEP _{EIAJ}	Stereo Separation 50 Hz5 kHz 50 Hz10 kHz		35 28			dB dB	EIA-J Stereo Signal, L or R 100% modulation

 [&]quot;n" means "1", "2", "3", or "4"; "s" means "L" or "R"; "p" means "M" or "A"
 EIM refers to 75-μs Equivalent Input Modulation. It is defined as the audio-signal level which results in a stated percentage modulation, when the DBX encoding process is replaced by a 75-μs preemphasis network.

Symbol	Parameter	Pin Name	L	Limit Valus		Unit	Test Conditions
			Min.	Тур.	Max.		
FM-Radio C	haracteristics (MSP Standard Code =	40 _{hex})					
S/N _{UKW}	S/N of FM-Radio Stereo Signal	DACp_s, SCn_OUT_s ¹⁾	70			dB	1 kHz L or R, 100% modu-
THD _{UKW}	THD+N of FM-Radio Stereo Signal	SCh_OUT_s			0.1	%	lation, 75 µs deemphasis, RMS unweighted 0 to 15 kHz
fR _{UKW}	Frequency Response of FM-Radio Stereo 50 Hz15 kHz		-1.0		+1.0	dB	L or R, 1%100% modulation, 75 μs deemphasis
Sep _{UKW}	Stereo Separation 50 Hz15 kHz		45			dB	
f _{Pilot}	Pilot Frequency Range	ANA_IN1+ ANA_IN2+	18.844		19.125	kHz	standard FM radio stereo signal

 $^{^{1)}}$ "n" means "1", "2", "3", or "4"; "s" means "L" or "R"; "p" means "M" or "A"

4.6.3.11. Audio/Video Synchronization Characteristics

Symbol	TV or Film Standard	Frequency	l	Limit Valus		Unit	Test Conditions
			Min.	Тур.	Max.		
A/V Sync F	requency Range for Automatic	/ideo Standard Detection	n				
	PAL / SECAM	50 Hz	47.5		52.5	Hz	
	NTSC	59.94 Hz	57.5		62.5	Hz	
	Monochrome	60 Hz	57.5		62.5	Hz	
A/V Sync F	requency Range Check						
	PAL / SECAM	50 Hz	45		55	Hz	
	NTSC	59.94 Hz	55		65	Hz	
	Monochrome	60 Hz	55		65	Hz	

²⁾ EIM refers to 75-μs Equivalent Input Modulation. It is defined as the audio-signal level which results in a stated percentage modulation, when the DBX encoding process is replaced by a 75-μs preemphasis network.

5. Appendix A: Overview of TV-Sound Standards

5.1. NICAM 728

Table 5–1: Summary of NICAM 728 sound modulation parameters

Specification	I	B/G	L		D/K		
Carrier frequency of digital sound	6.552 MHz	5.85 MHz	5.85 MHz		5.85 MHz		
Transmission rate		728 kbit/s					
Type of modulation	Di	Differentially encoded quadrature phase shift keying (DQPSK)					
Spectrum shaping Roll-off factor		by n	means of Roll-off filters				
Holl-off factor	1.0	0.4	0.4		0.4		
Carrier frequency of analog sound component	6.0 MHz FM mono	5.5 MHz FM mono	6.5 MHz terrestrial	AM mono	6.5 MHz FM mono		
Power ratio between vision carrier and analog sound carrier	10 dB	13 dB	10 dB	16 dB	13 dB		
Power ratio between analog and modulated	10 dB	7 dB	17 dB	11 dB	China/ Hungary	Poland	
digital sound carrier					12 dB	7 dB	

Table 5–2: Summary of NICAM 728 sound coding characteristics

Characteristics	Values
Audio sampling frequency	32 kHz
Number of channels	2
Initial resolution	14 bit/sample
Companding characteristics	near instantaneous, with compression to 10 bits/sample in 32-samples (1 ms) blocks
Coding for compressed samples	2's complement
Preemphasis	CCITT Recommendation J.17 (6.5 dB attenuation at 800 Hz)
Audio overload level	+12 dBm measured at the unity gain frequency of the preemphasis network (2 kHz)

5.2. A2-Systems

Table 5-3: Key parameters for A2 Systems of Standards B/G, D/K, and M

Characteristics	Sc	ound Carrier	FM1	So	ound Carrier	FM2
TV-Sound Standard	B/G	D/K	М	B/G	D/K	М
Carrier frequency in MHz	5.5	6.5	4.5	5.7421875	6.2578125 6.7421875 5.7421875	4.724212
Vision/sound power difference		13 dB			20 dB	
Sound bandwidth			40 Hz to	15 kHz		
Preemphasis	50	μS	75 μs	50 μs		75 μs
Frequency deviation (nom/max)	±27/±5	50 kHz	±17/±25 kHz			±15/±25 kHz
Transmission Modes						
Mono transmission		mono			mono	
Stereo transmission	(L+l	R)/2	(L+R)/2	ſ	3	(L-R)/2
Dual sound transmission		language A			language B	
Identification of Transmission Mode						
Pilot carrier frequency				54.68	75 kHz	55.0699 kHz
Max. deviation portion					±2.5 kHz	
Type of modulation / modulation depth					AM / 50%	
Modulation frequency				stereo: 1	nmodulated 17.5 Hz 74.1 Hz	149.9 Hz 276.0 Hz

