

AKD4115-A AK4115 Evaluation Board Rev.3

GENERAL DESCRIPTION

AKD4115 is the evaluation board for AK4115, 192kHz digital audio transceiver. This board has optical, cannon connector (XLR), and BNC connectors to interface with other digital audio equipment.

■ Ordering guide

AKD4115-A --- Evaluation board for AK4115

(A cable for connecting the printer port (parallel port) of IBM-AT compatible PC and control software are packed with this document. Please note that the control software does not operate on Windows NT)

FUNCTION

□ Digital interface

- -S/PDIF:
 - 8 channel input (optical, BNC or XLR)
 - 2 channel output (optical, BNC or XLR)
- Serial audio data I/F:
 - 1 input (for DIT data input. 10-pin port)
 - 1 output (for DIR data output. 10-pin port)
- -B,C,U,V bit:
 - 1 input/output port (10-pin port)
- -Serial control data I/F
 - 1 input/output port (10-pin port)

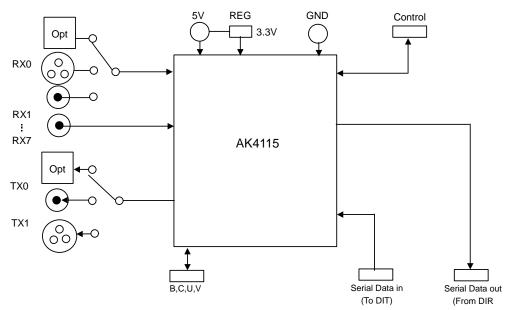


Figure 1. AKD4115-A Block Diagram

*Circuit diagram and PCB layout are attached at the end of this manual.

Evaluation Board Manual

■ Operating sequence

(1) Set up the power supply lines.

[+5V] (Red) = 5V [GND] (Black) = 0V

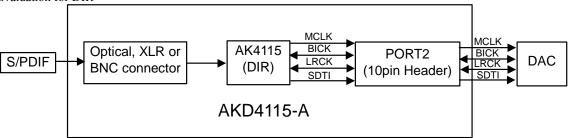
Each supply line should be distributed from the power supply unit.

- (2) Set up the evaluation mode and jumper pins. (Refer to the following item.)
- (3) Connect cables. (Refer to the following item.)
- (4) Power on.

The AK4115 should be reset once bringing PDN (SW2) "L" upon power-up.

■ Evaluation modes

(1) Evaluation for DIR



The DIR generates MCLK, BICK, LRCK and SDATA from the received data through optical connector(PORT1: TORX176), BNC connector or cannon connector(XLR). The AKD4115 can be connected with the AKM's DAC evaluation board via 10-pin cable.

a. Set-up of Bi-phase Input

RXP0/RXN0 and RX1-7 should not select BNC at the same time.

a-1. RXP0/RXN0

Connector	JP2(RXP0)	JP3(RXN0)	
Optical (PORT1)	OPT	BNC	
XLR (J1)	XLR	XLR	
BNC (J2)	BNC	BNC	

Table 1. Set-up of RXP0/RXN0

a-2. RX1, 2, 3, 4, 5, 6, and 7 can be inputted from a BNC (J2) connector only.

Only RX1, RX2 and RX 3 can be used in parallel mode. The jumper which selects the Rx channel should be Short.

Input	RX1	RX2	RX3	RX4	RX5	RX6	RX7
JP	JP4	JP5	JP6	JP7	JP8	JP9	JP10
JP	Short	Short	Short	RX4	RX5	RX6	RX7

Table 2. Set-up of RX1, 2, 3, 4, 5, 6 and 7

a-3. Set-up of AK4115 input path

In Parallel Mode you will need to use SW1_1 & SW1_5. In Serial Mode you will need to use IPS2-0 bits.

-	IPS1 pin (SW1_5)	IPS0 pin (SW1_1)	INPUT Data
IPS2 bit	IPS1 bit	IPS0 bit	
0	0	0	RX0
0	0	1	RX1
0	1	0	RX2
0	1	1	RX3
1	0	0	RX4
1	0	1	RX5
1	1	0	RX6
1	1	1	RX7

Default

(In parallel mode, IPS2 is fixed to "0") Table 3. Recovery Data Select

b. Set-up of clock input and output

The signal level outputted/inputted from PORT2 is 3.3V.

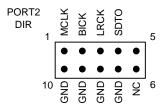


Figure 2. PORT2 pin layout

b-1. MCKO1/MCKO2

The output of MCKO1 pin or MCKO2 pin can be selected by JP12. The output frequency of MCKO1/MCKO2 is selected by OCKS 1-0.

Output signal	JP12	
MCKO1	MCKO1	Default
MCKO2	MCKO2	

Table 4. MCKO1/MCKO2 set-up

OCKS1 pin (SW3_2) OCKS1 bit	OCKS0 pin (SW3_3) OCKS0 bit	(X'tal)	MCKO1	MCKO2	fs (max)	
0	0	256fs	256fs	256fs	96 kHz	Default
0	1	256fs	256fs	128fs	96 kHz	
1	0	512fs	512fs	256fs	48 kHz	
1	1	128fs	128fs	64fs	192 kHz	

Table 5. Master Clock Frequency Select

b-2. Set-up of BICK and LRCK input and output

Please select SW 3_7 (DIR_I/O) according to the setup of audio format of AK4115 (Refer to Table 7).

Audio format	SW3_7 (DIR_I/O)	
Slave mode	0	
Master mode	1	

Default

Table 6. DIR_I/O set-up

c. Set-up of Audio format

It sets up by SW 1_2 and SW 1_3 in parallel mode. Please set up DIF2-0 bit and AES3 bit in serial mode.

