

# MMSF7P03HD

Preferred Device

## Power MOSFET

### 7 A, 30 V, P-Channel SO-8

These miniature surface mount devices are designed for use in low voltage, high speed switching applications where power efficiency is important. Typical applications are DC-DC converters, and power management in portable and battery powered products such as computers, printers, cellular and cordless phones. They can also be used for low voltage motor controls in mass storage products such as disk drives and tape drives.

#### Features

- Low  $R_{DS(on)}$  Provides Higher Efficiency and Extends Battery Life
- Logic Level Gate Drive – Can Be Driven by Logic ICs
- Miniature SO-8 Surface Mount Package – Saves Board Space
- Diode Is Characterized for Use In Bridge Circuits
- Diode Exhibits High Speed, With Soft Recovery
- $I_{DSS}$  Specified at Elevated Temperature
- Mounting Information for SO-8 Package Provided
- Pb-Free Package is Available

#### MAXIMUM RATINGS ( $T_J = 25^\circ\text{C}$ unless otherwise noted)

Rating	Symbol	Value	Unit
Drain-to-Source Voltage	$V_{DSS}$	30	Vdc
Gate-to-Source Voltage	$V_{GS}$	$\pm 20$	Vdc
Drain Current	$I_D$	7.0	A dc
Single Pulse ( $t_p \leq 10 \mu\text{s}$ )	$I_{DM}$	50	A pk
Source Current – Continuous @ $T_A = 25^\circ\text{C}$	$I_S$	2.3	A dc
Total Power Dissipation @ $T_A = 25^\circ\text{C}$ (Note 1)	$P_D$	2.5	W
Operating and Storage Temperature Range	$T_J, T_{stg}$	-55 to 150	$^\circ\text{C}$
Single Pulse Drain-to-Source Avalanche Energy – Starting $T_J = 25^\circ\text{C}$ ( $V_{DD} = 30 \text{ Vdc}$ , $V_{GS} = 5.0 \text{ Vdc}$ , $V_{DS} = 32 \text{ Vdc}$ , $I_L = 10 \text{ Apk}$ , $L = 10 \text{ mH}$ , $R_G = 25 \Omega$ )	$E_{AS}$	500	mJ
Thermal Resistance, Junction-to-Ambient	$R_{\theta JA}$	50	$^\circ\text{C/W}$
Maximum Temperature for Soldering	$T$	260	$^\circ\text{C}$

Maximum ratings are those values beyond which device damage can occur. Maximum ratings applied to the device are individual stress limit values (not normal operating conditions) and are not valid simultaneously. If these limits are exceeded, device functional operation is not implied, damage may occur and reliability may be affected.

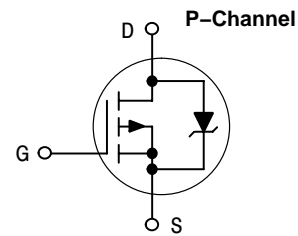
1. When mounted on 1 in square FR-4 or G-10 ( $V_{GS} = 10 \text{ V}$  @ 10 seconds)



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7 A, 30 V –  $R_{DS(on)} = 35 \text{ m}\Omega$



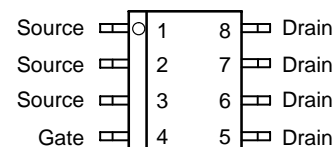
#### MARKING DIAGRAM



S7P03 = Device Code  
 A = Assembly Location  
 Y = Year  
 WW = Work Week  
 ■ = Pb-Free Package

(Note: Microdot may be in either location)

#### PIN ASSIGNMENT



Top View

#### ORDERING INFORMATION

Device	Package	Shipping†
MMSF7P03HDR2	SO-8	2500 / Tape&Reel
MMSF7P03HDR2G	SO-8 (Pb-Free)	2500 / Tape&Reel

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

Preferred devices are recommended choices for future use and best overall value.

