

TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

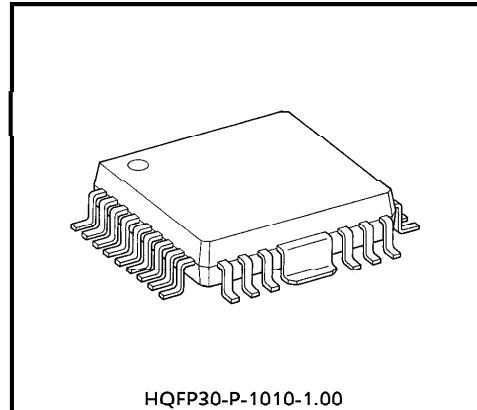
TA8463F

SINGLE CHIP 3 PHASE MOTOR DRIVER FOR FDD SPINDLE MOTOR.

The TA8463F is Single Chip Motor Driver IC for FDD Spindle Motor.

FEATURES

- 1 Chip motor driver with 3 phase semi-linear driving.
- Adjustment free with digital servo system.
- 300, 360rpm are obtained.
- Built-in index pulse output current.
- Operating supply voltage range : $V_{CC} = 4.2 \sim 7V$
- Output current : $I_O (\text{MAX.}) = 0.5A (\text{AVE.})$
- Built-in thermal shutdown circuit.
- Built-in over current protection circuit.
- Built-in stand-by circuit.