Mode	-	-	DIF1 pin (SW1_3)	DIF0 pin (SW1_2)	DAUX	SDTO	LR	CK	BICI	Κ
Wiode	AES3 bit	DIF2 bit	DIF1 bit	DIF0 bit	DAUX	3010		I/O		I/O
0	0	0	0	0	24bit, Left justified	16bit, Right justified	H/L	О	64fs	О
1	0	0	0	1	24bit, Left justified	18bit, Right justified	H/L	О	64fs	О
2	0	0	1	0	24bit, Left justified	20bit, Right justified	H/L	О	64fs	О
3	0	0	1	1	24bit, Left justified	24bit, Right justified	H/L	О	64fs	О
4	0	1	0	0	24bit, Left justified	24bit, Left justified	H/L	О	64fs	О
5	0	1	0	1	24bit, I ² S	24bit, I ² S	L/H	О	64fs	O
6	0	1	1	0	24bit, Left justified	24bit, Left justified	H/L	I	64-128f s	I
7	0	1	1	1	24bit, I ² S	24bit, I ² S	L/H	I	64-128f s	I
8	1	X	X	X	24bit, Left justified	AES3 Mode	H/L	О	64fs	О

Default

Table 7. Audio format

- 4 -

d. Set-up of CM1 and CM0

The operation mode of PLL is selected by CM1 and CM0. In parallel mode, it can be selected by SW3_4, SW3_1 and JP18. In serial mode, it can be selected by PSEL bit and CM1-0 bits.

PSEL pin (SW3_4) PSEL bit	CM1 pin (SW3_1) CM1 bit	CM0 pin (JP18) CM0 bit	(UNLOCK)	PLL	X'tal	Clock source	SDTO source	
0	0	0	-	ON	ON(Note)	PLL(RX)	RX	Default
0	0	1	-	OFF	ON	X'tal	DAUX	
0	1	0	0	ON	ON	PLL(RX)	RX	
U	1	U	1	ON	ON	X'tal	DAUX	
0	1	1	-	ON	ON	X'tal	DAUX	
1	0	0	-	ON	ON(Note)	PLL(ELRCK)	DAUX	
1	0	1	-	OFF	ON	X'tal	DAUX	
1	1	0	0	ON	ON	PLL(ELRCK)	DAUX	
	1	U	1	ON	ON	X'tal	DAUX	

ON: Oscillation (Power-up), OFF: STOP (Power-Down)

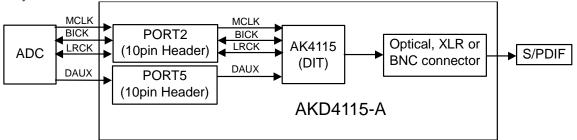
Note: When the X'tal is not used as clock comparison for fs detection (XTL0, 1= "1,1"), the X'tal is OFF.

Table 8. Clock Operation Mode Select

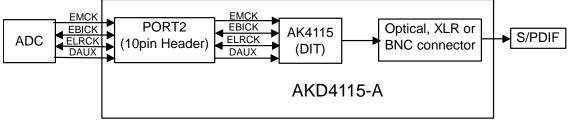
- 5 -

(2) Evaluation for DIT

1. Synchronous mode



2. Asynchronous mode



MCLK, BICK, LRCK and DAUX are input the via 10pin header (PORT5: DIT). The AKD4115-A can be connected with the AKM's ADC evaluation board via 10-pin cable.

a. Set-up of a Bi-phase output signal

TX0 and TXP0/TXN0 should not select an optical connector or a BNC connector at the same time.

a-1. The data outputted from TXP1/TXN1 can be selected by OPS12-10 bit.

Connector	JP19 (TXP1)	JP14 (TXN1)
Optical (PORT4)	OPT	BNC
XLR (J3)	XLR	XLR
BNC (J4)	BNC	BNC

Table 9. Set-up of TXP1/TXN1

a-2. As for TX0, only the loop back mode of RX corresponds. This mode is fixed to RX0 in parallel mode. In serial mode, it can be selected by OPS02-00 bits.

Connector	JP13 (TX0)	JP19 (TXP1)	JP14 (TXN1)
Optical (PORT4)	OPT	Open	BNC
BNC (J4)	BNC	Open	BNC

Table 10. Set-up of TX0

b. Set-up of clock input and output

b-1. In the case of synchronous mode (ASYNC bit="0" or Parallel mode)

The used signals are MCKO1, MCKO2, LRCK, BICK, ELRCK and DAUX. The signal level outputted and inputted from PORT2 and PORT5 is 3.3V.

Clock	PORT
MCLK	PORT2
BICK	PORT2
LRCK	PORT2
DAUX	PORT5
ELRCK	PORT5(LRCK)

Table 11. Clock input and output

b-1-1. MCKO1/MCKO2

The output of MCKO1 pin or MCKO2 pin can be selected by JP12. The output frequency of MCKO1/MCKO2 sets up by OCKS 1-0.

Default

Default

Output signal	JP12	JP15	JP11
MCKO1	MCKO1	MCKO	MCKO1
MCKO2	MCKO2	MCKO	MCKO2

Table 12. Selection of MCKO1/MCKO2

OCKS1 pin (SW3_2) OCKS1 bit	OCKS0 pin (SW3_3) OCKS0 bit	(X'tal)	MCKO1	MCKO2	fs (max)	
0	0	256fs	256fs	256fs	96 kHz	Default
0	1	256fs	256fs	128fs	96 kHz	
1	0	512fs	512fs	256fs	48 kHz	
1	1	128fs	128fs	64fs	192 kHz	

Table 13. Master Clock Frequency Select

b-1-2. Set-up of BICK and LRCK input and output

Please select SW 3_7 (DIR_I/O) according the setup of audio format of AK4115 (Refer to Table 7).

Audio format	SW3_7 (DIR_I/O)	
Slave mode	0	Default
Master mode	1	

Table 14. Set-up DIR I/O

b-1-3. A set up of ELRCK

As a reference clock of PLL, when using ELRCK clock, it inputs from PORT5 (LRCK).