# MMSF7P03HD

## ELECTRICAL CHARACTERISTICS ( $T_A = 25^\circ\text{C}$ unless otherwise noted) (Note 2)

Characteristic	Symbol	Min	Typ	Max	Unit
<b>OFF CHARACTERISTICS</b>					
Drain-to-Source Breakdown Voltage ( $V_{GS} = 0\text{ Vdc}$ , $I_D = 0.25\text{ mAdc}$ ) Temperature Coefficient (Positive)	$V_{(BR)DSS}$	30	–	–	Vdc
Zero Gate Voltage Drain Current ( $V_{DS} = 30\text{ Vdc}$ , $V_{GS} = 0\text{ Vdc}$ ) ( $V_{DS} = 30\text{ Vdc}$ , $V_{GS} = 0\text{ Vdc}$ , $T_J = 125^\circ\text{C}$ )	$I_{DSS}$	–	–	1.0 25	$\mu\text{Adc}$
Gate-Body Leakage Current ( $V_{GS} = \pm 20\text{ Vdc}$ , $V_{DS} = 0\text{ Vdc}$ )	$I_{GSS}$	–	–	100	nAdc

## ON CHARACTERISTICS (Note 3)

Gate Threshold Voltage ( $V_{DS} = V_{GS}$ , $I_D = 0.25\text{ mAdc}$ ) Threshold Temperature Coefficient (Negative)	$V_{GS(th)}$	1.0	–	–	Vdc
Static Drain-to-Source On-Resistance ( $V_{GS} = 10\text{ Vdc}$ , $I_D = 5.3\text{ Adc}$ ) ( $V_{GS} = 4.5\text{ Vdc}$ , $I_D = 2.0\text{ Adc}$ )	$R_{DS(on)}$	–	26 42	35 50	$\text{m}\Omega$
Forward Transconductance ( $V_{DS} = 15\text{ Vdc}$ , $I_D = 2.5\text{ Adc}$ )	$g_{FS}$	–	12	–	Mhos

## DYNAMIC CHARACTERISTICS

Input Capacitance	$(V_{DS} = 24\text{ Vdc}$ , $V_{GS} = 0\text{ V}$ , $f = 1.0\text{ MHz}$ )	$C_{iss}$	–	1200	1680	$\text{pF}$
Output Capacitance		$C_{oss}$	–	580	810	
Transfer Capacitance		$C_{rss}$	–	160	220	

## SWITCHING CHARACTERISTICS (Note 4)

Turn-On Delay Time	$(V_{DD} = 15\text{ Vdc}$ , $I_D = 1.0\text{ Adc}$ , $V_{GS} = 4.5\text{ Vdc}$ , $R_G = 10\ \Omega$ )	$t_{d(on)}$	–	23.5	47	ns
Rise Time		$t_r$	–	42.7	85.4	
Turn-Off Delay Time		$t_{d(off)}$	–	57.4	114.8	
Fall Time		$t_f$	–	53.6	107.2	
Turn-On Delay Time	$(V_{DD} = 15\text{ Vdc}$ , $I_D = 1.0\text{ Adc}$ , $V_{GS} = 10\text{ Vdc}$ , $R_G = 6.0\ \Omega$ )	$t_{d(on)}$	–	16	32	ns
Rise Time		$t_r$	–	15.2	30.6	
Turn-Off Delay Time		$t_{d(off)}$	–	99.7	199.4	
Fall Time		$t_f$	–	55.2	110.4	
Gate Charge (See Figure 8)	$(V_{DS} = 10\text{ Vdc}$ , $I_D = 4.9\text{ Adc}$ , $V_{GS} = 6.0\text{ Vdc}$ )	$Q_T$	–	37.9	75.8	nC
		$Q_1$	–	4.2	–	
		$Q_2$	–	11.5	–	
		$Q_3$	–	7.6	–	

## SOURCE-DRAIN DIODE CHARACTERISTICS

Forward On-Voltage	$(I_S = 2.3\text{ Adc}$ , $V_{GS} = 0\text{ Vdc}$ ) $(I_S = 2.3\text{ Adc}$ , $V_{GS} = 0\text{ Vdc}$ , $T_J = 125^\circ\text{C}$ )	$V_{SD}$	–	0.76 0.61	1.2 –	Vdc
Reverse Recovery Time	$(I_S = 4.9\text{ Adc}$ , $V_{GS} = 0\text{ Vdc}$ , $di_S/dt = 100\text{ A}/\mu\text{s}$ )	$t_{rr}$	–	47.9	–	ns
		$t_a$	–	27	–	
		$t_b$	–	21	–	
Reverse Recovery Stored Charge		$Q_{RR}$	–	0.052	–	$\mu\text{C}$

- Negative sign for P-Channel device omitted for clarity.
- Pulse Test: Pulse Width  $\leq 300\ \mu\text{s}$ , Duty Cycle  $\leq 2\%$ .
- Switching characteristics are independent of operating junction temperature.

