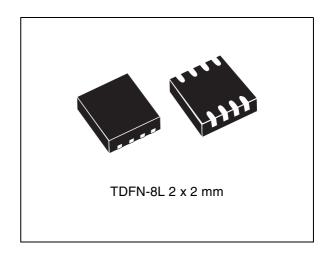


STM6513

Smart reset

Features

- Operating voltage 1.0 V (active-low output valid) to 5.5 V
- Low supply current 3 µA (typ.)
- Factory-programmable thresholds to monitor
 V_{CC} in the range of 1.575 to 4.625 V typ.
- Dual reset output
 - RST1 active-high, push-pull
 - RST2 active-low, open-drain
- Two smart reset push-button inputs with userprogrammable extended reset set up delay (by three-state input logic)
- User-programmable output reset pulse duration (t_{REC1}) by external capacitor C_{tREC}
- Power-on reset
- Operating temperature: industrial grade –40 °C to +85 °C
- Package: TDFN-8L 2 x 2 x 0.75 mm, 0.5 mm pitch
- RoHS compliant



Applications

- MP3 players
- Portable navigation devices
- Mobile phones
- Any application that requires delayed reset push-button(s) response for improved system stability.

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STM6513 Description

1 Description

1.1 Smart reset devices

The smart reset device family STM65xx provides a useful feature that ensures inadvertent short reset push-button closures do not cause system resets. This is done by implementing extended smart reset input delay periods (t_{SRC}). Hence, when valid smart reset input conditions and set up periods are met, the reset outputs will generate a pulse with user-programmable timeout period (t_{REC}).

The typical application hookup shows that the dual smart reset inputs can be also connected to the applications interrupt to allow the control of both the interrupt pin and the hard reset functions. If the push-buttons are closed for a short time, the processor is only interrupted. If the system still does not respond properly, holding the push-buttons for the extended set up time (t_{SRC}) causes hard reset of the processor through the reset outputs. The smart reset feature helps significantly increase system stability.

The STM65xx family of smart reset devices consists of low current microprocessor reset circuits targeted e.g. at MP3 players, portable navigation or mobile phones; generally any application that requires delayed reset push-button(s) response for improved system stability. The STM65xx devices feature single or dual smart reset inputs (SRx). The delayed smart reset set up time (t_{SRC}) options of 0 s, 2 s, 6 s and 10 s (all min.) are adjustable by an external capacitor or resistor on the SRC pin or selectable by three-state logic. The delayed set up period ignores switch closures shorter than t_{SRC} , thus preventing unwanted resets.

The STM65xx devices have active-low (optionally active-high) open-drain reset (RST) output(s) with or without internal pull-up resistor or push-pull as output options, with power-on reset function.

The reset output is also asserted when the monitored supply voltage V_{CC} drops below the specified threshold. The reset output remains asserted for the reset timeout period (t_{REC}) after the monitored supply voltage goes above the specified threshold.

1.2 STM6513

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The STM6513 has two separate delayed smart reset inputs ($\overline{SR0}$, $\overline{SR1}$) which when taken low simultaneously provide three user-selectable delayed smart reset set up time (t_{SRC}) options of 2 s, 6 s and 10 s. These are selected through a three-state TSR input pin: when connected to ground, $t_{SRC}=2$ s; when left open, $t_{SRC}=6$ s; when connected to V_{CC} , $t_{SRC}=10$ s (all the times are minimum). There are two reset outputs, both going active simultaneously after both the smart reset inputs were held active for the selected t_{SRC} delay time. The first reset output, RST1, is active-high, push-pull; the second reset output, $\overline{RST2}$, is active-low, open-drain requiring an external pull-up resistor to V_{CC} . The duration of the output reset pulses is independently programmable: t_{REC1} is user-programmable (by external capacitor C_{tREC}), t_{REC2} is factory-programmed to 210 ms (typ.), with the option of 360 ms typ. Additionally, the V_{CC} is monitored and if it drops below the selected V_{RST} threshold, both the reset outputs go active and remain so while V_{CC} is below the V_{RST} threshold, plus the defined duration of the reset pulse t_{REC} on each output.