5.3. BTSC-Sound System

Table 5–4: Key parameters for BTSC-Sound Systems

	Aural Carrier		втѕс	C-MPX-Components			
	Carrier	(L+R)	Pilot	(L-R)	SAP	Prof. Ch.	
Carrier frequency (f _{hNTSC} = 15.734 kHz) (f _{hPAL} = 15.625 kHz)	4.5 MHz	Baseband	f _h	2 f _h	5 f _h	6.5 f _h	
Sound bandwidth in kHz		0.05 - 15		0.05 - 15	0.05 - 10	0.05 - 3.4	
Preemphasis		75 μs		DBX	DBX	150 μs	
Max. deviation to Aural Carrier	73 kHz (total)	25 kHz ¹⁾	5 kHz	50 kHz ¹⁾	15 kHz	3 kHz	
Max. Freq. Deviation of Subcarrier Modulation Type				AM	10 kHz FM	3 kHz FM	
1) Sum does not exceed 50 kHz due to i	nterleaving effe	ects		ı	ı	ı	

5.4. Japanese FM Stereo System (EIA-J)

Table 5-5: Key parameters for Japanese FM-Stereo Sound System EIA-J

	Aural	E	EIA-J-MPX-Component	s
	Carrier FM	(L+R)	(L-R)	Identification
Carrier frequency (f _h = 15.734 kHz)	4.5 MHz	Baseband	2 f _h	3.5 f _h
Sound bandwidth		0.05 - 15 kHz	0.05 - 15 kHz	_
Preemphasis		75 μs	75 μs	none
Max. deviation portion to Aural Carrier	47 kHz	25 kHz	20 kHz	2 kHz
Max. Freq. Deviation of Subcarrier Modulation Type			10 kHz FM	60% AM
Transmitter-sided delay		20 μs	0 μs	0 μs
Mono transmission		L+R	_	unmodulated
Stereo transmission		L+R	L-R	982.5 Hz
Bilingual transmission		Language A	Language B	922.5 Hz

5.5. FM Satellite Sound

Table 5–6: Key parameters for FM Satellite Sound

Carrier Frequency	Maximum FM Deviation	Sound Mode	Bandwidth	Deemphasis
6.5 MHz	85 kHz	Mono	15 kHz	50 μs
7.02/7.20 MHz	50 kHz	Mono/Stereo/Bilingual	15 kHz	adaptive
7.38/7.56 MHz	50 kHz	Mono/Stereo/Bilingual	15 kHz	adaptive
7.74/7.92 MHz	50 kHz	Mono/Stereo/Bilingual	15 kHz	adaptive

5.6. FM-Stereo Radio

Table 5–7: Key parameters for FM-Stereo Radio Systems

	Aural	FM-Radio-MPX-Components					
	Carrier	(L+R)	Pilot	(L-R)	RDS/ARI		
Carrier frequency (f _p = 19 kHz)	10.7 MHz	Baseband	fp	2 f _p	3 f _p		
Sound bandwidth in kHz		0.05 - 15		0.05 - 15			
Preemphasis: - USA - Europe		75 μs 50 μs		75 μs 50 μs			
Max. deviation to Aural Carrier	75 kHz (100%)	90% ¹⁾	10%	90%1)	5%		

6. Appendix B: Manual Mode

To adapt the modes of the STANDARD SELECT register to individual requirements, the MSP 44x8G offers a Manual Mode, which provides sophisticated programming of the MSP 44x8G.

The Manual Mode can be used only in those cases, where user specific requirements concerning detection, identification, or carrier positioning have to be met.

After the setting of the STANDARD SELECT register, the MSP 44x8G is set up for optimal behavior. **Therefore**, it is not recommended to use the Manual mode.

6.1. Demodulator Write and Read Registers for Manual Mode

In case of Automatic Sound Select (MODUS[0]=1), any modifications of all DCO registers listed in Table 6–1 are ignored.

Table 6–1: Demodulator Write Registers; Subaddress: 10_{hex}; these registers are not readable!