	JP16	JP17
When inputting by AC coupling	AC	AC
When inputting by CMOS level	DC	DC

Table 15. Set-up of ELRCK input

b-2. In the case of the asynchronous mode (ASYNC bit="1", This mode is supported in serial mode.)

The used signals are EMCK, X'tal, EBICK, ELRCK, and DAUX. These signal levels outputted / inputted from PORT5 is 3.3V.

Clock	PORT
MCLK	PORT5
BICK	PORT5
LRCK	PORT5
DAUX	PORT5
ELRCK	PORT5

Table 16. Clock input and output b-2-1. Set-up of Master clock

When EMCK is used

Output signal	MSEL bit	JP15
EMCK	1	EMCK

Table 17. Selection of EMCK

When X'tal is used as master clock

Output signal	JP12	JP15	JP11
MCKO1	MCKO1	MCKO	MCKO1
MCKO2	MCKO2	MCKO	MCKO2

Table 18. Selection of MCKO1/MCKO2

b-2-2. Setup of BICK and LRCK input and output

Please set up SW 3_8 (DIT_I/O) according to the setup of audio format of AK4115 (Refer to Table 20). JP16 and 17 are fixed to the "DC" side.

Audio format	SW3_8 (DIT_I/O)
Slave mode	0
Master mode	1

Default

Table 19. DIT I/O set-up

c. Set-up of audio data format

c-1. In case of synchronous mode.

Please refer to Table 7.

c-2. In case of asynchronous mode

Mode	EDIF1 bit	EDIE0 bit	DAUX	ELR	CK	EBICK		
Wiode	LDII I UII	LDII 0 01t	DAUA		I/O		I/O	
4	0	0	24bit, Left justified	H/L	О	64fs	О	
5	0	1	24bit, I ² S	L/H	О	64fs	О	
6	1	0	24bit, Left justified	H/L	I	64-128fs	I	Default
7	1	1	24bit, I ² S	L/H	I	64-128fs	I	

Table 20. Audio data format in asynchronous mode

d. Set-up of PSEL, CM1 and CM0

d-1. In case of synchronous mode.

Please refer to Table 8.

d-2. In case of asynchronous mode

CM1	CM0					RX]
bit	bit	(UNLOCK)	PLL	X'tal	Clock	Clock	SDTO	Clock	Clock	
O1t	Oit				source	I/O	3010	source	I/O	
					DI I			X'tal or		
0	0	-	ON	ON(Note 2)	PLL	Note 3	RX	EMCK	Note 4	Default
					(RX)			(Note 5)		
0	1		OFF	ON	V'ta1	Note 2	"L"	X'tal or	Note 1	
0	1	-	OFF	ON	X'tal	Note 3	L	EMCK	Note 4	
		0	ON	ON	PLL	Note 2	RX	X'tal or	Note 1	
1	0	U	ON	ON	(RX)	Note 3	KA	EMCK	Note 4	
1	0	1	ON	ON	X'tal	Note 3	"L"	X'tal or	Note 1	
		1	ON	ON	A tai	Note 3	L.	EMCK	Note 4	
1	1		ON	ON	V'tal	Note 2	"L"	X'tal or	Note 4	
1	1	-	ON	ON	X'tal	Note 3	L.	EMCK	Note 4	

ON: Oscillation (Power-up), OFF: STOP (Power-Down)

Note 2: When the X'tal is not used as clock comparison for sampling frequency detection (i.e. XTL1, 0 = "1, 1"), the X'tal is OFF. Note 3: MCKO1/2, BICK, LRCK

Note 4: EMCK OR X'tal, EBICK, ELRCK, DAUX

Note 5: When X'tal is OFF, the clock source supports EMCK only.

Table 21. Clock Operation Mode Select

-9-

■ B, C, U, V Inputs and output

B(block start), C(channel status), U(user data) and V(validity) are inputted via 10pin header (PORT3: BCUV). When BCU_IO bit is set to "1", they are input signals. And when BCU_IO bit is set to "0", they are output signals. In parallel mode, they are fixed to output signals. Pin arrangement of PORT3 has become like Figure 3.

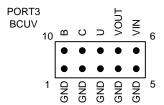


Figure 3. PORT3 pin layout

■ Serial control

The AK4115 can be controlled via the printer port (parallel port) of IBM-AT compatible PC. Connect the included 10pin cable to PORT6 (uP-I/F) of the AKD4115-A. Take care of the direction of connector. There is a mark at pin#1. And the pin layout of PORT6 is as Figure 4 shows.

Mode	SW1_5	JP18
4 wire Serial	L	CDTO/CM0="H" (Short)
IIC	Н	SDA (Short) CM0="L" (Short) (Note)

Note: In IIC mode, the chip address is fixed to "01". Table 22. Set-up of Parallel mode and Serial mode

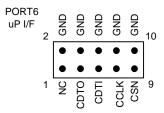


Figure 4. PORT6 pin layout

The evaluation board also includes control software and a software operation procedure is included in the evaluation board manual.

■ Toggle switch set-up

_	- 33		
	SW2	PDN	Reset switch for AK4115. Set to "H" during normal operation. Bring to "L" once after the power is supplied.

■ LED indication

	LE1	INT0	Bright when INT0 pin goes to "H".
1	LE2	INT1	Bright when INT1 pin goes to "H".