TYPICAL ELECTRICAL CHARACTERISTICS

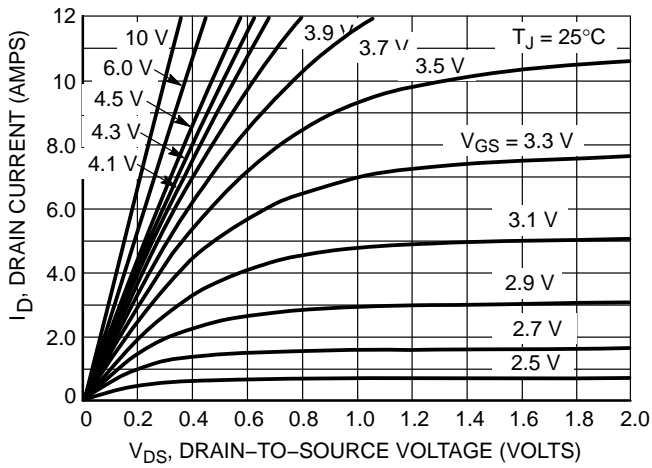


Figure 1. On-Region Characteristics

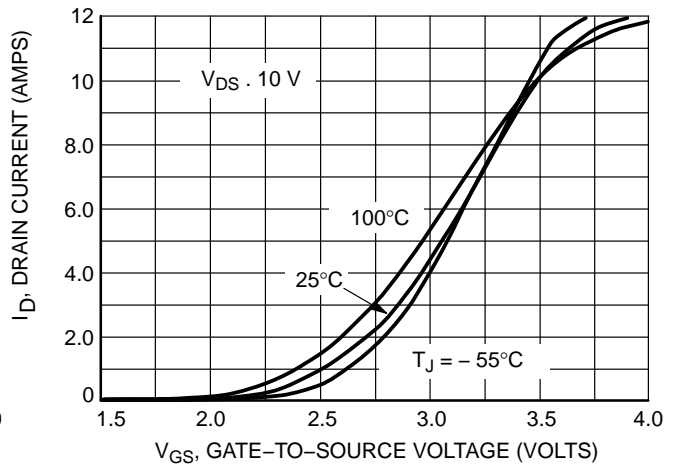


Figure 2. Transfer Characteristics

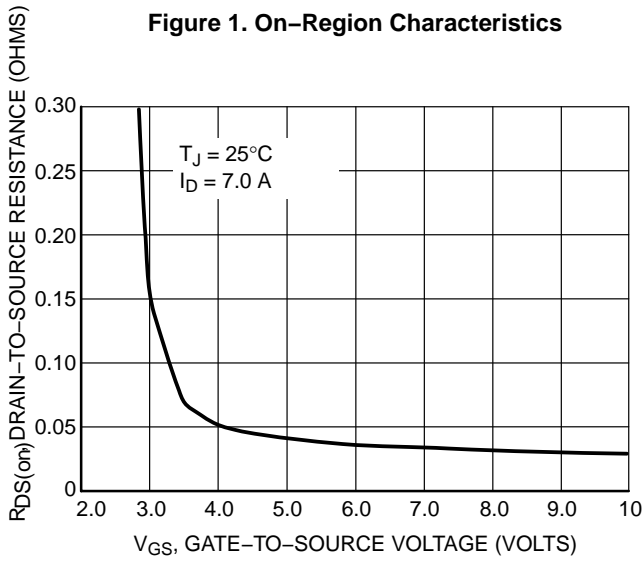


Figure 3. On-Resistance versus Gate-to-Source Voltage

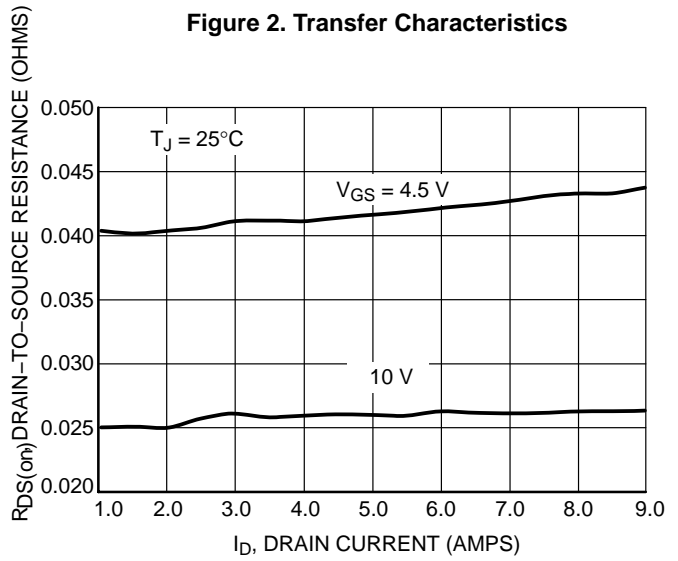


Figure 4. On-Resistance versus Drain Current and Gate Voltage

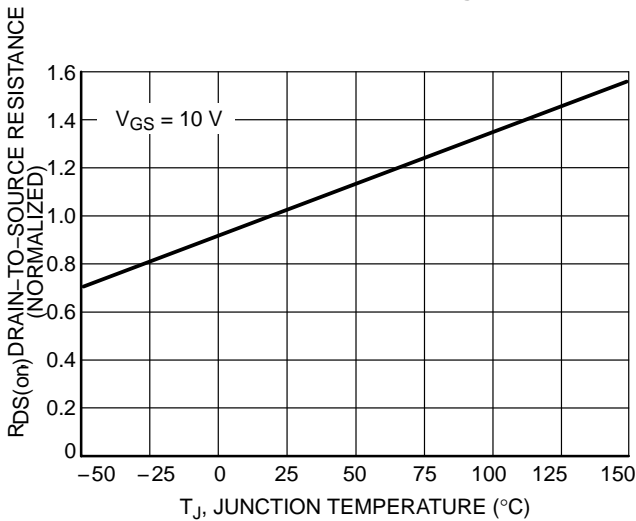


Figure 5. On-Resistance Variation with Temperature

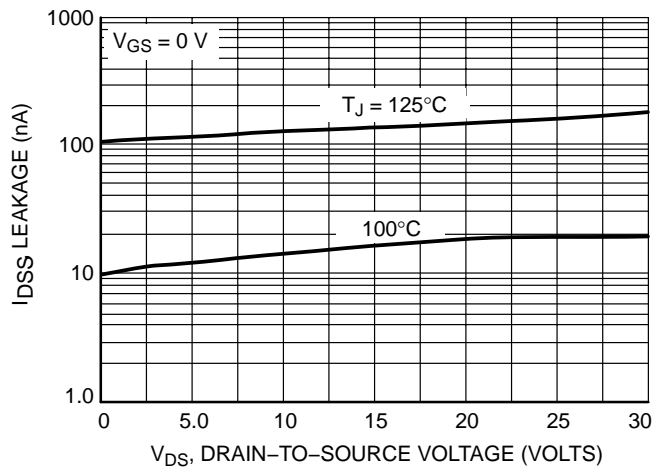


Figure 6. Drain-to-Source Leakage Current versus Voltage

POWER MOSFET SWITCHING

Switching behavior is most easily modeled and predicted by recognizing that the power MOSFET is charge controlled. The lengths of various switching intervals ( $\Delta t$ ) are determined by how fast the FET input capacitance can be charged by current from the generator.

The published capacitance data is difficult to use for calculating rise and fall because drain-gate capacitance varies greatly with applied voltage. Accordingly, gate charge data is used. In most cases, a satisfactory estimate of average input current ( $I_{G(AV)}$ ) can be made from a rudimentary analysis of the drive circuit so that

$$t = Q/I_{G(AV)}$$

During the rise and fall time interval when switching a resistive load,  $V_{GS}$  remains virtually constant at a level known as the plateau voltage,  $V_{GSP}$ . Therefore, rise and fall times may be approximated by the following:

$$t_r = Q_2 \times R_G / (V_{GG} - V_{GSP})$$

