

# **Single Phase Half Controlled Bridges**

PSBH 125

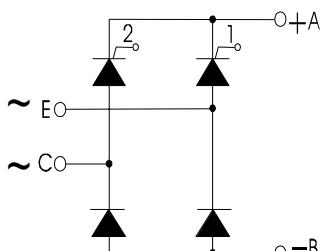
**I<sub>dAV</sub>**  
**V<sub>RRM</sub>**

$$= 123 \text{ A}$$

## Preliminary Data Sheet

| <b>V<sub>RSM</sub></b> | <b>V<sub>RRM</sub></b> | <b>Type</b> |
|------------------------|------------------------|-------------|
| <b>V<sub>DSM</sub></b> | <b>V<sub>DRM</sub></b> |             |
| 500                    | 400                    | PSBH 125/04 |
| 900                    | 800                    | PSBH 125/08 |
| 1300                   | 1200                   | PSBH 125/12 |
| 1500                   | 1400                   | PSBH 125/14 |
| *1700                  | *1600                  | PSBH 125/16 |

\* Delivery on request



## Symbol Test Conditions

#### **Maximum Ratings**

| Symbol             | Test Conditions                                    |   |               | Maximum Ratings |                 |
|--------------------|--|---|---------------|-----------------|-----------------|
| $I_{dAV}$          | $T_C = 85^\circ C$ , module                        |   |               | 123             | A               |
| $I_{FSM}, I_{TSM}$ | $T_{VJ} = 45^\circ C$                              | $t = 10 \text{ ms}$                       | (50 Hz), sine | 1500            | A               |
|                    | $V_R = 0$  | $t = 8.3 \text{ ms}$                      | (60 Hz), sine | 1600            | A               |
|                    | $T_{VJ} = T_{VJM}$                                 | $t = 10 \text{ ms}$                       | (50 Hz), sine | 1350            | A               |
|                    | $V_R = 0$  | $t = 8.3 \text{ ms}$                      | (60 Hz), sine | 1450            | A               |
| $\int i^2 dt$      | $T_{VJ} = 45^\circ C$                              | $t = 10 \text{ ms}$                       | (50 Hz), sine | 11 200          | $A^2 \text{ s}$ |
|                    | $V_R = 0$  | $t = 8.3 \text{ ms}$                      | (60 Hz), sine | 10 750          | $A^2 \text{ s}$ |
|                    | $T_{VJ} = T_{VJM}$                                 | $t = 10 \text{ ms}$                       | (50 Hz), sine | 9100            | $A^2 \text{ s}$ |
|                    | $V_R = 0$  | $t = 8.3 \text{ ms}$                      | (60 Hz), sine | 8830            | $A^2 \text{ s}$ |
| $(di/dt)_{cr}$     | $T_{VJ} = T_{VJM}$                                 | repetitive, $I_T = 50 \text{ A}$          |               | 150             | $A/\mu\text{s}$ |
|                    | $f = 400 \text{ Hz}$ , $t_P = 200 \mu\text{s}$     |   |               |                 |                 |
|                    | $V_D = 2/3 V_{DRM}$                                |   |               |                 |                 |
|                    | $I_G = 0.3 \text{ A}$                              | non repetitive, $I_T = 1/3 \cdot I_{dAV}$ |               | 500             | $A/\mu\text{s}$ |
| $(dv/dt)_{cr}$     | $T_{VJ} = T_{VJM}$                                 | $V_{DR} = 2/3 V_{DRM}$                    |               | 1000            | $V/\mu\text{s}$ |
|                    | $R_{GK} = \infty$ , method 1 (linear voltage rise) |   |               |                 |                 |
|                    | $T_{VJ} = T_{VJM}$                                 | $t_P = 30 \mu\text{s}$                    |               | $\leq 10$       | W               |
|                    | $I_T = I_{TAVM}$                                   | $t_P = 500 \mu\text{s}$                   |               | $\leq 5$        | W               |
| $P_{GAVM}$         |  |   |               | 0.5             | W               |
| $V_{RGM}$          |  |   |               | 10              | V               |
| $T_{VJ}$           |  |   | -40 ... + 125 |                 | $^\circ C$      |
| $T_{VJM}$          |  |   | 125           |                 | $^\circ C$      |
| $T_{stg}$          |  |   | -40 ... + 125 |                 | $^\circ C$      |
| $V_{ISOL}$         | 50/60 HZ, RMS                                      | $t = 1 \text{ min}$                       |               | 2500            | $V \sim$        |
|                    | $I_{ISOL} \leq 1 \text{ mA}$                       | $t = 1 \text{ s}$                         |               | 3000            | $V \sim$        |
| $M_d$              | Mounting torque                                    |   | (M6)          | 5               | Nm              |
|                    | Terminal connection torque                         |   | (M6)          | 5               | Nm              |
| <b>Weight</b>      | typ.   |   |               | 270             | g               |