■ DIP switch (SW1) set-up: -off- means "L"

No.	Switch Name	Function	Default
1	IPS0	Set-up of IPS0 pin. (in parallel mode)	OFF
2	DIF0	Set-up of DIF0 pin. (in parallel mode)	OFF
3	DIF1	Set-up of DIF1 pin. (in parallel mode)	
4	XSEL	Set-up of XSEL pin. (in parallel mode) "L": X'tal 1, "H": X'tal 2	OFF
5	IPS1/IIC	Set-up of IPS1 pin. (in parallel mode) Set-up of IIC pin. (in serial mode) "L": 4 wire Serial, "H": IIC	
6	P/SN	Set-up of P/SN pin. "L": Serial mode, "H": parallel mode OF	
7	TEST	Set-up of TEST pin. (always "OFF")	OFF
8	ACKS	Set-up of ACKS pin. (in parallel mode) "L": Manual Setting, "H": Auto Setting	OFF

Table 23

■ DIP switch (SW3) set-up: -off- means "L"

No.	Switch Name	Function	Default
1	CM1	Set-up of CM1 pin. (in parallel mode)	OFF
2	OCKS1	Set-up of OCKS1 pin. (in parallel mode)	OFF
3	OCKS0	Set-up of OCKS0 pin. (in parallel mode)	OFF
4	PSEL	Set-up of PSEL pin. (in parallel mode) "L": S/PDIF Input, "H": ELRCK Input Clock	OFF
5	XTL0	Set-up of XTL0 pin.	OFF
6	XTL1	Set-up of XTL1 pin.	OFF
7	DIR_I/O	Set-up of the transmission direction of 74AC245 "L": When inputting from PORT2, "H": When outputting from PORT2	ON
8	DIT_I/O	Set-up of the transmission direction of 74AC245 "L": When inputting from PORT5, "H": When outputting from PORT5.	OFF

Table 24

■ Set-up of XSEL, XTL1 and XTL0

SW1_4	Status	
XSEL	X'tal #1	X'tal #2
0	Power-Up	Power-Down
1	Power-Down	Power-Up

Table 25. Setting of X'tal oscillator

SW3_6	SW3_5	X'tal Frequency			
XTL1	XTL0	X'tal #1	X'tal #2		
0	0	11.2896MHz	Default		
0	1	12.288MHz 11.2896MHz			
1	0	24.576MHz 22.5792MHz			
1	1	(Use channel status)			

Table 26. Reference X'tal frequency

■ Jumper set up.

No.	Jumper Name	Function		
		Set-up of Power supply source for 74AC245.		
1	D3V/VD	D3V : D3V (default)		
		VD: VD		
		Set-up of RXP0 input circuit.		
2	RXP0	OPT : Optical (default)		
2		XLR : XLR		
		BNC : BNC		
		Set-up of RXP0 input circuit.		
3	RXN0	OPT : Optical (default)		
		BNC : BNC		
4,5,6	RX1-3	Set-up of RX1-3 input circuit.		
		RX4-7 set-up depending serial/parallel mode		
7,8,9,10	RX4-7	RX4-7 : Serial mode (default)		
, , ,		DIF2-0,IPS0 : Parallel mode		
	DID MCL I/	MCKO set-up for PORT5(DIT) and PORT2(DIR)		
11,12	DIR MCLK ,	MCKO1: MCKO1 of AK4115 (default)		
	DIT MCLK	MCKO2 : MCKO2 of AK4115		
		Set-up of TX0 output circuit.		
13	TX0	OPT : Optical		
		BNC : BNC (default)		
	TXN1	Set-up of TXN1 output circuit.		
14		XLR : XLR		
		BNC : BNC (default)		
	MCLK	MCLK input output selection of PORT5(DIT).		
15		MCKO : MCKO (default)		
		EMCK : EMCK		
	ELRCK	Set-up of ELRCK input signal.		
16,17		AC: AC		
		DC : DC (default)		
	SDA/CDTO	Set-up of SDA/CDTO pin.		
18		4 wire Serial: CDTO/CM0="H" (default)		
		IIC : SDA		
	TXP1	Set-up of TXP1 input circuit.		
19		OPT : Optical (default)		
19		XLR : XLR		
		BNC : BNC		

Control Software Manual

■ Set-up of evaluation board and control software

- 1. Set up the AKD4115-A according to previous term.
- 2. Connect IBM-AT compatible PC with AKD4115-A by 10-line type flat cable (packed with AKD4115-A). Take care of the direction of 10pin header. (Please install the driver in the CD-ROM when this control software is used on Windows 2000/XP. Please refer "Installation Manual of Control Software Driver by AKM device control software". In case of Windows95/98/ME, this installation is not needed. This control software does not operate on Windows NT.)
- 3. Insert the CD-ROM labeled "AKD4115-A Evaluation Kit" into the CD-ROM drive.
- 4. Access the CD-ROM drive and double-click the icon of "akd4115-a.exe" to set up the control program.
- 5. Then please evaluate according to the follows.

■ Operation flow

Keep the following flow.

- 1. Set up the control program according to explanation above.
- 2. Click "Port Reset" button.
- 3. Click "Write default" button

■ Explanation of each buttons

 $[Port\ Reset]: \hspace{1.5cm} Set\ up\ the\ USB\ interface\ board\ (AKDUSBIF-A)\ .$

[Write default]: Initialize the register of AK4115.

[All Write]: Write all registers that is currently displayed.[Function1]: Dialog to write data by keyboard operation.[Function2]: Dialog to write data by keyboard operation.

[Function3]: The sequence of register setting can be set and executed.

[Function4]: The sequence that is created on [Function3] can be assigned to buttons and executed. [Function5]: The register setting that is created by [SAVE] function on main window can be assigned to

buttons and executed.

[SAVE]: Save the current register setting.[OPEN]: Write the saved values to all register.[Write]: Dialog to write data by mouse operation.

■ Indication of data

Input data is indicated on the register map. Red letter indicates "H" or "1" and blue one indicates "L" or "0".

■ Explanation of each dialog

1. [Write Dialog]: Dialog to write data by mouse operation

There are dialogs corresponding to each register.

Click the [Write] button corresponding to each register to set up the dialog. If you check the check box, data becomes "H" or "1". If not, "L" or "0".

