

8-Bit Up/Down Counter

74ACT469A

Feature/Benefits

- Direct CMOS replacement of Monolithic Memories' SN74LS469A
- Zero standby power
- 8-bit up/down counter for microprogram-counter, DMA-controller and general-purpose counting applications
- 8 bits match byte boundaries
- Bus-structured pinout
- 24-pin SKINNYDIP® saves space
- Three-state outputs drive bus lines
- Expandable in 8-bit increments

Description

The 'ACT469A is an 8-bit synchronous up/down counter with parallel load and hold capability. Three function-select inputs (LD, UD, CBI) provide one of four operations which occur synchronously on the rising edge of the clock (CK).

The LOAD operation loads the inputs (D7-D0) into the output register (Q7-Q0). The HOLD operation holds the previous value regardless of clock transitions. The INCREMENT operation adds one to the output register when the carry-in input is TRUE (CBI = LOW), and the up/down control line (UD) is LOW, otherwise the operation is a HOLD. The carry-out (CBO) is TRUE (CBO = LOW) when the output register (Q7-Q0) is all HIGHs, otherwise FALSE (CBO = HIGH). The DECREMENT operation subtracts one from the output register when the borrow-in input is TRUE (CBI = LOW), and the up/down control line (UD) is HIGH, otherwise the operation is a HOLD. The borrow-out (CBO) is TRUE (CBO = LOW) when the output register (Q7-Q0) is all LOWs, otherwise FALSE (CBO = HIGH).

The data output pins are enabled when \overline{OE} is LOW, and disabled (HI-Z) when \overline{OE} is HIGH. The output drivers will sink the 24 mA required for many bus-interface standards. Two or more 'LS469A 8-bit up/down counters may be cascaded to provide larger counters.

Function Table

\overline{OE}	CK	LD	UD	CBI	D7-D0	Q7-Q0	OPERATION
H	*	*	*	*	*	Z	HI-Z*
L	1	L	X	X	D	D	LOAD
L	1	H	L	H	X	Q	HOLD
L	1	H	L	L	X	Q plus 1	INCREMENT
L	1	H	H	H	X	Q	HOLD
L	1	H	H	L	X	Q minus 1	DECREMENT

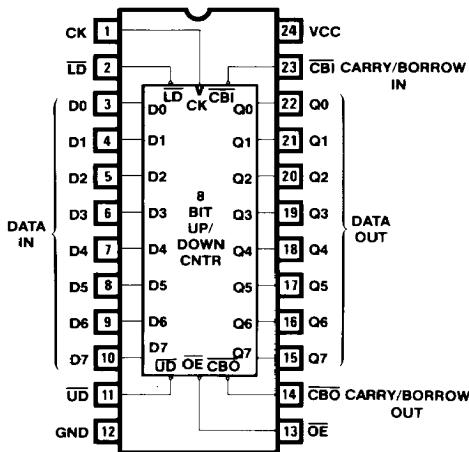
* When \overline{OE} is HIGH, the three-state outputs are disabled to the high-impedance state; however, sequential operation of the counter is not affected.

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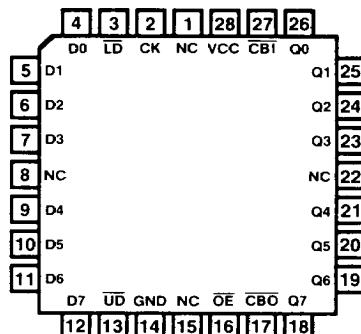
Ordering Information