	Demodulator Write Registers	Address (hex)	MSP- Version	Description	Reset Mode	Page
A	AUTO_FM/AM	00 21	4418, 4458	1. MODUS[0]=1 (Automatic Sound Select): Switching Level threshold of Automatic Switching between NICAM and FM/AM in case of bad NICAM reception		82
				2. MODUS[0]=0 (Manual Mode): Activation and configuration of Automatic Switching between NICAM and FM/AM in case of bad NICAM reception		
A	A2_Threshold	00 22		A2 Stereo Identification Threshold	01 90 _{hex}	84
C	CM_Threshold	00 24		Carrier-Mute Threshold	00 2A _{hex}	84
	DCO1_LO DCO1_HI	00 93 00 9B		Note: Modifications are ignored for Automatic Sound Select = on (MODUS[0]=1)	00 00 _{hex}	85
	0C02_L0 0C02_HI	00 A3 00 AB		Increment channel 1 Low Part Increment channel 1 High Part		
				Increment channel 2 Low Part Increment channel 2 High Part		

Note: All registers except AUTO_FM/AM, A2_Threshold, and CM_Threshold are initialized during STANDARD SELECTION and are automatically updated when Automatic Sound Select (MODUS[0]=1) is on.

Table 6–2: Demodulator Read Registers; Subaddress: 11_{hex}; these registers are not writable!

Demodulator Read Registers	Address (hex)	MSP- Version	Description	Page
C_AD_BITS	00 23	4418, 4458	NICAM-Sync bit, NICAM-C-Bits, and bit[2:0] of additional data bits	86
ADD_BITS	00 38	4430	NICAM: bit[10:3] of additional data bits	86
CIB_BITS	00 3E		NICAM: CIB1 and CIB2 control bits	86
ERROR_RATE	00 57		NICAM error rate, updated with 182 ms	86

6.2. DSP Write and Read Registers for Manual Mode

Table 6–3: DSP-Write Registers; Subaddress: 12_{hex}, all registers are readable as well

Write Register	Address (hex)	Bits	Operational Modes and Adjustable Range	Reset Mode	Page
Additional Channel Matrix Modes	00 08 00 09 00 0A 00 41 00 0B 00 0C	[7:0]	[SUM/DIFF, AB_XCHANGE, PHASE_CHANGE_B, PHASE_CHANGE_A, A_ONLY, B_ONLY]	00 _{hex}	87
FM Fixed Deemphasis	00 0F	[15:8]	[50 μs, 75 μs, J17, OFF]	OFF	87
FM Adaptive Deemphasis		[7:0]	[OFF, WP1]	OFF	87
Identification Mode	00 15	[7:0]	[B/G, M]	B/G	87

Table 6-4: DSP Read Registers; Subaddress: 13_{hex}, all registers are not writable

Additional Read Registers	Address (hex)	Bits	Output Range		Page
Stereo detection register for A2 Stereo Systems	00 18	[15:8]	[80 _{hex} 7F _{hex}]	8 bit two's complement	88
DC level readout FM1/Ch2-L	00 1B	[15:0]	[8000 _{hex} 7FFF _{hex}]	16 bit two's complement	88
DC level readout FM2/Ch1-R	00 1C	[15:0]	[8000 _{hex} 7FFF _{hex}]	16 bit two's complement	88

6.3. Manual Mode: Description of Demodulator Write Registers

6.3.1. Automatic Switching between NICAM and Analog Sound

In case of bad NICAM reception or loss of the NICAM-carrier, the MSP 44x8G offers an Automatic Switching (fall back) to the analog sound (FM/AMmono), without the necessity for the controller of reading and evaluating any parameters. If a proper NICAM signal returns, switching back to this source is performed automatically as well. The feature evaluates the NICAM ERROR_RATE and switches, if necessary, all output channels which are assigned to the NICAM-source, to the analog source, and vice versa.

An appropriate hysteresis algorithm avoids oscillating effects (see Fig. 6–1). STATUS[9] and C_AD_BITS[11] (Addr: 0023 hex) provide information about the actual NICAM-FM/AM-status.

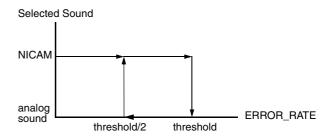


Fig. 6–1: Hysteresis for Automatic Switching

6.3.1.1. Function in Automatic Sound Select Mode

The Automatic Sound Select feature (MODUS[0]=1) includes the procedure mentioned above. By default, the internal ERROR_RATE threshold is set to $700_{\rm dec}$. i.e.:

- NICAM → analog Sound if ERROR_RATE > 700
- analog Sound → NICAM if ERROR_RATE < 700/2

The ERROR_RATE value of 700 corresponds to a BER of approximately 5.46*10⁻³ /s.

Individual configuration of the threshold can be done using Table 6–5. However, the internal setting used by the standard selection is recommended.