$$t_f = Q_2 \times R_G / V_{GSP}$$

where

$V_{GG}$  = the gate drive voltage, which varies from zero to  $V_{GG}$

$R_G$  = the gate drive resistance

and  $Q_2$  and  $V_{GSP}$  are read from the gate charge curve.

During the turn-on and turn-off delay times, gate current is not constant. The simplest calculation uses appropriate values from the capacitance curves in a standard equation for voltage change in an RC network. The equations are:

$$t_{d(on)} = R_G C_{iss} \ln [V_{GG}/(V_{GG} - V_{GSP})]$$

$$t_{d(off)} = R_G C_{iss} \ln (V_{GG}/V_{GSP})$$

The capacitance ( $C_{iss}$ ) is read from the capacitance curve at a voltage corresponding to the off-state condition when calculating  $t_{d(on)}$  and is read at a voltage corresponding to the on-state when calculating  $t_{d(off)}$ .

At high switching speeds, parasitic circuit elements complicate the analysis. The inductance of the MOSFET source lead, inside the package and in the circuit wiring which is common to both the drain and gate current paths, produces a voltage at the source which reduces the gate drive current. The voltage is determined by  $L di/dt$ , but since  $di/dt$  is a function of drain current, the mathematical solution is complex. The MOSFET output capacitance also complicates the mathematics. And finally, MOSFETs have finite internal gate resistance which effectively adds to the resistance of the driving source, but the internal resistance is difficult to measure and, consequently, is not specified.