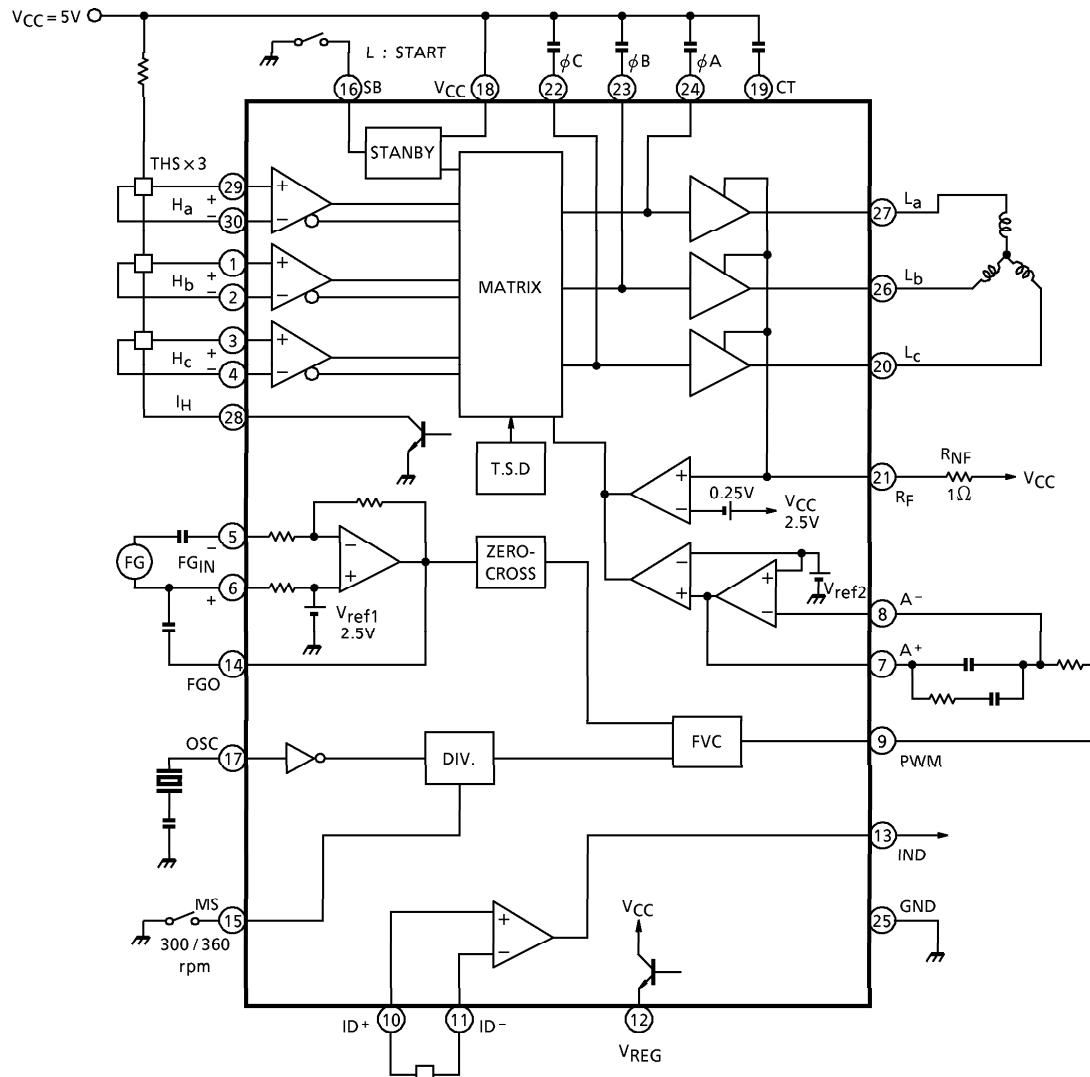
HQFP30-P-1010-1.00

Weight : 0.61g (Typ.)

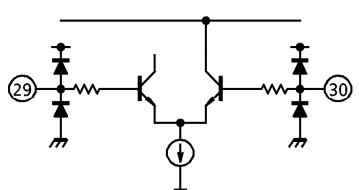
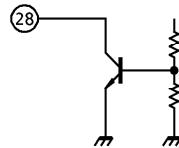
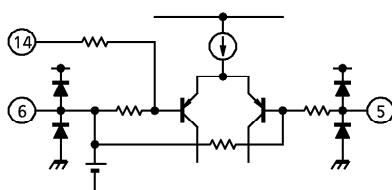
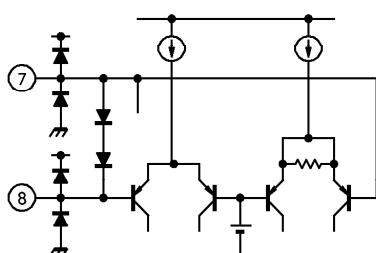
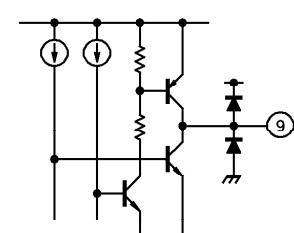
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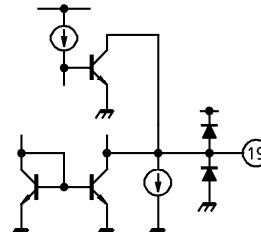
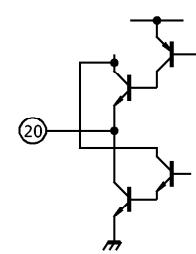
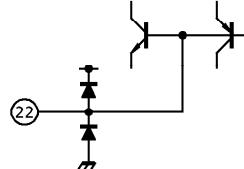
BLOCK DIAGRAM



PIN FUNCTION

PIN No.	SYM-BOL	FUNCTIONAL DESCRIPTION	EQUIVALENT CIRCUIT
29 30 1 2 3 4	H_a^+ H_a^- H_b^+ H_b^- H_c^+ H_c^-	<ul style="list-style-type: none"> ● Hall Amp. + / - Input Terminal. <p>The Hall Input Range is ; $V_H = 50 \sim 300$ [mV_{p-p}] $CMR = 1.3 \sim (V_{CC} - 0.9)$ [V]</p>	
28	I_H	<ul style="list-style-type: none"> ● Hall Bias Negative Side Connecting Terminal. <p>Open collector output.</p>	
5 6 14	FG_{IN}^- FG_{IN}^+ FG_O	<ul style="list-style-type: none"> ● FG Amp. Negative Input Terminal. ● FG Amp. Positive Input Terminal. ● FG Amp. Output Terminal. <p>High Sensitivity of FG Amp. ; $V_{HFG} = 2.5$mV</p>	
7 8	A^+ A^-	<ul style="list-style-type: none"> ● Error Amp. Output Terminal. ● Error Amp. Input Terminal. <p>External Ports Value (C.R) is determined by matching between Motor and IC.</p>	
9	PWM	<ul style="list-style-type: none"> ● F / V Converter Output Terminal <p>Reference : No.7 and No.8</p>	