The optimum NICAM sound can be assigned to the MSP output channels by selecting one of the "Stereo or A/B", "Stereo or A", or "Stereo or B" source channels

6.3.1.2. Function in Manual Mode

If the manual mode (MODUS[0]=0) is required, the activation and configuration of the Automatic Switching feature has to be done as described in Table 6–6. Note, that the channel matrix of the corresponding output-channels must be set according to the NICAM-mode and need not to be changed in the FM/ AM-fallback case.

Example:

Required threshold = 500: bits[10:1] = 00 1111 1010

Table 6–5: Coding of Automatic NICAM/Analog Sound Switching;
Automatic Sound Select is on (MODUS[0] = 1)

Mode	Description	AUTO_FM [11:0] Addr. = 00 21 _{hex}	ERROR_RATE- Threshold/dec	Source Select: Input at NICAM Path ¹⁾
1 Default	Automatic Switching with internal threshold	bit[11:0] = 0	700	NICAM or FM/AM, depending on ERROR_RATE
2	Automatic Switching with external threshold (Customizing of Automatic Sound Select)	bit[11] = 0 bit[10:1] = 251000 = threshold/2 bit[0] = 1	set by customer; recommended range: 502000	
3	Forced Analog Mono	bit[11] = 1 bit[10:1] = ignored bit[0] = 1		always FM/AM

¹⁾ The NICAM path may be assigned to "Stereo or A/B", "Stereo or A", or "Stereo or B" source channels (see Table 2–2 on page 13).

Table 6–6: Coding of Automatic NICAM/Analog Sound Switching;
Automatic Sound Select is off (MODUS[0] = 0)

Mode	Description	AUTO_FM [11:0] Addr. = 00 21 _{hex}	ERROR_RATE- Threshold/dec	Source Select: Input at NICAM Path
0 reset status	Forced NICAM (Automatic Switching disabled)	bit[11] = 0 bit[10:1] = 0 bit[0] = 0	none	always NICAM; Mute in case of no NICAM available
1	Automatic Switching with internal threshold (Default, if Automatic Sound Select is on)	bit[11] = 0 bit[10:1] = 0 bit[0] = 1	700	NICAM or FM/AM, depending on ERROR_RATE
2	Automatic Switching with external threshold (Customizing of Automatic Sound Select)	bit[11] = 0 bit[10:1] = 251000 = threshold/2 bit[0] = 1	set by customer; recommended range: 502000	
3	Forced Analog Mono (Automatic Switching disabled)	bit[11] = 1 bit[10:1] = 0 bit[0] = 1	none	always FM/AM

6.3.2. A2 Threshold

The threshold between Stereo/Bilingual and Mono Identification for the A2 Standard has been made programmable according to the user's preferences.

An internal hysteresis ensures robustness and stability.

Table 6–7: Write Register on I²C Subaddress 10_{hex}: A2 Threshold

Register Address	Function	Name
THRESHOLDS		
00 22 _{hex} (write)	A2 THRESHOLD Register	A2_THRESH
	Defines threshold of all A2 and EIA_J standards for Stereo and Bilingual detection	
	bit[15:0] 07F0 _{hex} force Mono Identification	
	0190 _{hex} default setting after reset	
	00A0 _{hex} minimum Threshold for stable detection	
	recommended range: 00A0 _{hex} 03C0 _{hex}	

6.3.3. Carrier-Mute Threshold

The Carrier-Mute threshold has been made programmable according to the users preferences. An internal hysteresis ensures stable behavior.

Table 6–8: Write Register on I^2C Subaddress 10_{hex} : Carrier-Mute Threshold

Register Address	Function	Name
THRESHOLDS		
00 24 _{hex} (write)	Carrier-Mute THRESHOLD Register Defines threshold for the carrier mute feature bit[15:0] 0000 _{hex} Carrier-Mute always ON (both channels muted) 002A _{hex} default setting after reset 07FF _{hex} Carrier-Mute always OFF (both channels forced on) recommended range: 0014 _{hex} 0050 _{hex}	CM_THRESH

6.3.4. DCO-Registers

Note: The use of this register is not recommended. It should be used only in cases where non-standard carrier frequencies have to be processed. Please note, that the usage of user specific demodulation frequencies is not possible in combination with the Automatic Sound Select (MODUS[0]=1).

When selecting a TV-sound standard by means of the STANDARD SELECT register, all frequency tuning is performed automatically.

If manual setting of the tuning frequency is required, a set of 24-bit registers determining the mixing frequencies of the quadrature mixers can be written manually into the MSP. In Table 6–9, examples for DCO register programming are listed. It is necessary to separate these registers into two categories: low part and high part. The formula for the calculation of the INCR values for any chosen IF frequency is as follows:

$$INCR_{dec} = int (f / fs \cdot 2^{24})$$

with: int = integer function

f = IF frequency in MHz

 f_S = sampling frequency (18.432 MHz)

Conversion of INCR into hex-format and separation of the 12-bit low and high parts lead to the required register values (DCO1_HI and _LO for MSP-Ch1, DCO2_HI and _LO for MSP-Ch2).