The resistive switching time variation versus gate resistance (Figure 9) shows how typical switching performance is affected by the parasitic circuit elements. If the parasitics were not present, the slope of the curves would maintain a value of unity regardless of the switching speed. The circuit used to obtain the data is constructed to minimize common inductance in the drain and gate circuit loops and is believed readily achievable with board mounted components. Most power electronic loads are inductive; the data in the figure is taken with a resistive load, which approximates an optimally snubbed inductive load. Power MOSFETs may be safely operated into an inductive load; however, snubbing reduces switching losses.

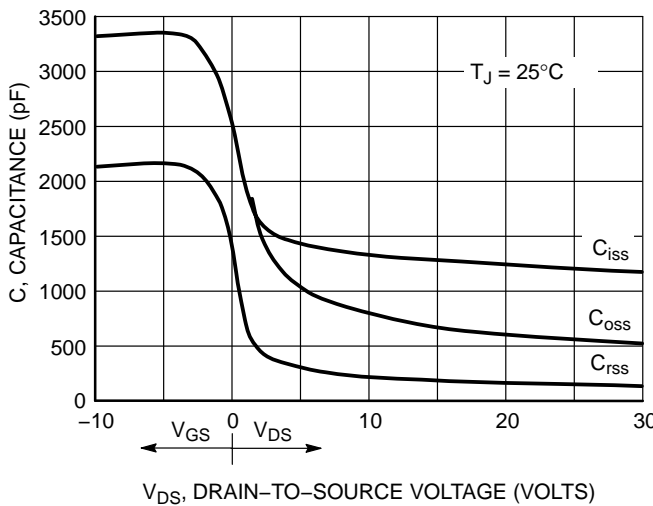


Figure 7. Capacitance Variation

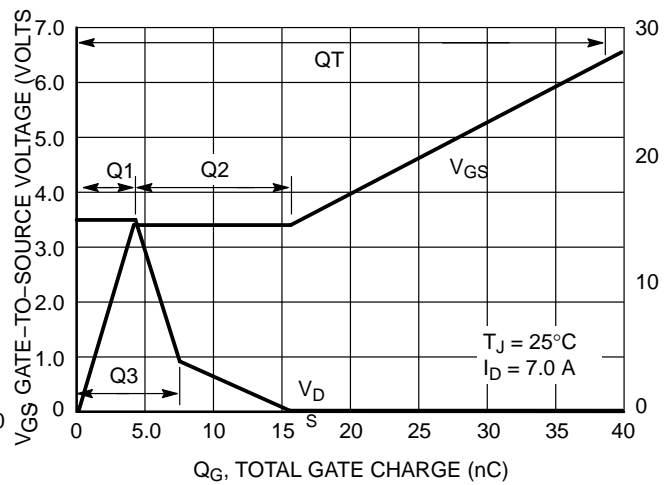
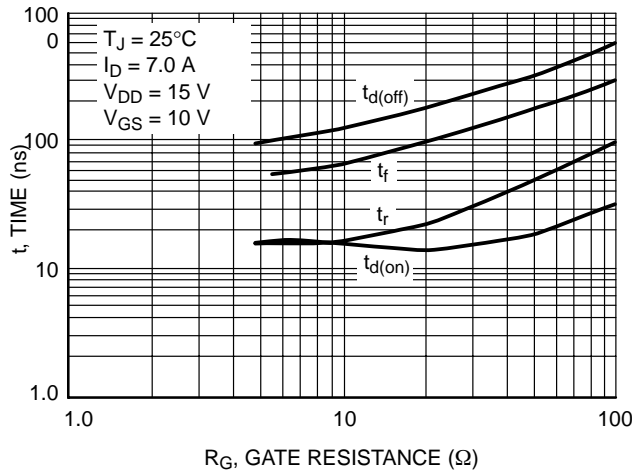


Figure 8. Gate-to-Source and Drain-to-Source Voltage versus Total Charge

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**Figure 9. Resistive Switching Time Variation versus Gate Resistance**