Description STM6513

Figure 1. Logic diagram

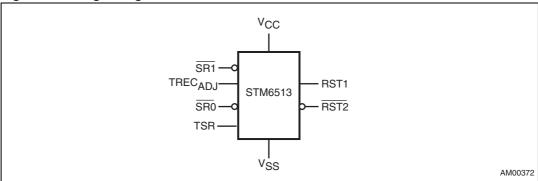
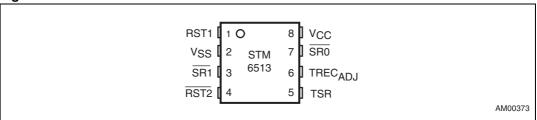


Figure 2. Pin connections



STM6513 Device overview

2 Device overview

Table 1. Signal names

| Symbol | Input/output | Description |
|---------------------|-------------------|--|
| RST1 | Output | First reset output, active-high, push-pull. |
| RST2 | Output | Second reset output, active-low, open-drain. |
| SR0 | Input | Primary push-button smart reset input. Active-low. |
| SR1 | Input | Secondary push-button smart reset input. Active-low. |
| TSR | Input | A Three-state smart reset input delay set up control. When connected to ground, $t_{SRC}=2$ s; when left open, $t_{SRC}=6$ s; when connected to V_{CC} , $t_{SRC}=10$ s (all times are minimum). TSR is a DC-type input, intended to be either permanently grounded, permanently connected to V_{CC} or permanently left open. |
| TREC _{ADJ} | Input | Input pin for t_{REC1} reset pulse duration adjustment. Connect an external capacitor C_{tREC} to this pin to determine t_{REC1} ; t_{REC2} is factory-programmed. |
| V _{CC} | Supply voltage | Positive supply voltage input. Power supply for the device and an input for the monitored supply voltage. A 0.1 μF decoupling ceramic capacitor is recommended to be connected between V_{CC} and V_{SS} pins. |
| V _{SS} | Supply ground | Ground |

Pin descriptions STM6513

3 Pin descriptions

3.1 Power supply (V_{CC})

This pin is used to provide the power to the smart reset device and to monitor the power supply. A 0.1 μ F decoupling ceramic capacitor is recommended to be connected between V_{CC} and V_{SS} pins.

3.2 Ground (V_{SS})

This is the ground for the device and all supplies.

3.3 Smart reset inputs ($\overline{SR0}$, $\overline{SR1}$)

Push-button smart reset inputs. Both inputs need to be held active at the same time for at least t_{SRC} to activate the reset outputs.

3.4 User-programmable smart reset delay (TSR pin)

Used to allow the user to program the set up time before the push-buttons action is validated by reset output. Controlled by different voltage levels on the TSR pin: when connected to ground, $t_{SRC} = 2$ s; when left open, $t_{SRC} = 6$ s; when connected to V_{CC} , $t_{SRC} = 10$ s (all times are minimum). TSR is a DC-type input, intended to be either permanently grounded, permanently connected to V_{CC} or permanently left open.

3.5 Reset outputs (RST1, RST2)

Reset outputs, RST1 active-high, push-pull type, RST2 active-low, open-drain.

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3.6 Adjustable output reset timeout period input pin (TREC_{ADJ})

The output reset timeout period (t_{REC1}) on RST1 is adjustable by connecting an external capacitor C_{tREC} to this pin. The relation between t_{REC1} and C_{tREC} is the following:

STM6513 Pin descriptions

Device option with $t_{\mbox{\scriptsize REC1}}$ programmed by external capacitor, most common $t_{\mbox{\scriptsize REC}}$ values selected:

Table 2. t_{REC1} vs. C_{tREC} relation

| C _{tREC} value (μF) | | Closest common | | |
|------------------------------|------|----------------|------|------------------------------|
| OtREC Value (pi) | Min. | Тур. | Max. | C _{tREC} value (µF) |
| 0 | 0.1 | 0.15 | 0.2 | _ |
| 0.002 | 20 | 30 | 40 | 0.0022 |
| 0.01 | 100 | 150 | 200 | 0.01 |
| 0.014 | 140 | 210 | 280 | 0.015 |
| 0.028 | 280 | 420 | 560 | 0.027 |
| 0.056 | 560 | 840 | 1120 | 0.056 |
| 0.112 | 1120 | 1680 | 2240 | 0.12 |