6.4. Manual Mode: Description of Demodulator Read Registers

Note: Using the STANDARD SELECTION register together with the STATUS register provides a more economic way to program the MSP 44x8G and to retrieve information from the MSP.

All registers except C_AD_BITs are 8 bits wide. They can be read out of the RAM of the MSP 44x8G.

All transmissions take place in 16-bit words. The valid 8-bit data are the 8 LSBs of the received data word.

If the Automatic Sound Select feature is not used, the NICAM or FM-identification parameters must be read and evaluated by the controller in order to enable appropriate switching of the channel select matrix of the baseband processing part. The FM-identification registers are described in Section 6.6.1. To handle the NICAM-sound and to observe the NICAM-quality, at least the registers C_AD_BITS and ERROR_RATE must be read and evaluated by the controller. Additional data bits and CIB bits, if supplied by the NICAM transmitter, can be obtained by reading the registers ADD_BITS and CIB_BITS.

Table 6-9: DCO registers for the MSP 44x8G; reset status: DCO_HI/LO = "00 00"

	DCO1_LO 00 93 _{hex} , DCO1_HI 00 9B _{hex} ; DCO2_LO 00 A3 _{hex} , DCO2_HI 00 AB _{hex}									
IF-Freq. [MHz]	DCO_HI [hex]	DCO_LO [hex]	IF-Freq. [MHz]	DCO_HI [hex]	DCO_LO [hex]					
4.5	03 E8	00 00								
5.04 5.5 5.58 5.7421875	04 60 04 C6 04 D8 04 FC	00 00 03 8E 00 00 00 AA	5.76 5.85 5.94	05 00 05 14 05 28	00 00 00 00 00 00					
6.0 6.2 6.5 6.552	05 35 05 61 05 A4 05 B0	05 55 0C 71 07 1C 00 00	6.6 6.65 6.8	05 BA 05 C5 05 E7	0A AA 0C 71 01 C7					
7.02	06 18	00 00	7.2	06 40	00 00					
7.38	06 68	00 00	7.56	06 90	00 00					

6.4.1. NICAM Mode Control/Additional Data Bits Register

NICAM operation mode control bits and A[2:0] of the additional data bits.

Format:

MSB C_AD_BITS 00 23 _{hex}									
11		7	6	5	4	3	2	1	0
Auto _FM		A[2]	A[1]	A[0]	C4	C3	C2	C1	S

Important: "S" = Bit[0] indicates correct NICAM-synchronization (S = 1). If S = 0, the MSP 4418/4458G has not yet synchronized correctly to frame and sequence, or has lost synchronization. The remaining read registers are therefore not valid. The MSP mutes the NICAM output automatically and tries to synchronize again as long as any NICAM standard is selected by the STANDARD SELECT register.

The operation mode is coded by C4-C1 as shown in Table 6-10.

Table 6–10: NICAM operation modes as defined by the EBU NICAM 728 specification

C4	СЗ	C2	C1	Operation Mode
0	0	0	0	Stereo sound (NICAMA/B), independent mono sound (FM1)
0	0	0	1	Two independent mono signals (NICAMA, FM1)
0	0	1	0	Three independent mono channels (NICAMA, NICAMB, FM1)
0	0	1	1	Data transmission only; no audio
1	0	0	0	Stereo sound (NICAMA/B), FM1 carries same channel
1	0	0	1	One mono signal (NICAMA). FM1 carries same channel as NICAMA
1	0	1	0	Two independent mono channels (NICAMA, NICAMB). FM1 carries same channel as NICAMA
1	0	1	1	Data transmission only; no audio
х	1	х	х	Unimplemented sound coding option (not yet defined by EBU NICAM 728 specification)

AUTO_FM: monitor bit for the AUTO_FM Status:

0: NICAM source is NICAM

1: NICAM source is FM

Note: It is not necessary to read out and evaluate the C_AD_BITS. All evaluation is performed in the MSP and indicated in the STATUS register.

6.4.2. Additional Data Bits Register

Contains the remaining 8 of the 11 additional data bits. The additional data bits are not yet defined by the NICAM 728 system.

Format:

MSB		ADD_BITS 00 38 _{hex}						
7	6	5	4	3	2	1	0	
A[10]	A[9]	A[8]	A[7]	A[6]	A[5]	A[4]	A[3]	

6.4.3. CIB Bits Register

CIB bits 1 and 2 (see NICAM 728 specifications).