If you want to write the input data to the AK4115, click [OK] button. If not, click [Cancel] button.

2. [Function1 Dialog]: Dialog to write data by keyboard operation

Address Box: Input registers address in 2 figures of hexadecimal.

Input registers data in 2 figures of hexadecimal.

If you want to write the input data to the AK4115, click [OK] button. If not, click [Cancel] button.

3. [Function2 Dialog]: Dialog to evaluate volume

Address Box: Input registers address in 2 figures of hexadecimal.

Start Data Box: Input starts data in 2 figures of hexadecimal.

Input end data in 2 figures of hexadecimal.

Interval Box: Data is written to the AK4115 by this interval.

Step Box: Data changes by this step.

Mode Select Box:

If you check this check box, data reaches end data, and returns to start data.

[Example] Start Data = 00, End Data = 09

Data flow: 00 01 02 03 04 05 06 07 08 09 09 08 07 06 05 04 03 02 01 00

If you do not check this check box, data reaches end data, but does not return to start data.

Example] Start Data = 00, End Data = 09 Data flow: 00 01 02 03 04 05 06 07 08 09

If you want to write the input data to the AK4115, click [OK] button. If not, click [Cancel] button.

4. [SAVE] and [OPEN]

4-1. [SAVE]

All of current register setting values displayed on the main window are saved to the file. The extension of file name is "akr".

<Operation flow>

- (1) Click [SAVE] Button.
- (2) Set the file name and click [SAVE] Button. The extension of file name is "akr".

4-2. [OPEN]

The register setting values saved by [SAVE] are written to the AK4115. The file type is the same as [SAVE].

- <Operation flow>
- (1) Click [OPEN] Button.
- (2) Select the file (*.akr) and Click [OPEN] Button.

5. [Function3 Dialog]

The sequence of register setting can be set and executed.

- (1) Click [F3] Button.
- (2) Set the control sequence.
 Set the address, Data and Interval time. Set "-1" to the address of the step where the sequence should be paused.
- (3) Click [START] button. Then this sequence is executed.

The sequence is paused at the step of Interval="-1". Click [START] button, the sequence restarts from the paused step.

This sequence can be saved and opened by [SAVE] and [OPEN] button on the Function3 window. The extension of file name is "aks".

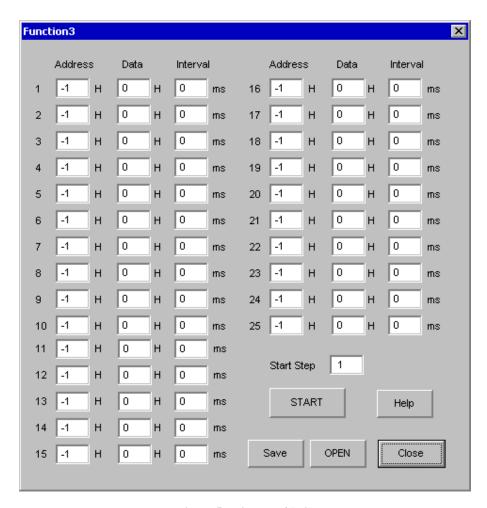


Figure 5. Window of [F3]

6. [Function4 Dialog]

The sequence file (*.aks) saved by [Function3] can be listed up to 10 files, assigned to buttons and then executed. When [F4] button is clicked, the window as shown in Figure 10 opens.

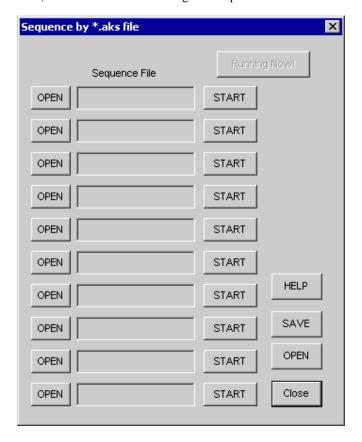


Figure 6. [F4] window

6-1. [OPEN] buttons on left side and [START] buttons

(1) Click [OPEN] button and select the sequence file (*.aks) saved by [Function3].

The sequence file name is displayed as shown in Figure 11. (In case that the selected sequence file name is "DAC_Stereo_ON.aks")

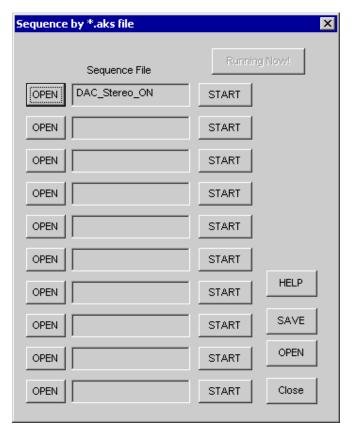


Figure 7. [F4] window(2)

(2) Click [START] button, then the sequence is executed.

6-2. [SAVE] and [OPEN] buttons on right side

[SAVE] : The name assign of sequence file displayed on [Function4] window can be saved to the file. The extension of the file is "*.ak4".

[OPEN]: The name assign of sequence file(*.ak4) saved by [SAVE] is loaded.

6-3. Note

- (1) This function doesn't support the pause function of sequence function.
- (2) All files used by [SAVE] and [OPEN] function on right side need to be in the same folder.
- (3) When the sequence is changed in [Function3], the sequence file (*.aks) should be loaded again in order to reflect the change.

7. [Function5 Dialog]

The register setting file(*.akr) saved by [SAVE] function on main window can be listed up to 10 files, assigned to buttons and then executed. When [F5] button is clicked, the window as shown in Figure 12 opens.