PART NUMBER	PACKAGE	TEMPERATURE
74ACT469A	NS, JS, FN (28)	Com

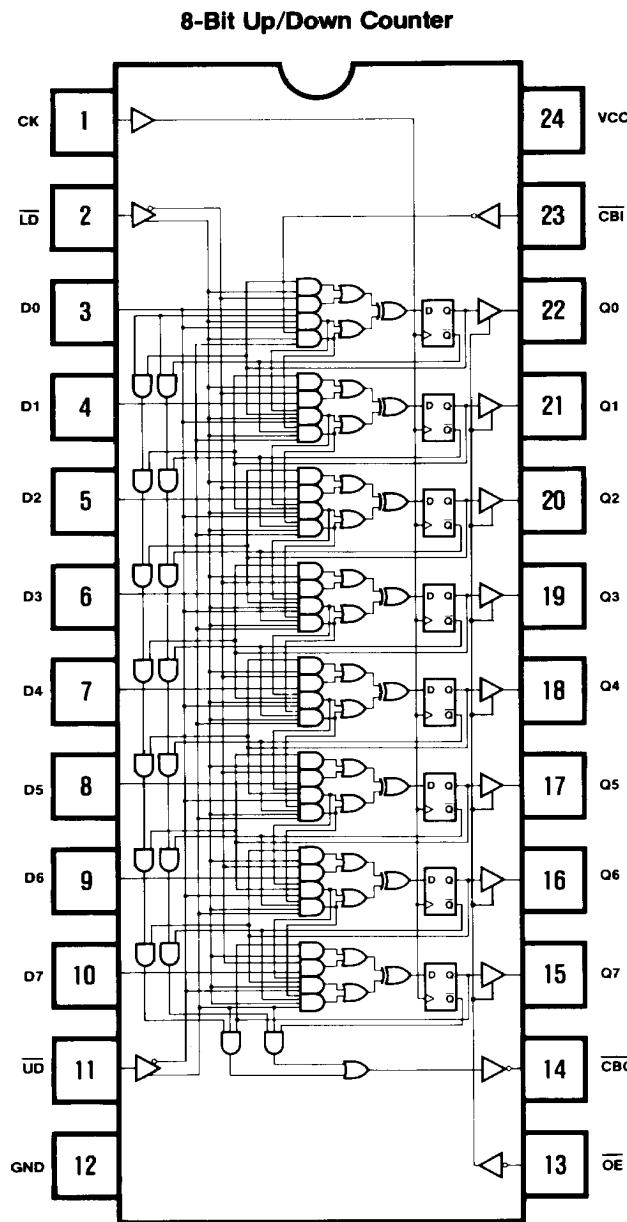
Logic Symbols



SKINNYDIP Package



Plastic Leaded Chip Carrier

Logic Diagram

Operating Conditions

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
V _{CC}	Supply voltage	4.75	5	5.25	V
t _w	Width of clock	15	5		ns
t _{su}	Setup time from input to clock	30	15		ns
t _h	Hold time	0	-10		ns
T _A	Operating free-air temperature	0	25	75	°C

Electrical Characteristics Over Operating Conditions

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{IL} ²	Low-level input voltage		0	0.8		V
V _{IH} ²	High-level input voltage		2	V _{CC}		V
I _{IL}	Low-level input current	V _{CC} = MAX V _I = GND		-1		μA
I _{IH}	High-level input current Pin 10 ³	V _{CC} = MAX V _I = V _{CC}		8	30	μA
					1	μA
V _{OL}	Low-level output voltage	V _{CC} = MIN I _{OL} = 8 mA	0.1	0.4		V
		V _{CC} = 5 V I _{OL} = 1 μA			0.05	
V _{OH}	High-level output voltage	V _{CC} = MIN I _{OH} = -6 mA	3.76 ⁴	4.1		V
		V _{CC} = 5 V I _{OH} = -1 μA	4.95			
I _{OZL} ⁵	Off-state output current	V _O = GND	0	-10		μA
			V _O = V _{CC}	0	10	μA
I _{CC}	Standby supply current ⁶	I _O = 0 mA, V _I = GND or V _{CC}	0	100		μA
	Operating supply current	f = 1 MHz, I _O = 0 mA, V _I = GND or V _{CC}	2	5 ⁷		mA

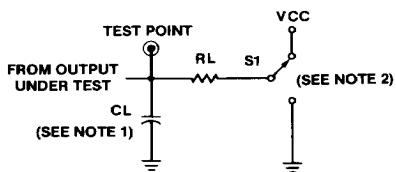
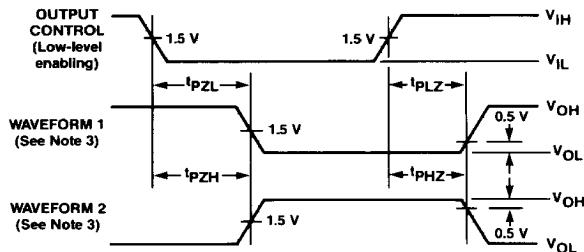
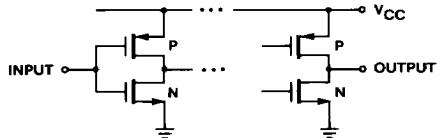
Switching Characteristics Over Operating Conditions