## DRAIN-TO-SOURCE DIODE CHARACTERISTICS

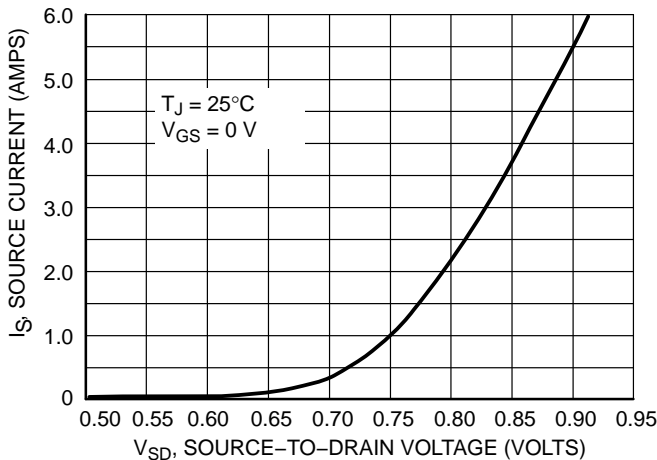
The switching characteristics of a MOSFET body diode are very important in systems using it as a freewheeling or commutating diode. Of particular interest are the reverse recovery characteristics which play a major role in determining switching losses, radiated noise, EMI and RFI.

System switching losses are largely due to the nature of the body diode itself. The body diode is a minority carrier device, therefore it has a finite reverse recovery time,  $t_{rr}$ , due to the storage of minority carrier charge,  $Q_{RR}$ , as shown in the typical reverse recovery wave form of Figure 11. It is this stored charge that, when cleared from the diode, passes through a potential and defines an energy loss. Obviously, repeatedly forcing the diode through reverse recovery further increases switching losses. Therefore, one would like a diode with short  $t_{rr}$  and low  $Q_{RR}$  specifications to minimize these losses.

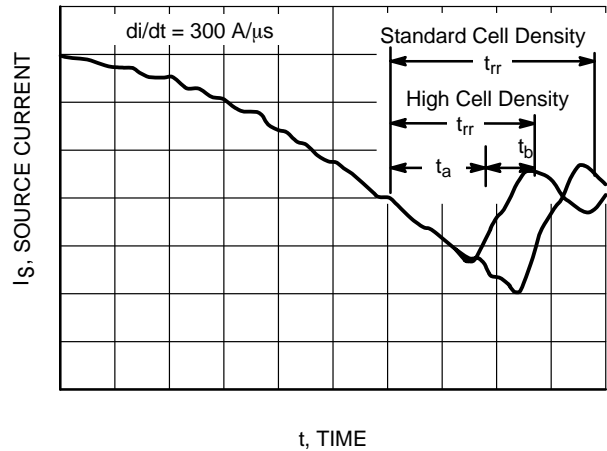
The abruptness of diode reverse recovery effects the amount of radiated noise, voltage spikes, and current ringing. The mechanisms at work are finite irremovable circuit parasitic inductances and capacitances acted upon by

high  $di/dt$ s. The diode's negative  $di/dt$  during  $t_a$  is directly controlled by the device clearing the stored charge. However, the positive  $di/dt$  during  $t_b$  is an uncontrollable diode characteristic and is usually the culprit that induces current ringing. Therefore, when comparing diodes, the ratio of  $t_b/t_a$  serves as a good indicator of recovery abruptness and thus gives a comparative estimate of probable noise generated. A ratio of 1 is considered ideal and values less than 0.5 are considered snappy.

Compared to ON Semiconductor standard cell density low voltage MOSFETs, high cell density MOSFET diodes are faster (shorter  $t_{rr}$ ), have less stored charge and a softer reverse recovery characteristic. The softness advantage of the high cell density diode means they can be forced through reverse recovery at a higher  $di/dt$  than a standard cell MOSFET diode without increasing the current ringing or the noise generated. In addition, power dissipation incurred from switching the diode will be less due to the shorter recovery time and lower switching losses.