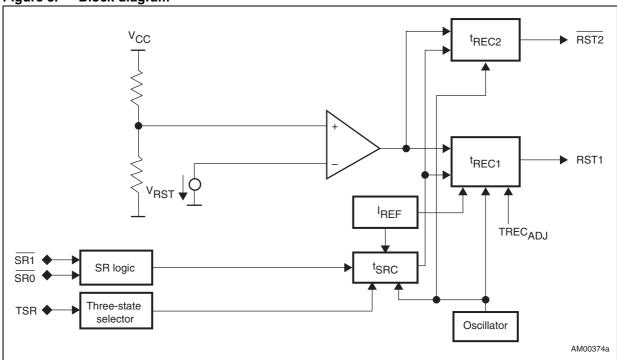
 $t_{REC1~min.} \approx~10~000~x~C_{tREC}~(ms,~\mu\text{F}).$

- Note: 1 In case of quickly repeated activations of the internal t_{REC} counter, an interval of 10 ms min. is needed between t_{REC} intervals to fully discharge C_{tREC} , so that the next t_{REC1} is as specified.
 - 2 It should be considered during application design and component selection that the current flowing into the external t_{REC} programming component (C_{tREC}) is in the order of 100 nA, therefore a low-leakage capacitor and PCB environment should be used to prevent t_{REC} accuracy from being affected.

Block diagram STM6513

4 Block diagram





STM6513 Block diagram

STM6513 hookup with RST1 and $\overline{RST2}$, bridging the PS_hold reset pulse during the microprocessor reset initiated by the STM6513 smart reset device:

Figure 4. Typical application diagram

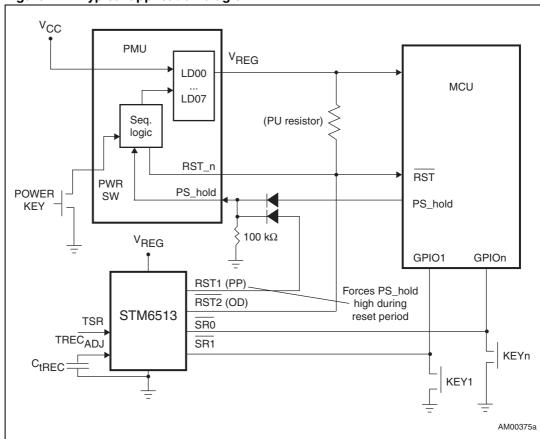
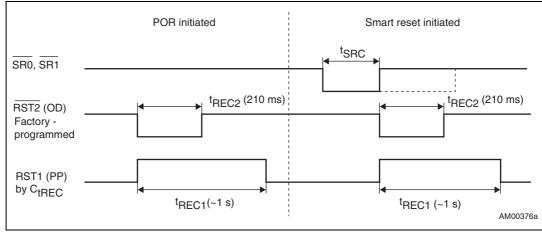
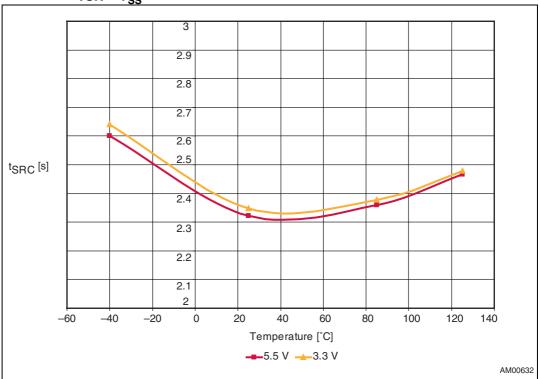


Figure 5. Timing waveforms



5 Typical operating characteristics

Figure 6. Smart reset delay t_{SRC} vs. temperature and supply voltage V_{CC} , $TSR = V_{SS}$



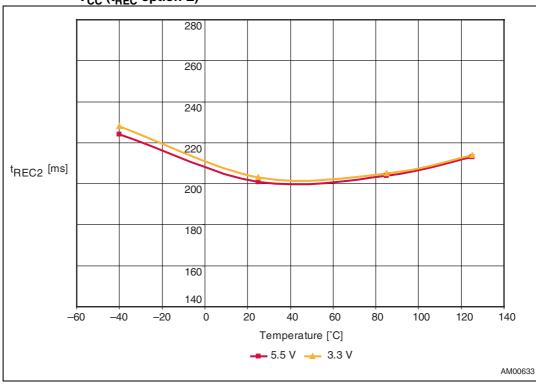


Figure 7. Output reset timeout period t_{REC2} vs. temperature and supply voltage V_{CC} (t_{REC} option E)