PIN No.	SYM-BOL	FUNCTIONAL DESCRIPTION	EQUIVALENT CIRCUIT
10 11	ID + ID -	<ul style="list-style-type: none"> • Index Positive Input Terminal. • Index Negative Input Terminal. 	
13	IND	<ul style="list-style-type: none"> • Index Amp. Output Terminal. <p>Reference : No.10 and No.11</p>	
15	MS	<ul style="list-style-type: none"> • Mode Select Terminal. <p>300rpm : L 360rpm : H</p>	
16	SB	<ul style="list-style-type: none"> • Stand-by Terminal. <p>SB : H ST : L</p>	
17	OSC	<ul style="list-style-type: none"> • Oscillation Terminal. <p>The correct value of the exterior condenser constant differs depending on the type of ceramic oscillator used. To determine the constant, refer to the oscillator manufacturer.</p> <p>External CK Pulse is used, connect Resistor (min. 20kΩ) in series.</p>	

PIN No.	SYM-BOL	FUNCTIONAL DESCRIPTION	EQUIVALENT CIRCUIT
18	V _{CC}	• Supply Voltage Input Terminal.	
19	CT	• Phase Compensation Terminal. Connect Capacitor between pin ⑩ and GND.	
20 26 27	L _c L _b L _a	• Output Terminals.	
21	R _F	• Power Supply Voltage Input Terminal. By connecting resistors between V _{CC} terminal and pin ⑪, Current Limiter is available. $I_{LIM} = \frac{V_{ISD}}{R_{NF}}$ $V_{ISD} = 0.14V \quad I_O (\text{MAX.}) = 0.5A$	
22 23 24	φC φB φA	• Capacitor Connect Terminal for prevention of oscillation.	
25 Fin	GND	• GND	

MAXIMUM RATINGS ($T_a = 25^\circ\text{C}$)