**Figure 10. Diode Forward Voltage versus Current**



**Figure 11. Reverse Recovery Time ( $t_{rr}$ )**

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## SAFE OPERATING AREA

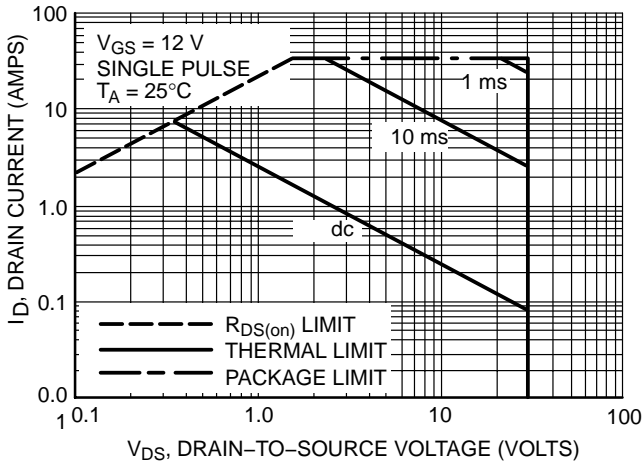
The Forward Biased Safe Operating Area curve (Figure 12) defines the maximum simultaneous drain-to-source voltage and drain current that a transistor can handle safely when it is forward biased. Curves are based upon maximum peak junction temperature and a case temperature ( $T_C$ ) of 25°C. Peak repetitive pulsed power limits are determined by using the thermal response data in conjunction with the procedures discussed in AN569, “Transient Thermal Resistance – General Data and Its Use.”

Switching between the off-state and the on-state may traverse any load line provided neither rated peak current ( $I_{DM}$ ) nor rated voltage ( $V_{DSS}$ ) is exceeded, and that the transition time ( $t_r$ ,  $t_f$ ) does not exceed 10  $\mu$ s. In addition the total power averaged over a complete switching cycle must not exceed  $(T_{J(MAX)} - T_C)/(R_{\theta JC})$ .

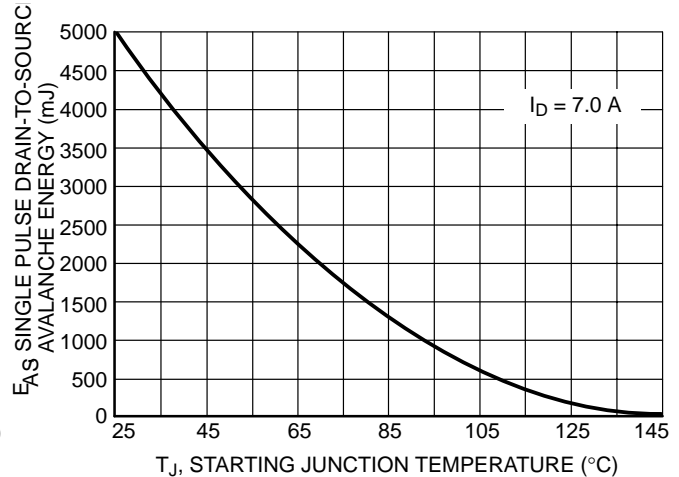
A power MOSFET designated E-FET can be safely used in switching circuits with unclamped inductive loads. For

reliable operation, the stored energy from circuit inductance dissipated in the transistor while in avalanche must be less than the rated limit and must be adjusted for operating conditions differing from those specified. Although industry practice is to rate in terms of energy, avalanche energy capability is not a constant. The energy rating decreases non-linearly with an increase of peak current in avalanche and peak junction temperature.

Although many E-FETs can withstand the stress of drain-to-source avalanche at currents up to rated pulsed current ( $I_{DM}$ ), the energy rating is specified at rated continuous current ( $I_D$ ), in accordance with industry custom. The energy rating must be derated for temperature as shown in the accompanying graph (Figure 13). Maximum energy at currents below rated continuous  $I_D$  can safely be assumed to equal the values indicated.



**Figure 12. Maximum Rated Forward Biased Safe Operating Area**



**Figure 13. Maximum Avalanche Energy versus Starting Junction Temperature**

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## TYPICAL ELECTRICAL CHARACTERISTICS