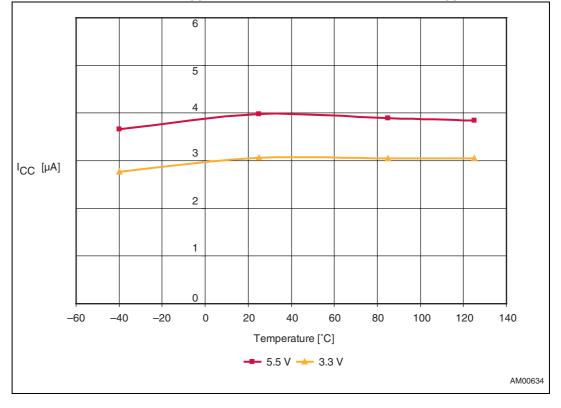


Figure 9. Reset voltage V_{RST} (falling) vs. temperature (threshold option S, 2.925 V typ.)

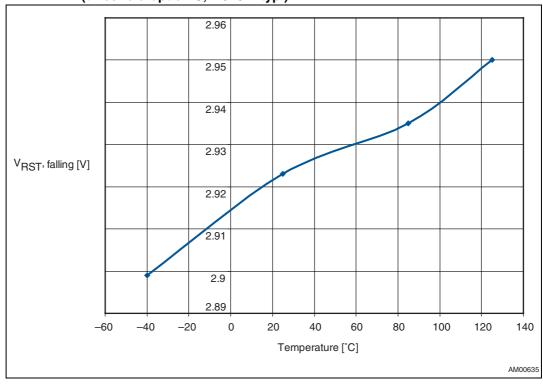
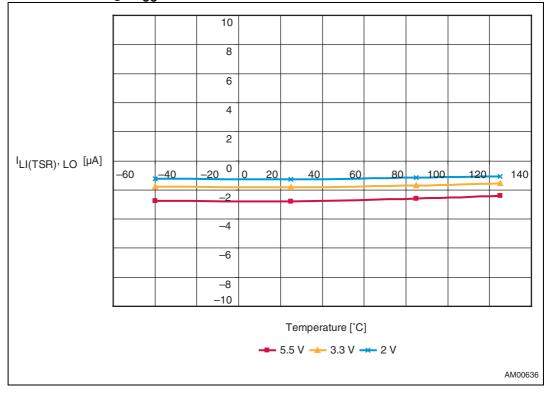


Figure 10. Input leakage current, TSR pin, logic low vs. temperature and supply voltage V_{CC}



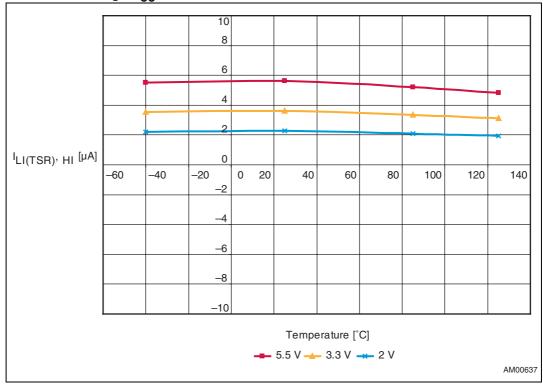


Figure 11. Input leakage current, TSR pin, logic high vs. temperature and supply voltage V_{CC}

Maximum rating STM6513

6 Maximum rating

Stressing the device above the rating listed in the *Table 3: Absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics SURE Program and other relevant quality documents.