## Features

- Package with screw terminals
  - Isolation voltage 3000 V~
  - Planar glasspassivated chips
  - Low forward voltage drop
  - UL released. E 148688

## Applications

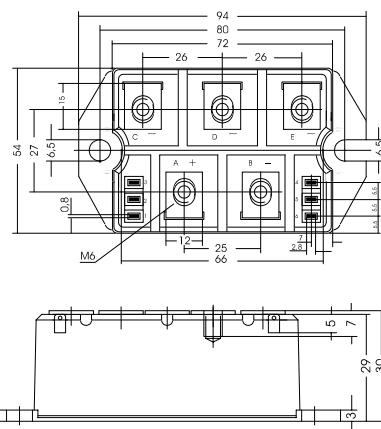
- Heat and temperature control for industrial furnaces and chemical processes
  - Lighting control
  - Motor control
  - Power converter

## Advantages

- Easy to mount with two screws
  - Space and weight savings
  - Improved temperature and power cycling capability
  - High power density

## Package, style and outline

Dimensions in mm (1mm = 0.0394")



| Symbol     | Test Conditions  |                        | Characteristic Value |        |           |
|------------|--|------------------------|----------------------|--------|-----------|
| $I_D, I_R$ | $T_{VJ} = T_{VJM}$ , $V_R = V_{RRM}$ , $V_D = V_{DRM}$   |                        | $\leq$               | 5      | mA        |
| $V_T$      | $I_T = 200A$ , $T_{VJ} = 25^\circ C$   |                        | $\leq$               | 1.57   | V         |
| $V_{TO}$   | For power-loss calculations only ( $T_{VJ} = T_{VJM}$ )  |                        |                      | 0.85   | V         |
| $r_T$      |  |                        |                      | 3.5    | $m\Omega$ |
| $V_{GT}$   | $V_D = 6V$   | $T_{VJ} = 25^\circ C$  | $\leq$               | 1.5    | V         |
|            |  | $T_{VJ} = -40^\circ C$ | $\leq$               | 1.6    | V         |
| $I_{GT}$   | $V_D = 6V$   | $T_{VJ} = 25^\circ C$  | $\leq$               | 100    | mA        |
|            |  | $T_{VJ} = -40^\circ C$ | $\leq$               | 200    | mA        |
| $V_{GD}$   | $T_{VJ} = T_{VJM}$   | $V_D = 2/3 V_{DRM}$    | $\leq$               | 0.2    | V         |
| $I_{GD}$   | $T_{VJ} = T_{VJM}$   | $V_D = 2/3 V_{DRM}$    | $\leq$               | 5      | mA        |
| $I_L$      | $T_{VJ} = 25^\circ C$ , $t_P = 30\mu s$<br>$I_G = 0.3A$ , $dI_G/dt = 0.3A/\mu s$   |                        | $\leq$               | 450    | mA        |
| $I_H$      | $T_{VJ} = 25^\circ C$ , $V_D = 6V$ , $R_{GK} = \infty$   |                        | $\leq$               | 200    | mA        |
| $t_{gd}$   | $T_{VJ} = 25^\circ C$ , $V_D = 1/2 V_{DRM}$<br>$I_G = 0.3A$ , $dI_G/dt = 0.3A/\mu s$   |                        | $\leq$               | 2      | $\mu s$   |
| $t_q$      | $T_{VJ} = T_{VJM}$ , $I_T = 20A$ , $t_P = 200\mu s$ , $V_R = 100V$<br>$-di/dt = 10A/\mu s$ , $dv/dt = 15V/\mu s$ , $V_D = 2/3 V_{DRM}$ |                        |                      | 150    | $\mu s$   |
| $R_{thJC}$ | per thyristor; sine 180°el   |                        |                      | 0.46   | K/W       |
|            | per module   |                        |                      | 0.115  | K/W       |
| $R_{thJK}$ | per thyristor; sine 180° el  |                        |                      | 0.55   | K/W       |
|            | per module   |                        |                      | 0.1375 | K/W       |
| $d_s$      | Creeping distance on surface   |                        |                      | 10     | mm        |
| $d_A$      | Creeping distance in air   |                        |                      | 9.4    | mm        |
| $a$        | Max. allowable acceleration  |                        |                      | 50     | $m/s^2$   |