SYMBOL	PARAMETER	TEST CONDITIONS (See test Load/Waveforms)	MIN	TYP	MAX	UNIT
t _{MAX}	Maximum clock frequency ¹		23			MHz
t _{CLK}	Clock to Q	R _L = 1KΩ C _L = 50 pF	12	15		ns
t _{PZX}	Output enable delay			15	20	ns
t _{PXZ}	Output disable delay	R _L = 1K C _L = 5 pF	15	20		ns

- Notes:
1. t_{MAX} is derived from: 1/MAX [(t_{su} + t_h), t_w (Low) + t_w (High), t_{CLK}].
 2. These are absolute voltages with respect to the ground pin on the device and include all overshoots due to system and/or tester noise. Do not attempt to test these values without suitable equipment.
 3. Pin 10 DIP, Pin 12 PLCC.
 4. JEDEC standard no. 7 for high-speed CMOS devices.
 5. Applies to pins 14-23 for DIP.
 6. Disable output pins = V_{CC} or GND.
 7. Add 3 mA per additional 1.0 MHz of operation over 1 MHz.

Absolute Maximum Ratings

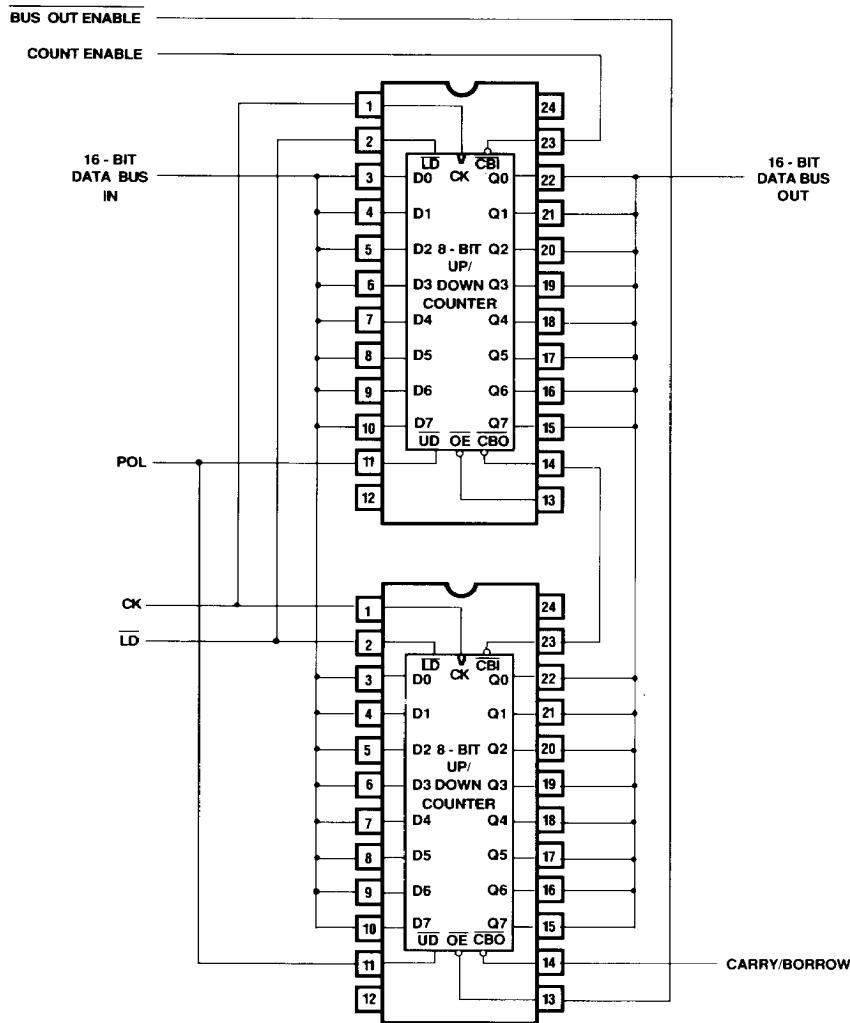
Supply voltage, V_{CC}	-0.5 V to 7.0 V
DC input voltage, V_I	-0.5 V to V_{CC} +0.5 V
DC output voltage, V_O	-0.5 V to V_{CC} +0.5 V
DC output source/sink current per output pin, I_O	±35 mA
DC V_{CC} or ground current, I_{CC} or I_{GND}	±100 mA
Input diode current, I_{IK} :	
$V_I < 0$	-20 mA
$V_I > V_{CC}$	+20 mA
Output diode current, I_{OK} :	
$V_O < 0$	-20 mA
$V_O > V_{CC}$	+20 mA
Storage temperature	-65°C to +150°C