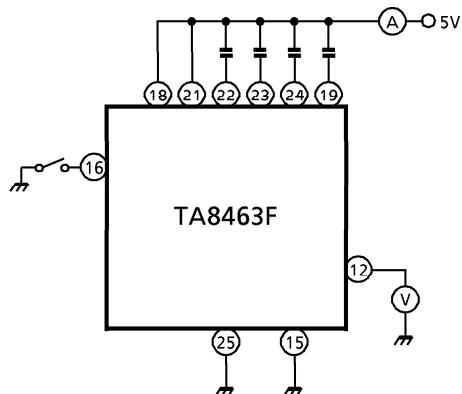
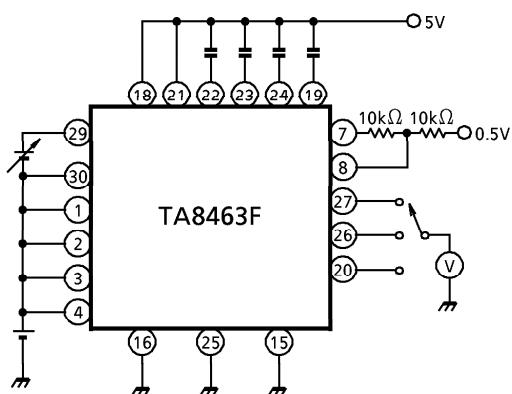
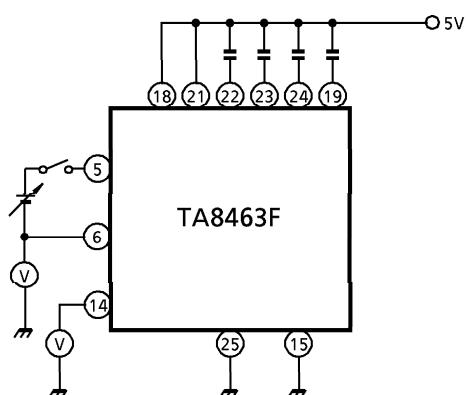
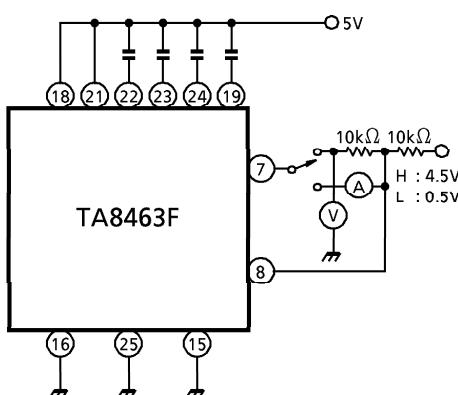
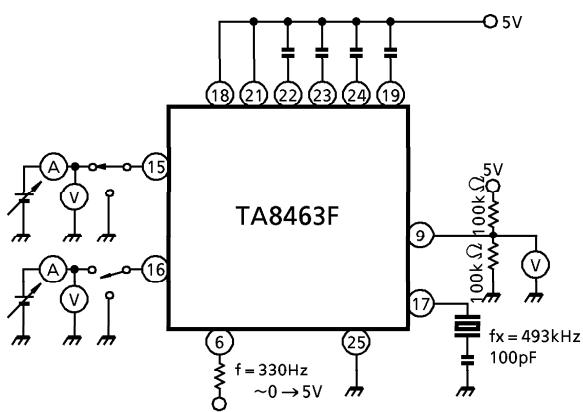
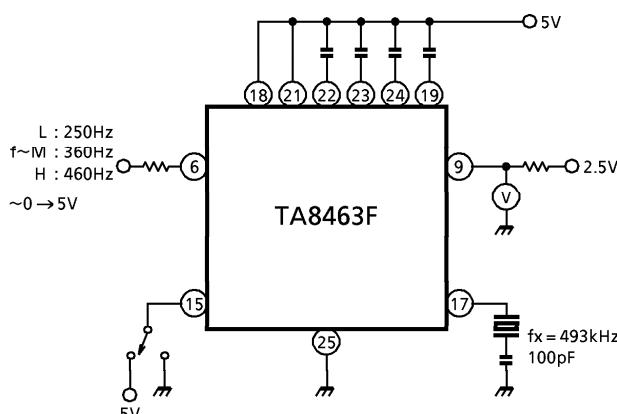
CHARACTERISTIC	SYMBOL	RATING	UNIT
Supply Voltage	V_{CC}	8	V
Output Current	I_O	0.6	A
Power Dissipation	P_D	1.0	W
		(Note) 1.5	
Operating Temperature	T_{opr}	-30~75	$^\circ\text{C}$
Storage Temperature	T_{stg}	-55~150	$^\circ\text{C}$

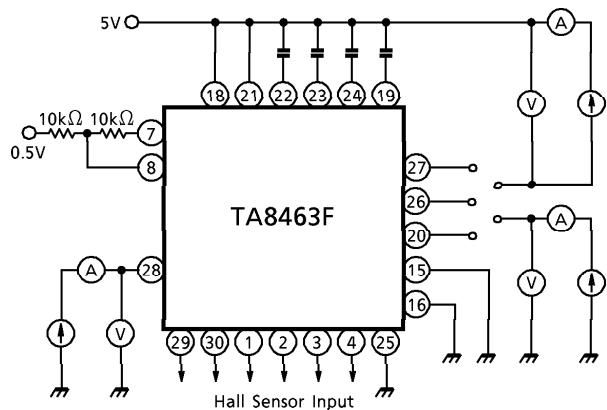
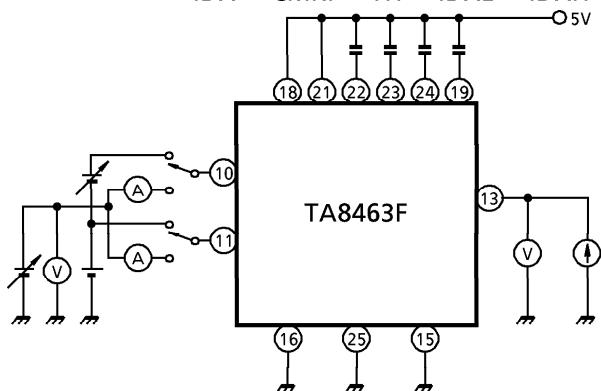
(Note) With Heat-Sink (60×60×1.6mm Cu 50%)