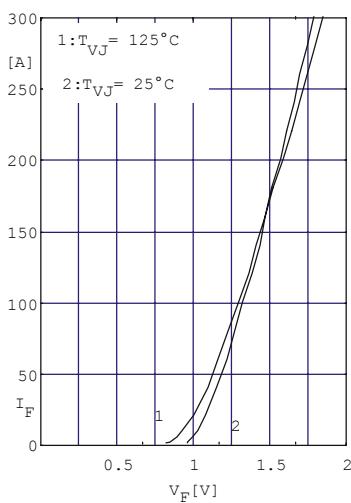


Fig. 1 Forward current vs. voltage drop per diode or thyristor

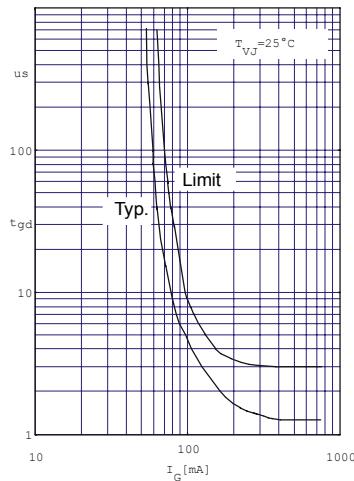


Fig. 2 Gate trigger delay time

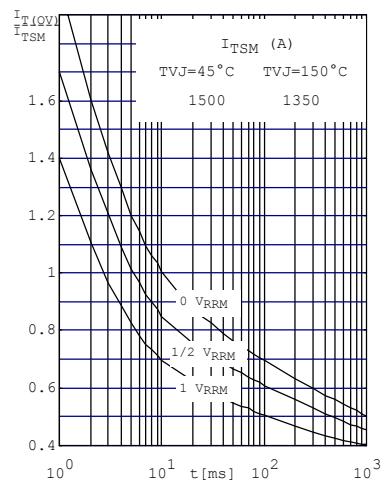


Fig. 3 Surge overload current per diode (or thyristor)  $I_{FSM}$ ,  $I_{TSM}$ : Crest value  $t$ : duration