Switching Test Load**Enable/Disable Delay****Schematic of Inputs and Outputs**

- Notes:
1. C_L includes probe and jig capacitance.
 2. When measuring t_{PLZ} and t_{PZL} , S1 is tied to V_{CC} . When measuring t_{PHZ} and t_{PZH} , S1 is tied to ground. t_{PZX} is measured with $C_L = 50 \text{ pF}$. t_{PXZ} is measured with $C_L = 5 \text{ pF}$. When measuring propagation delay times of three-state outputs, S1 is open, i.e., not connected to V_{CC} or ground.
 3. Waveform 1 is for an output with internal conditions such that the output is LOW except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is HIGH except when disabled by the output control.

Application

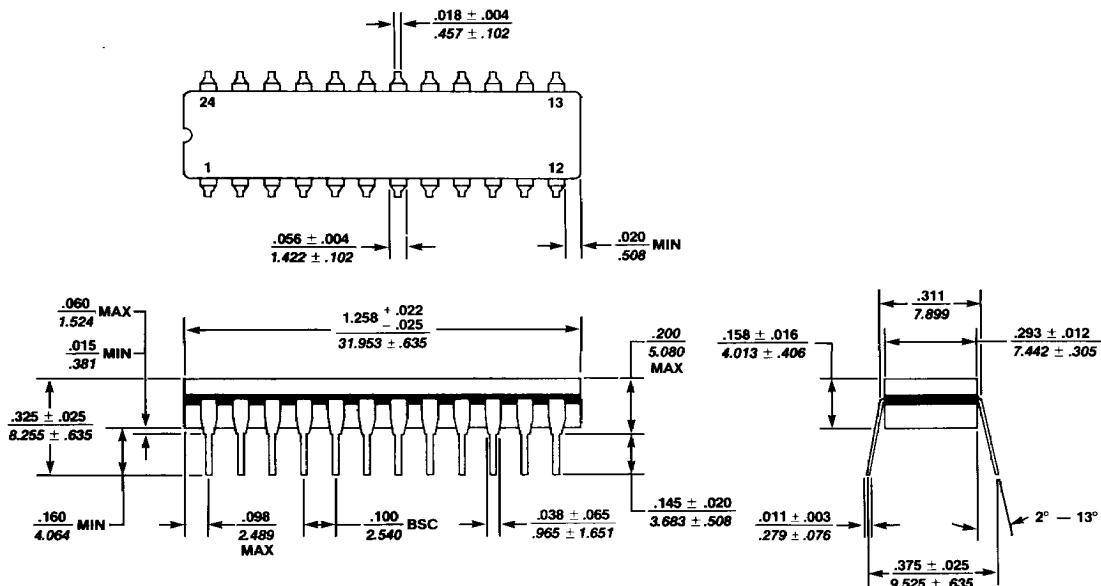
16-Bit Up/Down Counter



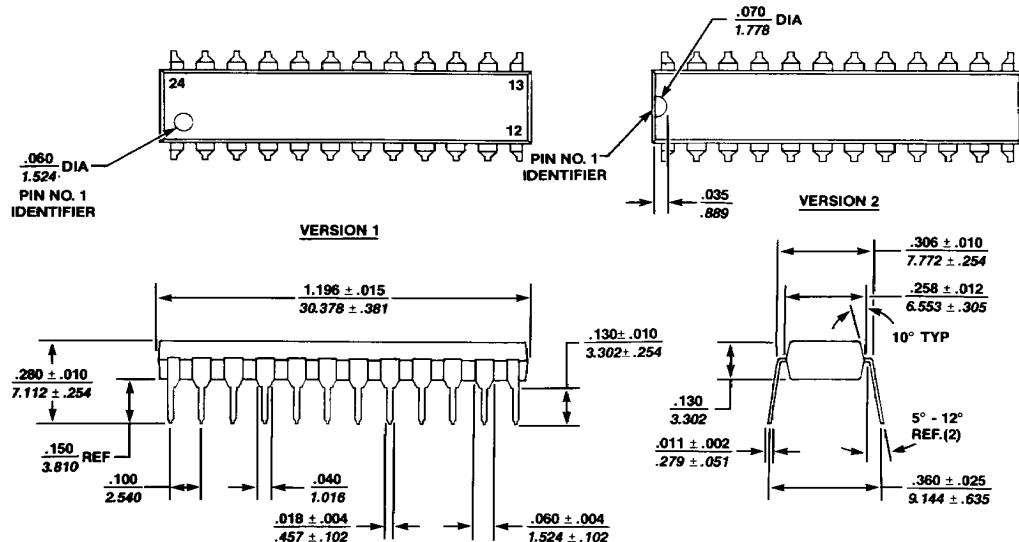
$$\text{NOTE } f_{\text{MAX}} = \frac{1}{t_{\text{PD CLK TO CO}} + t_{\text{SU}}}$$

Package Drawings

24JS Ceramic SKINNYDIP



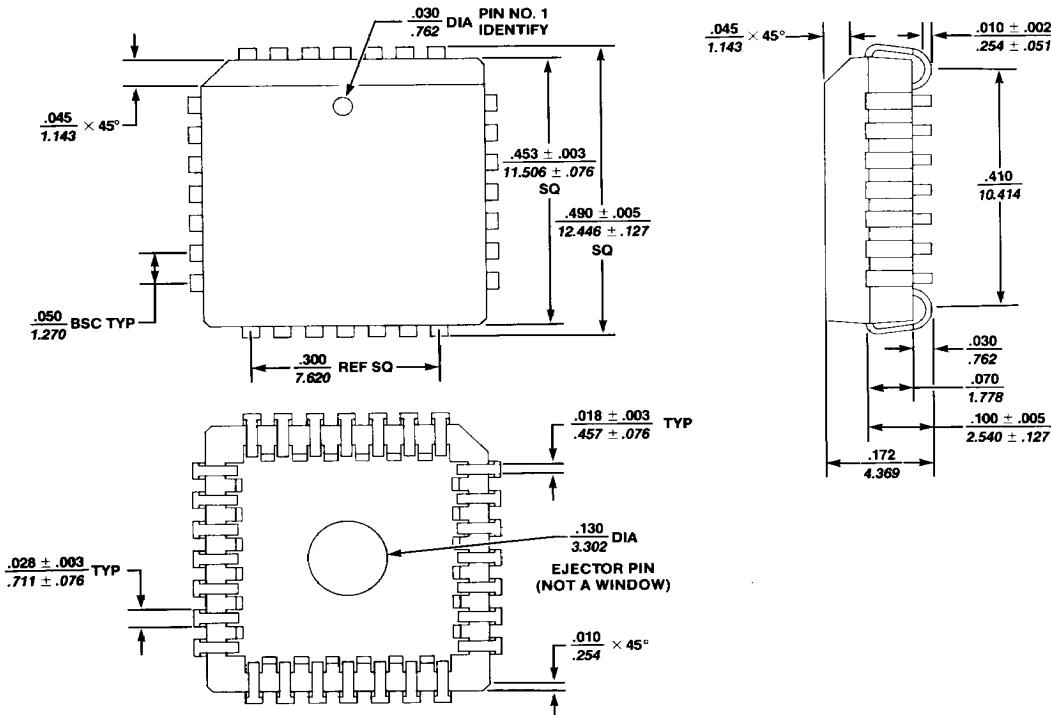
24NS Molded SKINNYDIP



UNLESS OTHERWISE SPECIFIED:
 ALL DIMENSIONS MIN-MAX. IN INCHES
 ALL DIMENSIONS MIN-MAX. IN MILLIMETERS
 ALL TOLERANCES ARE $\pm .007$ INCHES

Package Drawings

28NL/FN Plastic Leaded Chip Carrier
(.451" x .451")



UNLESS OTHERWISE SPECIFIED:
ALL DIMENSIONS MIN.-MAX. IN INCHES
ALL DIMENSIONS MIN.-MAX. IN MILLIMETERS
ALL TOLERANCES ARE $\pm .007$ INCHES

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