ELECTRICAL CHARACTERISTICS (Unless otherwise specified, $V_{CC} = 5\text{V}$, $T_a = 25^\circ\text{C}$)

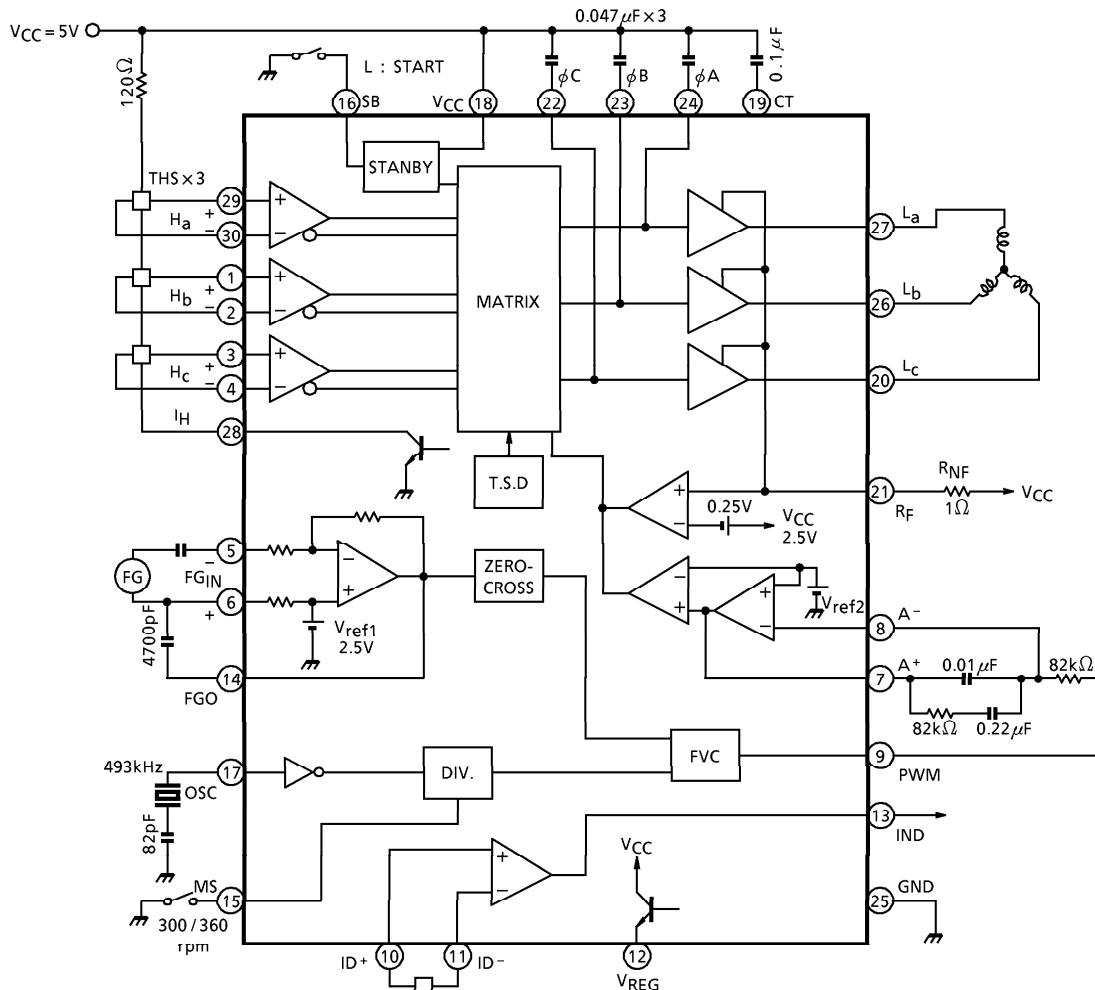
CHARACTERISTIC		SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Supply Current		I_{CC1}	1	SB = OPEN, output open	—	125	200	μA
		I_{CC2}	1	SB = GND, output open	—	23.9	36	mA
Hall Amp.	Gain	G_{HO}	—	Output connection state	—	31	—	dB
	Input Sensitivity	V_H	2		50	—	300	$\text{mV}_{\text{p-p}}$
	Common Mode Voltage Range	V_{CMRH}	2		1.3	—	$V_{CC} - 0.9$	V
PG Amp.	Closed Loop Gain	G_{FGO}	3		40	46	50	dB
	Reference Voltage	V_{ref}	3		2.15	2.6	2.9	V
	Input Sensitivity	V_{HFG}	3		—	2.5	—	$\text{mV}_{\text{p-p}}$
	Input Offset Voltage	V_{OFG}	3		—	1	—	mV
Integrator Amp.	Output Voltage	V_{INT-H}	4		3.4	3.8	4.7	V
	High	V_{INT-L}	4		0.4	1.0	1.6	V
	A-Input Current	I_{A-}	4		—	—	0.4	μA
	Open Loop Gain	G_{INT}	—	-3dB point	—	55	—	dB
Speed Changing	Input Switching Voltage	V_{MS-th}	5	H : 360rpm L : 300rpm	3.0 0	— —	V_{CC} 2.0	V
	Input Current	I_{MS}	5	$V_{MS} = \text{GND}$	—	-2.5	0.1	μA
OSC Frequency Range		f_{osc}	—	$T_j = -30\text{~}125^\circ\text{C}$	300	490	600	kHz