Table 3. Absolute maximum ratings

| Symbol | Parameter | | Value | Unit |
|---------------------------------|---|-------------|------------------------------|------|
| T _{STG} | Storage temperature (V _{CC} off) | -55 to +150 | °C | |
| T _{SLD} ⁽¹⁾ | Lead solder temperature for 10 seconds | 260 | °C | |
| θ_{JA} | Thermal resistance (junction to ambient) | 149.0 | °C/W | |
| V _{IO} | Input or output voltage | | -0.3 to V _{CC} +0.3 | ٧ |
| V _{CC} | Supply voltage | | –0.3 to 7 | V |

^{1.} Reflow at peak temperature of 260 °C. The time above 255 °C must not exceed 30 s.

7 DC and AC parameters

This section summarizes the operating measurement conditions, and the DC and AC characteristics of the device. The parameters in the *Table 5: DC and AC characteristics* that follow, are derived from tests performed under the Measurement Conditions summarized in *Table 4.: Operating and measurement conditions*. Designers should check that the operating conditions in their circuit match the operating conditions when relying on the quoted parameters.

Table 4. Operating and measurement conditions

| Parameter | Value | Unit |
|---|----------------------------|------|
| V _{CC} supply voltage | 1.0 to 5.5 | V |
| Ambient operating temperature (T _A) | -40 to +85 | °C |
| Input rise and fall times | ≤ 5 | ns |
| Input pulse voltages | 0.2 to 0.8 V _{CC} | V |
| Input and output timing ref. voltages | 0.3 to 0.7 V _{CC} | V |

Figure 12. AC testing input/output waveforms

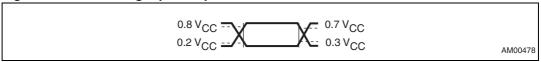


Table 5. DC and AC characteristics

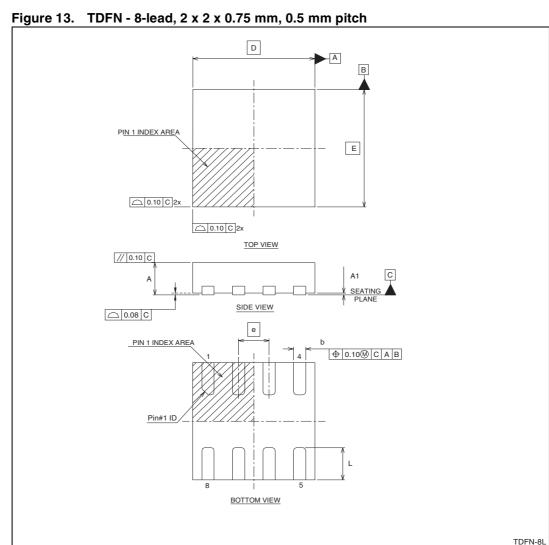
| Symbol | Parameter | Test conditions ⁽¹⁾ | Min. | Тур. | Max. | Units |
|----------------------|---|---|---------------------------|------------------|---------------------------|-------|
| M | O | Reset output valid - active-low | 1.0 | | 5.5 | V |
| V _{CC} | Supply voltage range | Reset output valid - active-high | 1.2 | | 5.5 | V |
| | Cumply ourrent ()/ | V _{CC} = 3.0 V | | 3 | 5 | μΑ |
| I _{CC} | Supply current (V _{CC}) | V _{CC} = 5.0 V | | 4 | 6 | μΑ |
| | | V _{CC} ≥ 4.5 V, sinking 3.2 mA | | | 0.3 | V |
| V _{OL} | Reset output voltage low | V _{CC} ≥ 3.3 V, sinking 2.5 mA | | | 0.3 | V |
| | | V _{CC} ≥ 1.0 V, sinking 0.1 mA | | | 0.3 | V |
| | | $V_{CC} \ge 4.5 \text{ V}, I_{SOURCE} = 0.8 \text{ mA}$ | 0.8 V _{CC} | | | V |
| V _{OH} | Reset output voltage high, RST1 | $V_{CC} \ge 2.7 \text{ V, I}_{SOURCE} = 0.5 \text{ mA}$ | 0.8 V _{CC} | | | V |
| | | $V_{CC} \ge 1.2 \text{ V}, I_{SOURCE} = 0.05 \text{ mA}$ | 0.8 V _{CC} | | | V |
| V | Fixed voltage trip point for V _{CC} | -40 to +85 °C | V _{RST} -2.5% | V _{RST} | V _{RST} +2.5% | V |
| V _{RST} | (refer Table 6) | 25 °C | V _{RST} -2.0% | V _{RST} | V _{RST} +2.0% | V |
| V | Hyptoropia of V | L, M | | 0.5% | | |
| V _{HYST} | Hysteresis of V _{RST} | T, S, R, Z, Y, W, V | | 1% | | |
| | V _{CC} to reset delay | V _{CC} falling from (V _{RST} + 100 mV) to (V _{RST} - 100 mV) at 10 mV/μs | | 20 | | μs |
| + | Output reset timeout period on | Option E | 140 | 210 | 280 | ms |
| t _{REC2} | RST2, factory-programmed | Option F | 240 | 360 | 480 | ms |
| t _{REC1} | User-programmable output reset timeout period on RST1 | | | See Table 2 | | ms |
| Smart re | eset inputs (SRx) | | | | | |
| Sheet4U.co | m | TSR = V _{SS} | 2 | 2.5 | 3 | s |
| t _{SRC} | Smart reset delay | TSR = floating | 6 | 7.5 | 9 | s |
| | | TSR = V _{CC} | 10 | 12.5 | 15 | s |
| V _{IL} | SR0, SR1 input voltage low | | | | 0.3 V _{CC} | ٧ |
| V _{IH} | SR0, SR1 input voltage high | | 0.7 V _{CC} | | | V |
| | Input glitch immunity | Corresponds to the actual t _{SRC} | | t _{SRC} | | s |
| I _{LI(SR)} | Input leakage current (SR0, SR1 pins) | | -1 | | 1 | μA |
| I _{LI(TSR)} | Input leakage current (TSR pin) | | -5 | | 7 | μA |