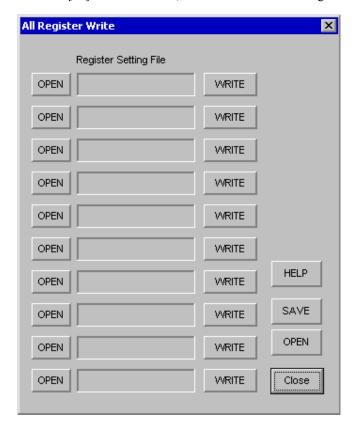


Figure 8. [F5] window

7-1. [OPEN] buttons on left side and [WRITE] button

(1) Click [OPEN] button and select the register setting file (*.akr).

The register setting file name is displayed as shown in Figure 13. (In case that the selected file name is "DAC_Output.akr")

(2) Click [WRITE] button, then the register setting is executed.

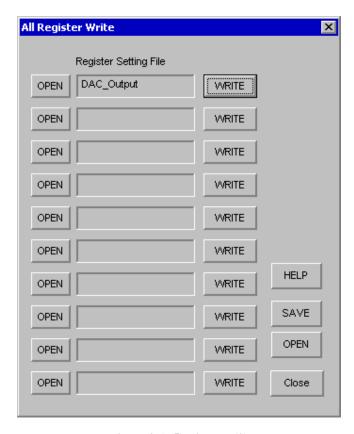


Figure 9. [F5] windows(2)

7-2. [SAVE] and [OPEN] buttons on right side

[SAVE]: The name assign of register setting file displayed on [Function5] window can be saved to the file. The file name is "*.ak5".

[OPEN]: The file extension assignment of the register setting file(*.ak5) saved by [SAVE] is loaded.

7-3. Note

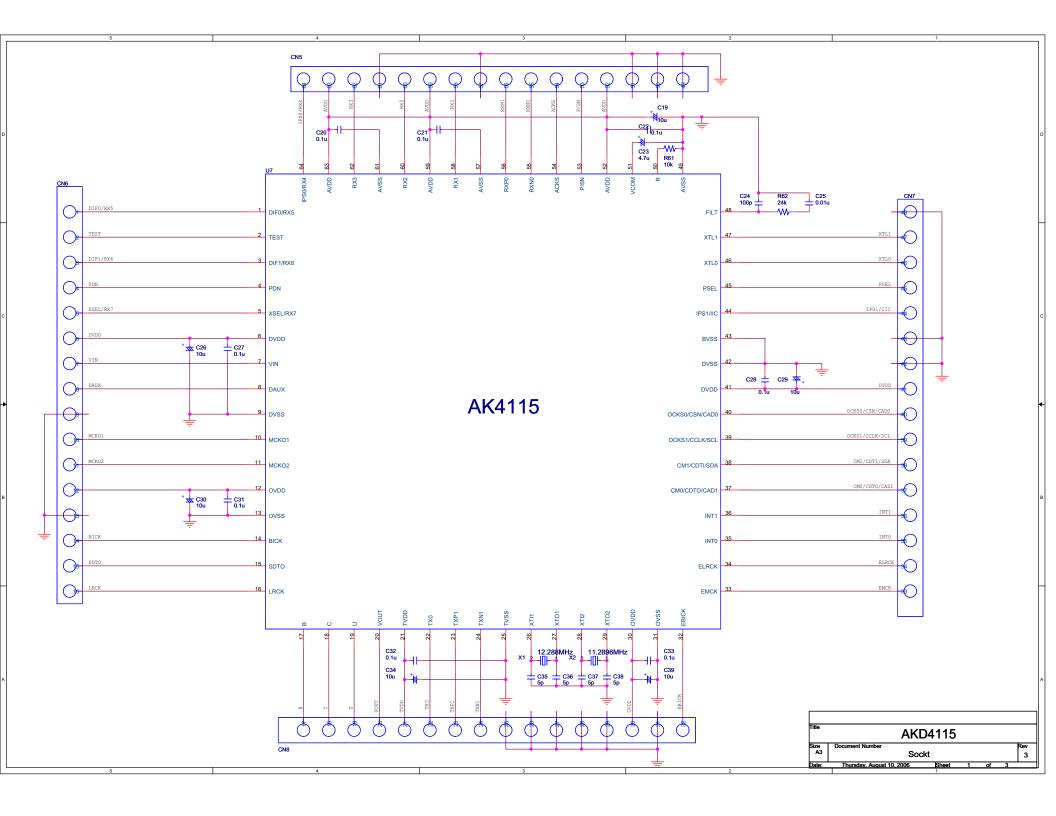
- (1) All files used by [SAVE] and [OPEN] function on right side need to be in the same folder.
- (2) When the register setting is changed by [SAVE] Button on the main window, the register setting file (*.akr) should be loaded again in order to reflect the change.