CHARACTERISTIC			SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT		
PWM Output Voltage	High	V _{PWM H}	6	I _{OH} = -100 μ A (fx / 8192) < FG	—	V _{CC} - 0.1	—	—	V		
	Hiddle	V _{PWM M}	6	OUTPUT-V _{CC} : 50k Ω OUTPUT-GND : 50k Ω (fx / 8192) = FG	—	V _{CC} / 2	—	—	V		
	Low	V _{PWM L}	6	I _{OL} = -100 μ A (fx / 8192) > FG	—	0.1	—	—	V		
Output Stage	Static Voltage		V _{MID}	—	G _V (INT) = 1 V = (V _{CC} / 2) + 1V	—	2.2	—	V		
	Output Refferencial Voltage-1		V _{M-diff1}	—	G _V (INT) = 1 V = (V _{CC} / 2) + 1V	—	10	60	mV		
	Output Refferencial Voltage-2		V _{M-diff2}	—	G _V (INT) = 1 V = (V _{CC} / 2) - 1V H _a = H _b = H _c = V _{CC} / 2	—	0.4	—	V		
	Saturation Voltage	Upper	V _{sat U}	7	I _O = 500mA	—	1.1	1.35	V		
		Lower	V _{sat L}	7	I _O = 500mA	—	0.5	0.75	V		
Stand-by Input	Switching Voltage		V _{ST-th}	5	H : Stand-by Mode L : Enable Mode	2.4 0	—	V _{CC} 0.8	V		
	Input Current		I _{ST}	5	V _{ST} = GND	—	0.05	1.0	μ A		
Hall Bias Storation Voltage			V _{SB-SAT}	7	I _{IH} = 10mA I _{IH} = 20mA	— —	0.11 0.19	0.3 0.5	V		
Current Limit Operating Voltage			V _{ISD}	—	R _f Voltage	—	140	—	mV		
Index Stage	Input Current		I _{IDX}	8	—	—	—	3	μ A		
	Common Mode Voltage Range		V _{CMRI}	8	—	1.5	—	V _{CC} - 0.3	V		
	Hysteresis Width		V _{hys}	—	—	—	2.5	—	mV		
	Output Voltage	Low	V _{IDXL}	8	I _O = 1.0mA	—	1.0	0.4	V		
		High	V _{IDXH}	8	I _O = 1.0mA	—	V _{CC}	—	V		
Maximum Input			V _{INI}	8	—	—	—	0.3	V _{p-p}		
Index Sensor Bias			V _{REG}	1	R _L = 1k Ω	2.1	2.5	2.9	V		
Thermal Shutdown Operating Temperature			TSD	—	—	150	—	—	°C		