Format:

MSB		CIB_BITS 00 3E _{hex} LSE					LSB
7	6	6 5 4 3 2 1					0
х	х	х	х	х	х	CIB1	CIB2

6.4.4. NICAM Error Rate Register

ERROR_RATE	00 57 _{hex}		
Error free	0000 _{hex}		
maximum error rate	07FF _{hex}		

Average error rate of the NICAM reception in a time interval of 182 ms, which should be close to 0. The initial and maximum value of ERROR_RATE is 2047. This value is also active if no NICAM-standard is selected. Since the value is achieved by filtering, a certain transition time (approx. 0.5 sec) is unavoidable. Acceptable audio may have error rates up to a value of 700_{dec}. Individual evaluation of this value by the controller and an appropriate threshold may define the fallback mode from NICAM to FM/AM-Mono in case of poor NICAM reception.

The bit error rate per second (BER) can be calculated by means of the following formula:

BER = ERROR RATE * $12.3*10^{-6}$ /s

6.5. Manual Mode: Description of DSP Write Registers

6.5.1. Additional Channel Matrix Modes

Main Matrix	00 08 _{hex}	L
Aux Matrix	00 09 _{hex}	L
SCART1 Matrix	00 0A _{hex}	L
SCART2 Matrix	00 41 _{hex}	L
I ² S Matrix	00 0B _{hex}	L
Quasi-Peak Detector Matrix	00 0C _{hex}	L
Mix1	00 38 _{hex}	L
Mix2	00 38 _{hex}	L
I2S4 Async Output	00 46 _{hex}	L
SUM/DIFF	0100 0000	40 _{hex}
AB_XCHANGE	0101 0000	50 _{hex}
PHASE_CHANGE_B	0110 0000	60 _{hex}
PHASE_CHANGE_A	0111 0000	70 _{hex}
A_ONLY	1000 0000	80 _{hex}
B_ONLY	1001 0000	90 _{hex}

This table shows additional modes for the channel matrix registers.

The sum/difference mode can be used together with the quasi-peak detector to determine the sound material mode. If the difference signal on channel B (right) is near to zero, and the sum signal on channel A (left) is high, the incoming audio signal is mono. If there is a significant level on the difference signal, the incoming audio is stereo.

6.5.2. FM Fixed Deemphasis

FM Deemphasis	00 0F _{hex}	Н
50 μs	0000 0000 RESET	00 _{hex}
75 μs	0000 0001	01 _{hex}
J17	0000 0100	04 _{hex}
OFF	0011 1111	3F _{hex}

Note: This register is initialized during STANDARD SELECTION and is automatically updated when Automatic Sound Select (MODUS[0]=1) is on.

6.5.3. FM Adaptive Deemphasis

FM Adaptive Deemphasis WP1	00 0F _{hex}	L
OFF	0000 0000 RESET	00 _{hex}
WP1	0011 1111	3F _{hex}

Note: This register is initialized during STANDARD SELECTION and is automatically updated when Automatic Sound Select (MODUS[0]=1) is on.

6.5.4. NICAM Deemphasis

A J17 Deemphasis is always applied to the NICAM signal. It is not switchable.

6.5.5. Identification Mode for A2 Stereo Systems

Identification Mode	00 15 _{hex}	L
Standard B/G (German Stereo)	0000 0000 RESET	00 _{hex}
Standard M (Korean Stereo)	0000 0001	01 _{hex}
Reset of Ident-Filter	0011 1111	3F _{hex}

To shorten the response time of the identification algorithm after a program change between two FM-Stereo capable programs, the reset of the ident-filter can be applied.

Sequence:

- 1. Program change
- 2. Reset ident-filter
- 3. Set identification mode back to standard B/G or M
- 4. Wait approx. 500 ms
- 5. Read stereo detection register

Note: This register is initialized during STANDARD SELECTION and is automatically updated when Automatic Sound Select (MODUS[0]=1) is on.

6.6. Manual Mode: Description of DSP Read Registers

All readable registers are 16-bit wide. Transmissions via I²C bus have to take place in 16-bit words. Some of the defined 16-bit words are divided into low and high byte, thus holding two different control entities.

These registers are not writable.

6.6.1. Stereo Detection Register for A2 Stereo Systems

Stereo Detection Register	00 18 _{hex} H			
Stereo Mode	Reading (two's complement)			
MONO	near zero			
STEREO	positive value (ideal reception: 7F _{hex})			
BILINGUAL	negative value (ideal reception: 80 _{hex)}			

Note: It is not necessary to read out and evaluate the A2 identification level. All evaluation is performed in the MSP and indicated in the STATUS register.

6.6.2. DC Level Register

DC Level Readout FM1 (MSP-Ch2)	00 1B _{hex} H+L
DC Level Readout FM2 (MSP-Ch1)	00 1C _{hex} H+L
DC Level	[8000 _{hex} 7FFF _{hex}] values are 16 bit two's complement

The DC level register measures the DC component of the incoming FM signals (FM1 and FM2). This can be used for seek functions in satellite receivers and for IF FM frequencies fine tuning. If the DCO frequency is lower than the actuel carrier frequency, the resulting DC level will be positive, an dvia versa. In the audio signal the DC content is suppressed. The time constant τ , defining the transition time of the DC Level Register, is approximately 28 ms.