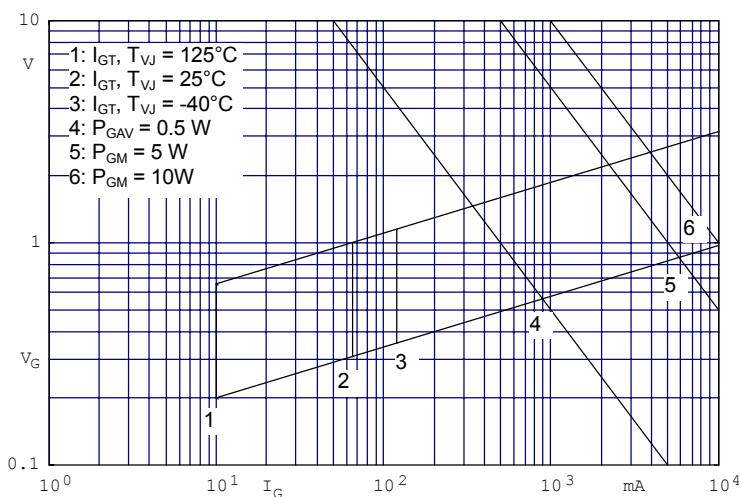


Fig.4 Gate trigger characteristic

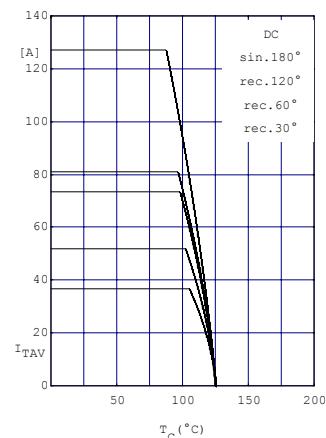


Fig.5 Maximum forward current at case temperature

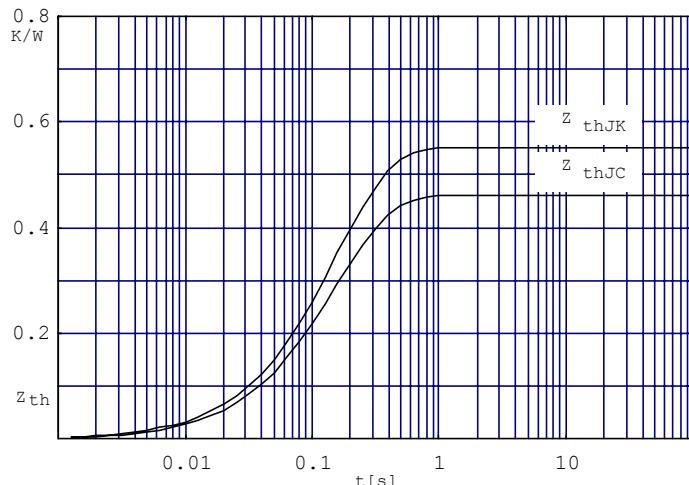


Fig.6 Transient thermal impedance per thyristor or diode (calculated)

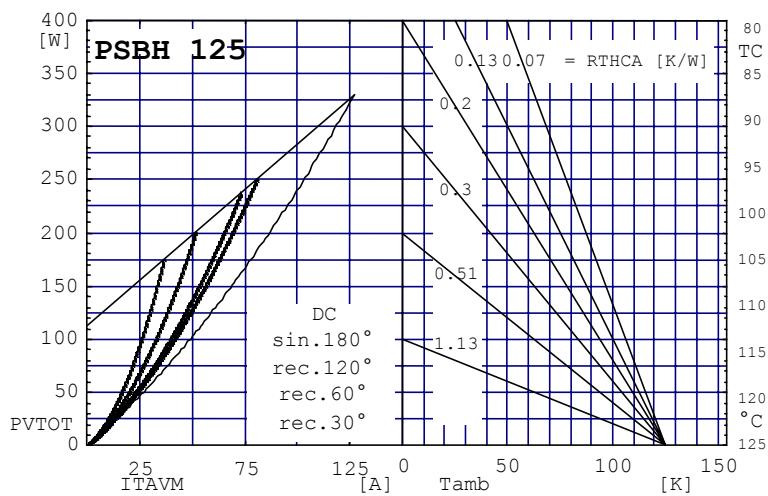


Fig. 7 Power dissipation vs. direct output current and ambient temperature