TEST CIRCUIT 1 I_{CC1} , I_{CC2} , V_{REG} **TEST CIRCUIT 2** V_H , V_{CMRH} **TEST CIRCUIT 3** G_{FGO} , V_{ref} , V_{HFG} , V_{OFG} **TEST CIRCUIT 4** V_{INT-H} , V_{INT-L} , I_A- **TEST CIRCUIT 5** V_{MS-th} , I_{MS} , V_{ST-th} , I_{ST} **TEST CIRCUIT 6** $V_{PWM\ H}$, $V_{PWM\ M}$, $V_{PWM\ L}$ 

TEST CIRCUIT 7 $V_{sat\ U}$, $V_{sat\ L}$, V_{SB-SAT} **TEST CIRCUIT 8** I_{IDX} , V_{CMRI} , V_{TH} , V_{IDXL} , V_{IDXH} , V_{INI} 

APPLICATION CIRCUIT

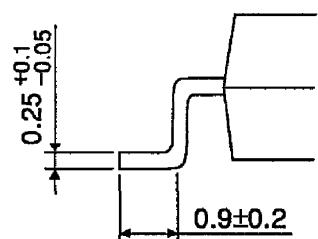
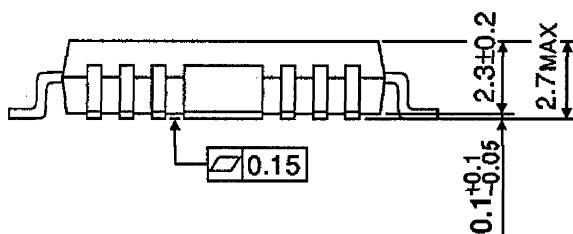
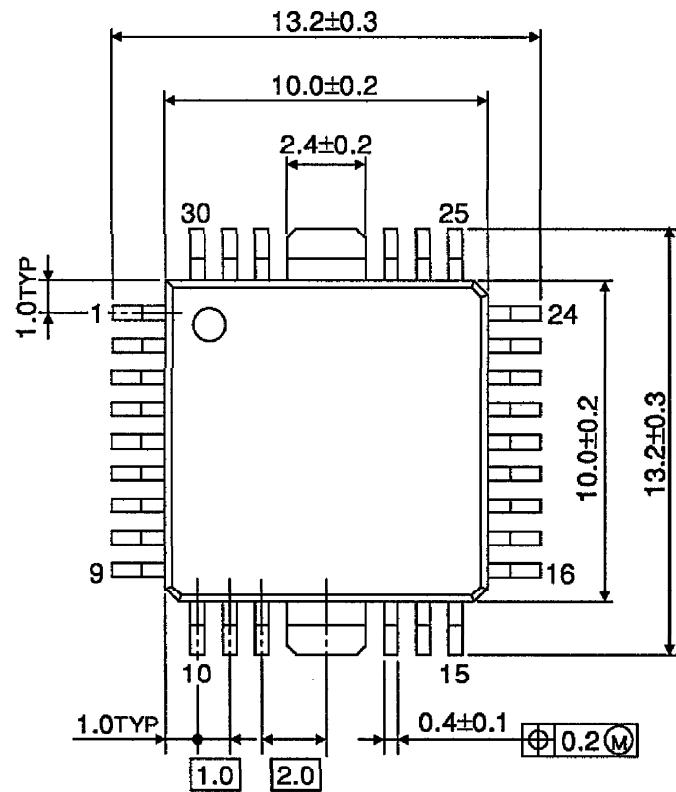


(Note) Utmost care is necessary in the design of the output line, V_{CC} and GND line since IC may be destroyed due to short-circuit between outputs, air contamination fault, or fault by improper grounding.

OUTLINE DRAWING

HQFP30-P-1010-1.00

Unit : mm



Weight : 0.61g (Typ.)