6.7. Demodulator Source Channels in Manual Mode

6.7.1. Terrestrial Sound Standards

Table 6–11 shows the source channel assignment of the demodulated signals in case of manual mode for all terrestrial sound standards. See Table 2–2 for the assignment in the Automatic Sound Select mode. In manual mode for terrestrial sound standards, only two demodulator sources are defined.

6.7.2. SAT Sound Standards

Table 6–12 shows the source channel assignment of the demodulated signals for SAT sound standards.

Table 6-11: Manual Sound Select Mode for Terrestrial Sound Standards

Source Channels of Sound Select Bloo						
Broadcasted Sound Standard	Selected MSP Standard Code	Broadcasted Sound Mode	FM Matrix	FM/AM (use 0 for channel select)	Stereo or A/B (use 1 for channel select)	
B/G-FM	03	MONO	Sound A Mono	Mono	Mono	
D/K-FM M-Korea M-Japan	04, 05 02 30	STEREO	German Stereo Korean Stereo	Stereo	Stereo	
		BILINGUAL, Languages A and B	No Matrix	Left = A Right = B	Left = A Right = B	
B/G-NICAM L-NICAM I-NICAM D/K-NICAM	08 09 0A 0B 0C, 0D	NICAM not available or NICAM error rate too high	Sound A Mono ¹⁾	analog Mono	no sound with AUTO_FM: analog Mono	
D/K-NICAM (with high		MONO	Sound A Mono ¹⁾	analog Mono	NICAM Mono	
deviation FM)		STEREO	Sound A Mono ¹⁾	analog Mono	NICAM Stereo	
		BILINGUAL, Languages A and B	Sound A Mono ¹⁾	analog Mono	Left = NICAM A Right = NICAM B	
	20	MONO	Sound A Mono	Mono	Mono	
		STEREO	Korean Stereo	Stereo	Stereo	
		MONO + SAP	Sound A Mono	Mono	Mono	
BTSC		STEREO + SAP	Korean Stereo	Stereo	Stereo	
D100	21	MONO	Sound A Mono	Mono	Mono	
		STEREO	Count / Wione	Wiorio	IVIOLIO	
		MONO + SAP	No Matrix	Left = Mono	Left = Mono	
		STEREO + SAP	140 Manix	Right = SAP	Right = SAP	
FM-Radio	40	MONO	Sound A Mono	Mono	Mono	
i ivi-i iaulu	70	STEREO	Korean Stereo	Stereo	Stereo	
1) Automatic ref	resh to Sound A M	lono, do not write any ot	her value to the reg	ister FM Matrix!		

Table 6–12: Manual Sound Select Modes for SAT-reception (FM Matrix is set automatically)

				Source Channels of Sound Select Block for SAT-Modes			
Broadcasted Sound Standard	Selected MSP Standard Code	Broadcasted Sound Mode	FM Matrix	FM/AM (source select: 0)	Stereo or A/B (source select: 1)	Stereo or A (source select: 3)	Stereo or B (source select: 4)
FM SAT	6, 50 _{hex}	MONO	Sound A Mono	Mono	Mono	Mono	Mono
	51 _{hex}	STEREO	No Matrix	Stereo	Stereo	Stereo	Stereo
		BILINGUAL	No Matrix	Left = A (FM1) Right = B (FM2)	Left = A (FM1) Right = B (FM2)	A (FM1)	B (FM2)

7. Appendix C: Application Information

7.1. Exclusions of Audio Baseband Features

In general, all functions can be switched independently. Two exceptions exist:

- 1. NICAM cannot be processed simultaneously with secondary channel (see Fig. 2–3 and Fig. 2–2 on page 12).
- 2. FM adaptive deemphasis cannot be processed simultaneously with FM-identification.

7.2. Phase Relationship of Analog Outputs

The analog output signals: Main, Aux, and SCART2 all have the same phases. The SCART1 output has opposite phase.

Using the I²S-outputs for other DSPs or D/A converters, care must be taken to adjust for the correct phase.