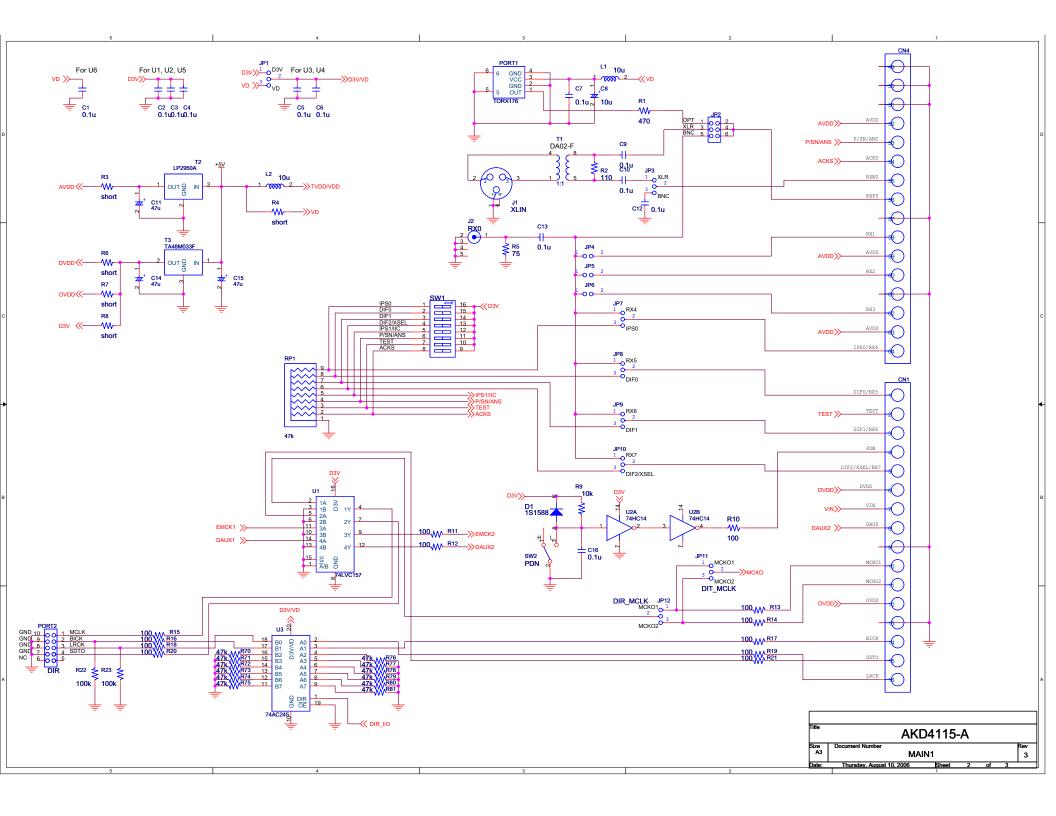
Revision History

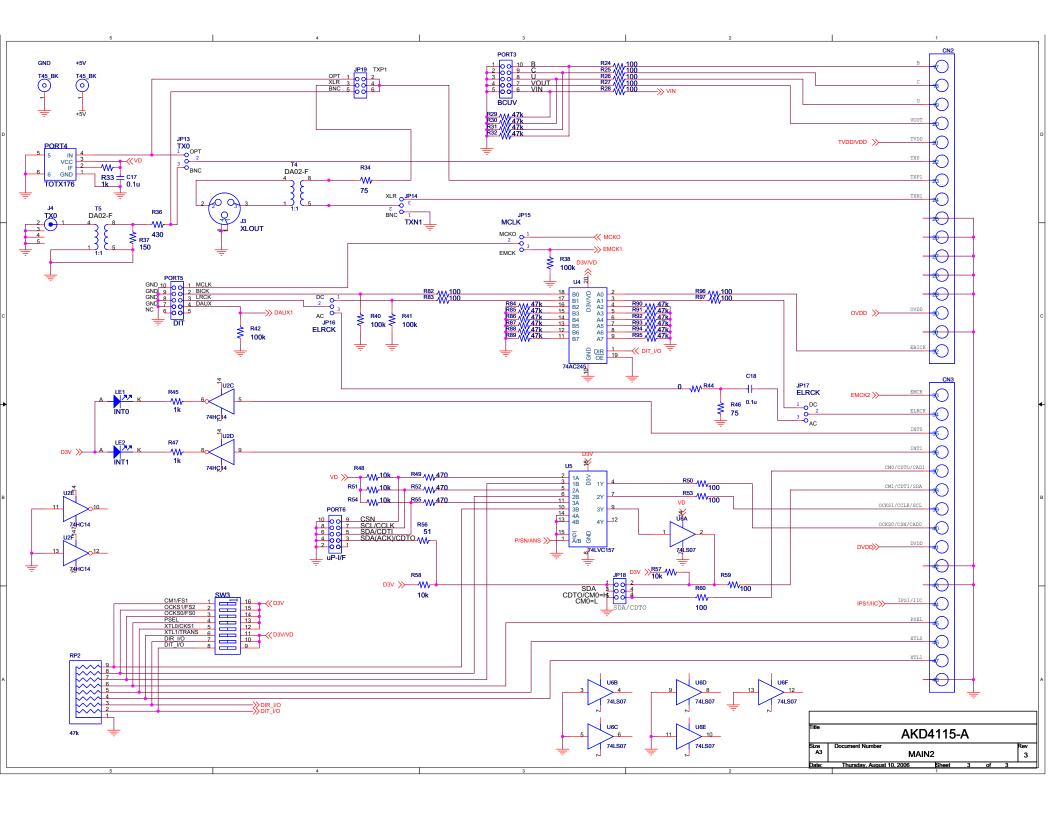
Date (YY/MM/DD)	Manual Revision	Board Revision	Reason	Contents
04/12/08	KM076400	0	First edition	
06/02/15	KM076401	1	Modification	 Circuit diagram was changed (page 1/3). The R61 changed from 15kΩ to 10kΩ.
06/06/15	KM076402	2		P13 "Instruction for use" was added.
				Control software was updated: 1.0 → 3.0 Control software manual was changed: P13-14 → P14-21
				P10 • SW_6 → SW_5 • CDTO/CM0="H" → CDTO/CM0="H" (Short) • SDA and CM0="L" → SDA (Short) CM0="L" (Short)
06/08/10	KM076403	3	Change device Revision Delete the explanation	AK4115: Rev. C → Rev. D P13 "Instruction for use" was deleted.
			Change control software	Control software was updated: $3.0 \rightarrow 4.0$