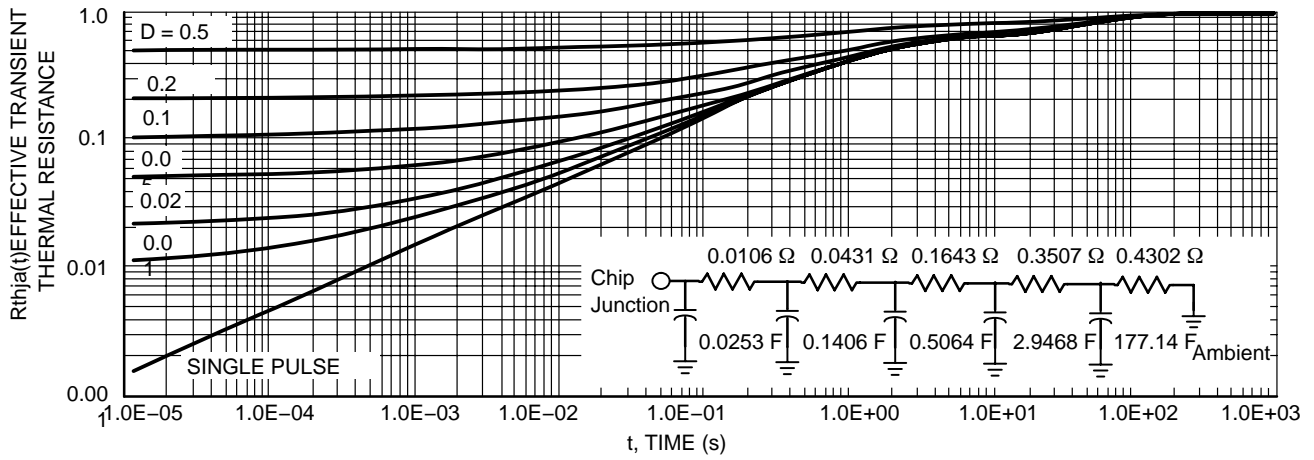


Figure 14. Thermal Response

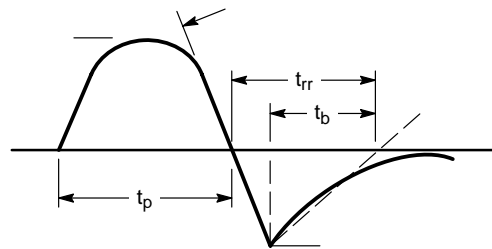
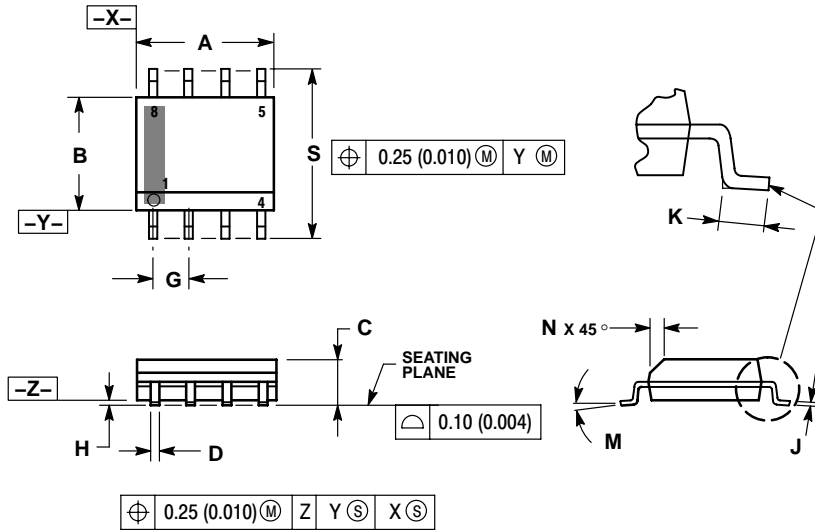


Figure 15. Diode Reverse Recovery Waveform

# MMSF7P03HD

## PACKAGE DIMENSIONS

SOIC-8  
CASE 751-07  
ISSUE AG



### NOTES:

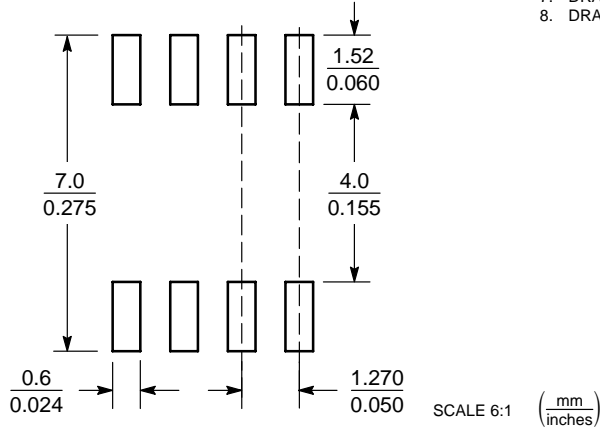
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.
6. 751-01 THRU 751-06 ARE OBSOLETE. NEW STANDARD IS 751-07.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	4.80	5.00	0.189	0.197
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.053	0.069
D	0.33	0.51	0.013	0.020
G	1.27 BSC		0.050 BSC	
H	0.10	0.25	0.004	0.010
J	0.19	0.25	0.007	0.010
K	0.40	1.27	0.016	0.050
M	0°	8°	0°	8°
N	0.25	0.50	0.010	0.020
S	5.80	6.20	0.228	0.244

### STYLE 12:

- PIN 1. SOURCE
- SOURCE
- SOURCE
- GATE
- DRAIN
- DRAIN
- DRAIN
- DRAIN

### SOLDERING FOOTPRINT\*



\*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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