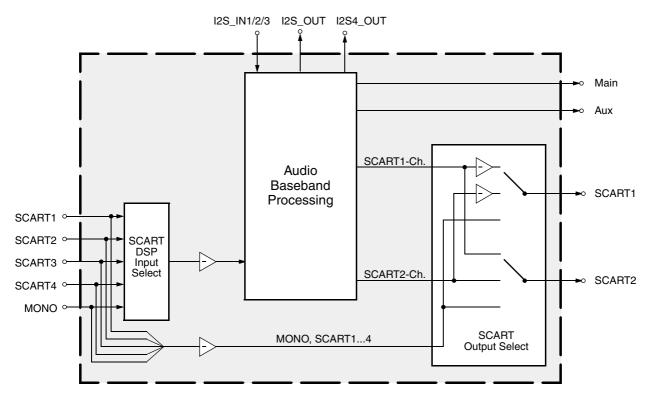
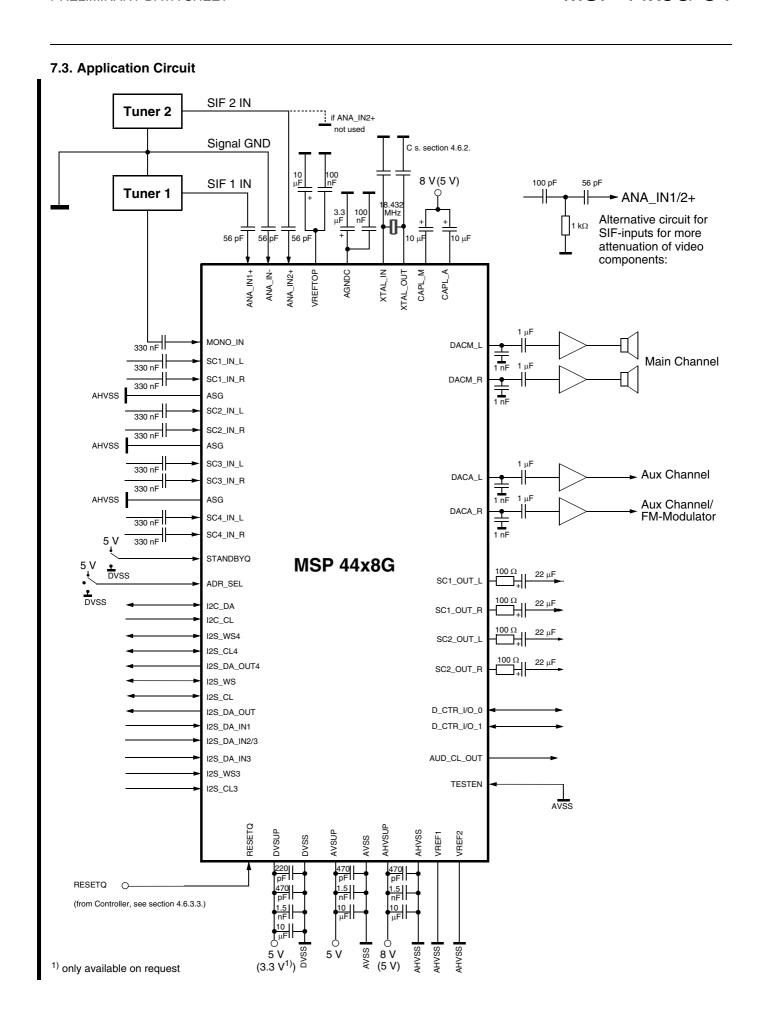


Fig. 7-1: Phase diagram of the MSP 44x8G



8. Appendix D: MSP 44x8G Version History

MSP 44x8G-A1

First release

MSP 44x8G-A2

- J17 FM-deemphasis implemented
- input specification for RESETQ and TESTEN changed

MSP 44x8G-B3

- The Automatic Sound Select (ASS) malfunction has been corrected. In the previous version, under certain circumstances and depending on the processor load, e.g.: use of the asynchronous I²S3 interface, the Automatic Sound Select Feature (ASS) did not work correctly.
- correction of 10 μs delay between Left and Right: In case of any Stereo output from the demodulator (FM/AM, ST or A/B) there was a constant time delay of 10 μs between Left and Right channel in the A1 and A2 versions.
- correction of default Scart-Switch configuration during power-up
- correction of unstable sound mode detection when the MSP reaches a specific higher case temperature (occurs only in EIA-J standard)
- correction of I²S output interface

MSP 44x8G-C4

- asynchronous I²S output interface and related control interfaces implemented
- Astra Digital Radio (ADR) no longer supported
- 3.3 V mode for DVSUP2 available on request
- Audio/Video Synchronization is only available if I²S4 sample length I2S4_WLEN is set to 32 bit per sample.

9. Data Sheet History

- 1. Data Sheet: "MSP 44x8G Multistandard Sound Processor Family", June 16, 2003, 6251-516-1DS. First release of the data sheet. Major changes:
- specification for version B3 added
- Section 4.1.: diagrams for all packages changed
- PLQFP64 changed to PMQFP64-2
- Preliminary Data Sheet: "MSP 44x8G-C4 Multistandard Sound Processor Family", March 29, 2004, 6251-623-1PD. First release of the preliminary data sheet. Major changes:
- new order no. for version C4
- specification for version C4 added

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