^{1.} Valid for ambient operating temperature: $T_A = -40$ to +85 °C; $V_{CC} = 1.0$ V to 5.5 V (except where noted).

| V _{CC} voltage | Tun | ±2.5% (–40 ° | C to +85 °C) | ±2.0% (| Unit | |
|----------------------------|-------|--------------|--------------|---------|-------|-------|
| threshold V _{RST} | Тур. | Min. | Max. | Min. | Max. | Offic |
| L (falling) | 4.625 | 4.509 | 4.741 | 4.533 | 4.718 | V |
| M (falling) | 4.375 | 4.266 | 4.484 | 4.288 | 4.463 | V |
| T (falling) | 3.075 | 2.998 | 3.152 | 3.014 | 3.137 | V |
| S (falling) | 2.925 | 2.852 | 2.998 | 2.867 | 2.984 | V |
| R (falling) | 2.625 | 2.559 | 2.691 | 2.573 | 2.678 | V |
| Z (falling) | 2.313 | 2.255 | 2.371 | 2.267 | 2.359 | V |
| Y (falling) | 2.188 | 2.133 | 2.243 | 2.144 | 2.232 | V |
| W (falling) | 1.665 | 1.623 | 1.707 | 1.632 | 1.698 | V |
| V (falling) | 1.575 | 1.536 | 1.614 | 1.544 | 1.607 | V |

8 Package mechanical data

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status are available at: www.st.com. ECOPACK[®] is an ST trademark.



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Table 7. TDFN – 8-lead 2 x 2 x 0.75 mm, 0.5 mm package mechanical data

| Symbol | D | imension (mn | n) | Dimension (inches) | | | |
|----------|------|--------------|------|--------------------|-------|-------|--|
| | Min. | Nom. | Max. | Min. | Nom. | Max. | |
| А | 0.70 | 0.75 | 0.80 | 0.028 | 0.030 | 0.031 | |
| A1 | 0.00 | 0.02 | 0.05 | 0.000 | 0.001 | 0.002 | |
| b | 0.15 | 0.20 | 0.25 | 0.006 | 0.008 | 0.010 | |
| D BSC | | 2.00 | | | 0.079 | | |
| E BSC | | 2.00 | | | 0.079 | | |
| е | | 0.50 | | | 0.020 | | |
| L | 0.45 | 0.55 | 0.65 | 0.018 | 0.022 | 0.026 | |