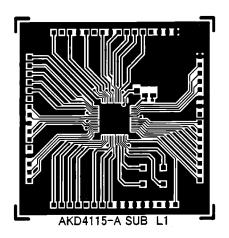
IMPORTANT NOTICE

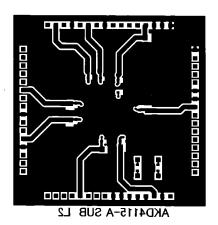
- These products and their specifications are subject to change without notice. Before considering any use or application, consult the Asahi Kasei Microsystems Co., Ltd. (AKM) sales office or authorized distributor concerning their current status.
- AKM assumes no liability for infringement of any patent, intellectual property, or other right in the application or use of any information contained herein.
- Any export of these products, or devices or systems containing them, may require an export license or other official approval under the law and regulations of the country of export pertaining to customs and tariffs, currency exchange, or strategic materials.
- AKM products are neither intended nor authorized for use as critical components in any safety, life support, or other hazard related device or system, and AKM assumes no responsibility relating to any such use, except with the express written consent of the Representative Director of AKM. As used here:
 - (a) A hazard related device or system is one designed or intended for life support or maintenance of safety or for applications in medicine, aerospace, nuclear energy, or other fields, in which its failure to function or perform may reasonably be expected to result in loss of life or in significant injury or damage to person or property.
 - (b) A critical component is one whose failure to function or perform may reasonably be expected to result, whether directly or indirectly, in the loss of the safety or effectiveness of the device or system containing it, and which must therefore meet very high standards of performance and reliability.
- It is the responsibility of the buyer or distributor of an AKM product who distributes, disposes of, or otherwise places the product with a third party to notify that party in advance of the above content and conditions, and the buyer or distributor agrees to assume any and all responsibility and liability for and hold AKM harmless from any and all claims arising from the use of said product in the absence of such notification.

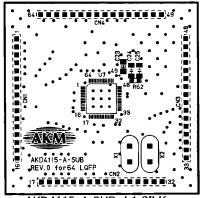




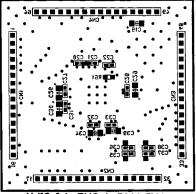




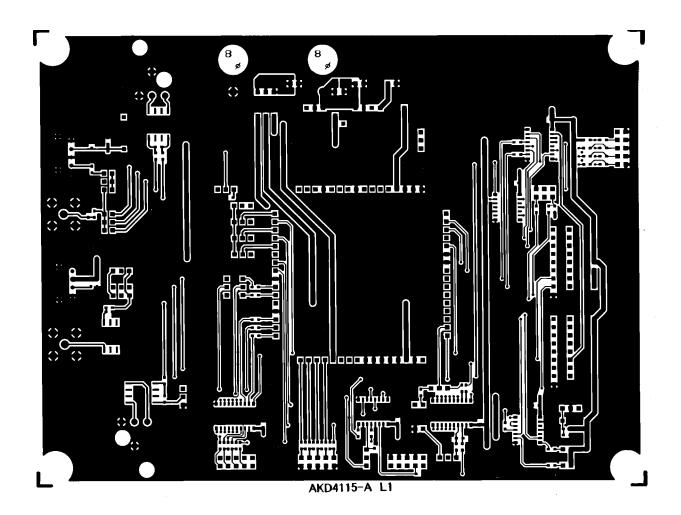


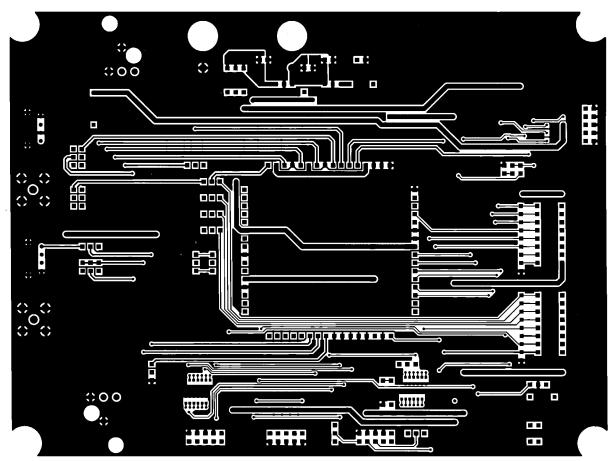


AKD4115-A SUB L1_SILK

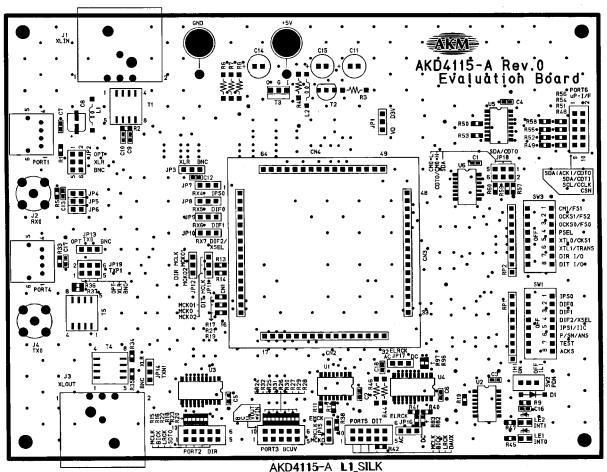


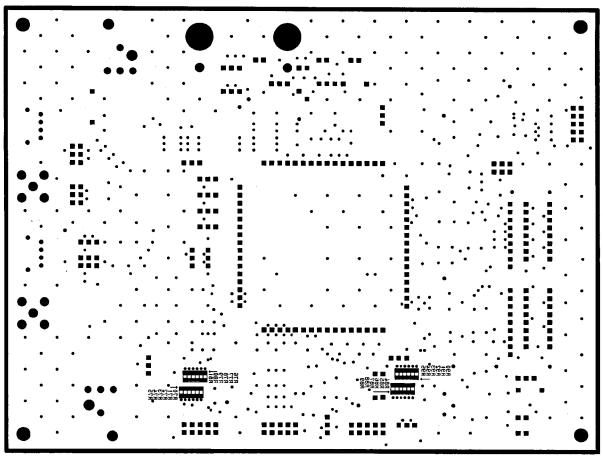
AKD4115-A SUB L2_SILK





AKD4115-A L2





AKD4115-A L2_SILK