Package footprint STM6513

9 Package footprint

Figure 14. Landing pattern - TDFN - 8-lead 2 x 2 mm without thermal pad

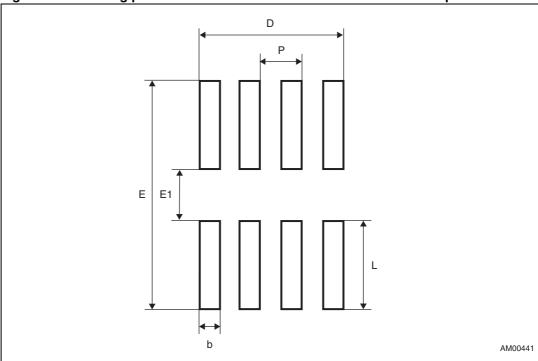


Table 8. Parameter for landing pattern - TDFN - 8-lead 2 x 2 mm package

| Parameter | Description | Dimension (mm) | | | | |
|-----------|-------------------------------|----------------|------|------|--|--|
| Farameter | Description | Min. | Nom. | Max. | | |
| L | Contact length | 1.05 | _ | 1.15 | | |
| b | Contact width | 0.25 | _ | 0.30 | | |
| Е | Max. land pattern Y-direction | _ | 2.75 | _ | | |
| E1 | Contact gap spacing | _ | 0.65 | _ | | |
| D | Max. land pattern X-direction | 1 | 1.75 | - | | |
| Р | Contact pitch | _ | 0.5 | _ | | |

10 Tape and reel information

Figure 15. Carrier tape

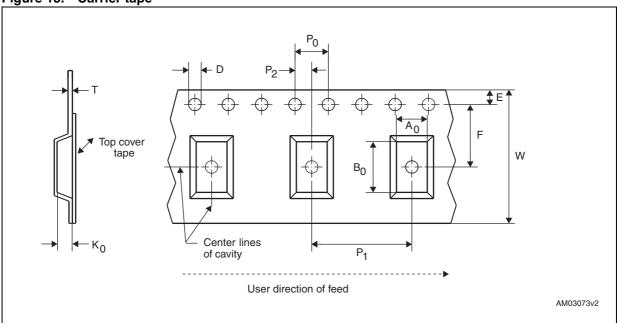


Table 9. Carrier tape dimensions

| Package | W | D | E | P ₀ | P ₂ | F | A ₀ | B ₀ | K ₀ | P ₁ | Т | Unit | Bulk Qty. |
|---------|------------------------|-------------------------|---------------|----------------|----------------|---------------|-----------------------|----------------|----------------|----------------|----------------|------|--------------|
| TDFN8 | 8.00 -0.30 -0.10 | 1.50 +0.10/ -0.00 | 1.75 ±0.10 | 4.00 ±0.10 | 2.00 ±0.10 | 3.50 ±0.05 | 2.30 ±0.05 | 2.30 ±0.05 | 1.00 ±0.05 | 4.00 ±0.10 | 0.250 ±0.05 | mm | 3000 |

Figure 16. Reel dimensions

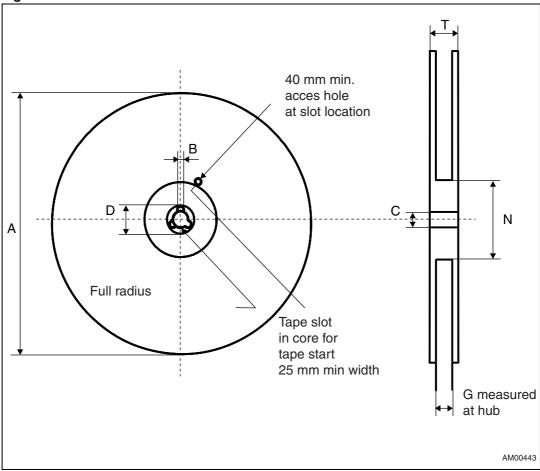


Table 10. Reel dimensions

| Tape sizes | A max. | B min. | С | D min. | N min. | G | T max. |
|------------|----------------|--------|---------------|--------|--------|-----------|--------|
| 8 mm | 180 (7 inches) | 1.50 | 13.0 +/- 0.20 | 20.20 | 60 | 8.4 +2/-0 | 14.40 |

Figure 17. Tape trailer/leader

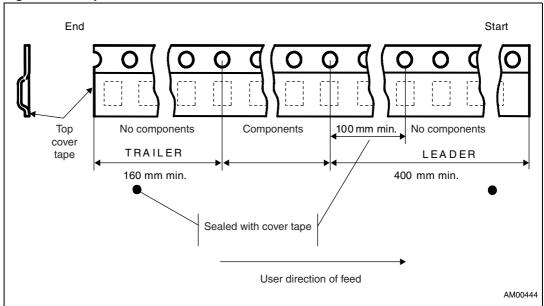
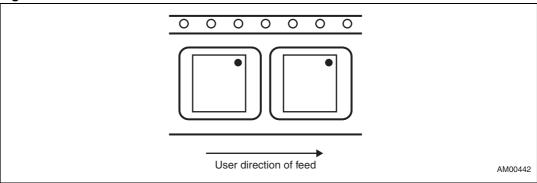


Figure 18. Pin 1 orientation



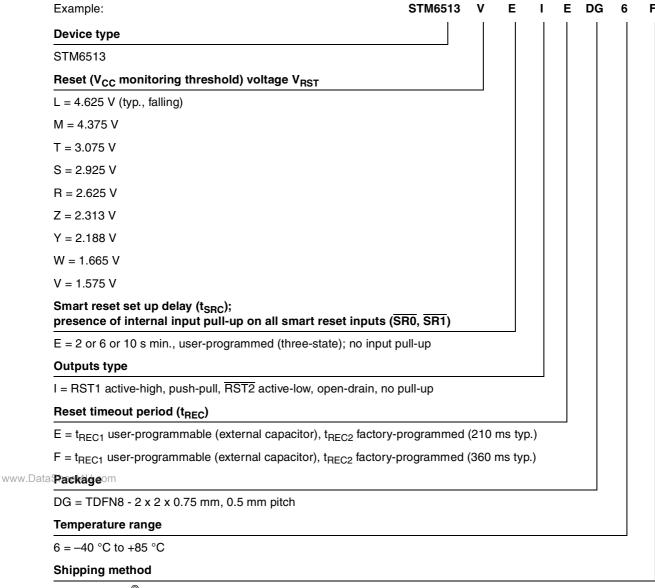
Drawings are not to scale.

2 All dimensions are in mm, unless otherwise noted.

Part numbering STM6513

11 Part numbering

Table 11. Ordering information scheme



F = ECOPACK® package, tape and reel

For other options, voltage threshold values etc. or for more information on any aspect of this device, please contact the ST sales office nearest you.

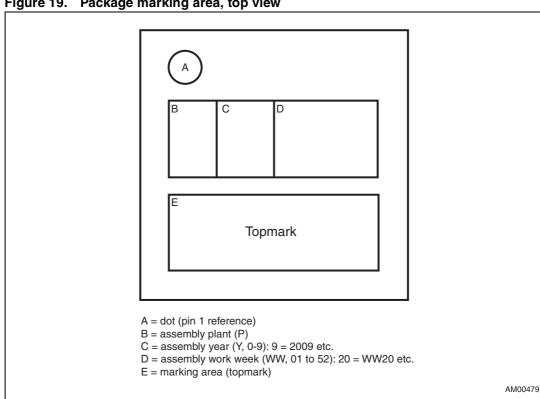
12 Package marking information

Package marking⁽¹⁾ Table 12.

| Full part number | t _{SRC} delay control | Smart reset inputs type | V _{RST} | RST1 output type | t _{REC1} programming | RST2 output type | t _{REC2} | Topmark |
|------------------|--------------------------------------|-------------------------|------------------|------------------------|-------------------------------|------------------------|-------------------|---------|
| STM6513VEIEDG6F | TSR | AL | V | AH, PP | C _{tREC} | AL, OD | E | 9AH |
| STM6513SEIEDG6F | TSR | AL | S | AH, PP | C _{tREC} | AL, OD | E | 9SH |
| STM6513REIEDG6F | TSR | AL | R | AH, PP | C _{tREC} | AL, OD | Е | 9RH |

^{1.} AL = active-low, AH = active-high; PP = push-pull, OD = open-drain.

Figure 19. Package marking area, top view



Revision history STM6513

13 Revision history

Table 13. Document revision history

| Date | Revision | Changes | |
|-------------|----------|------------------|--|
| 22-Oct-2009 | 1 | Initial release. | |

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